### **Solutions to Chapter 3 Problems**

### **S.3.1**

Initially the stress function,  $\phi$ , must be expressed in terms of Cartesian coordinates. Thus, from the equation of a circle of radius, *a*, and having the origin of its axes at its centre.

$$
\phi = k(x^2 + y^2 - a^2) \tag{i}
$$

From Eqs (3.4) and (3.11)

$$
\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = F = -2G \frac{d\theta}{dz}
$$
 (ii)

Differentiating Eq. (i) and substituting in Eq. (ii)

$$
4k = -2G\frac{\mathrm{d}\theta}{\mathrm{d}z}
$$

or

$$
k = -\frac{1}{2}G\frac{d\theta}{dz} \tag{iii}
$$

From Eq. (3.8)

$$
T = 2 \iint \phi \, dx \, dy
$$

i.e.

$$
T = -G\frac{d\theta}{dz} \left[ \iint_A x^2 dx dy + \iint_A y^2 dx dy - a^2 \iint_A dx dy \right]
$$
 (iv)

where  $\iint_{A} x^2 dx dy = I_y$ , the second moment of area of the cross-section about the *y* axis;  $\iint_A y^2 dx dy = I_x$ , the second moment of area of the cross-section about the *x* axis and  $\iint_A dx dy = A$ , the area of the cross-section. Thus, since  $I_y = \pi a^4/4$ ,  $I_x = \pi a^4/4$ and  $A = \pi a^2$  Eq. (iv) becomes

$$
T = G \frac{\mathrm{d}\theta}{\mathrm{d}z} \frac{\pi a^4}{2}
$$

or

$$
\frac{d\theta}{dz} = \frac{2T}{G\pi a^4} = \frac{T}{GI_p} \tag{v}
$$

From Eqs  $(3.2)$  and  $(v)$ 

$$
\tau_{zy} = -\frac{\partial \phi}{\partial x} = -2kx = G\frac{d\theta}{dz}x = \frac{Tx}{I_p}
$$
 (vi)

and

$$
\tau_{zx} = \frac{\partial \phi}{\partial y} = 2ky = -G \frac{d\theta}{dz} y = -\frac{Ty}{I_p}
$$
 (vii)

Substituting for  $\tau_{zy}$  and  $\tau_{zx}$  from Eqs (vi) and (vii) in the second of Eqs (3.15)

$$
\tau_{zs} = \frac{T}{I_p}(xl + ym) \tag{viii}
$$

in which, from Eqs (3.6)

$$
l = \frac{\mathrm{d}y}{\mathrm{d}s} \quad m = -\frac{\mathrm{d}x}{\mathrm{d}s}
$$

Suppose that the bar of Fig. 3.2 is circular in cross-section and that the radius makes an angle  $\alpha$  with the *x* axis. Then.

$$
m = \sin \alpha
$$
 and  $l = \cos \alpha$ 

Also, at any radius, *r*

$$
y = r \sin \alpha \quad x = r \cos \alpha
$$

Substituting for  $x$ ,  $l$ ,  $y$  and  $m$  in Eq. (viii) gives

$$
\tau_{zs}=\frac{Tr}{I_p} (=\tau)
$$

Now substituting for  $\tau_{zx}$ ,  $\tau_{zy}$  and  $d\theta/dz$  from Eqs (vii), (vi) and (v) in Eqs (3.10)

$$
\frac{\partial w}{\partial x} = -\frac{Ty}{GI_p} + \frac{Ty}{GI_p} = 0
$$
 (ix)

$$
\frac{\partial w}{\partial y} = \frac{T x}{G I_p} - \frac{T x}{G I_p} = 0
$$
 (x)

The possible solutions of Eqs (ix) and (x) are  $w = 0$  and  $w = constant$ . The latter solution implies a displacement of the whole bar along the  $z$  axis which, under the given loading, cannot occur. Therefore, the first solution applies, i.e. the warping is zero at all points in the cross-section.

The stress function,  $\phi$ , defined in Eq. (i) is constant at any radius, *r*, in the crosssection of the bar so that there are no shear stresses acting across such a boundary. Thus, the material contained within this boundary could be removed without affecting the stress distribution in the outer portion. Therefore, the stress function could be used for a hollow bar of circular cross-section.

## **S.3.2**

In S.3.1 it has been shown that the warping of the cross-section of the bar is everywhere zero. Then, from Eq. (3.17) and since  $d\theta/dz \neq 0$ 

$$
\psi(x, y) = 0 \tag{i}
$$

This warping function satisfies Eq. (3.20). Also Eq. (3.21) reduces to

$$
xm - yl = 0 \tag{ii}
$$

On the boundary of the bar  $x = al$ ,  $y = am$  so that Eq. (ii), i.e. Eq. (3.21), is satisfied. Since  $\psi = 0$ , Eq. (3.23) for the torsion constant reduces to

$$
J = \iint_A x^2 dx dy + \iint_A y^2 dx dy = I_p
$$

Therefore, from Eq. (3.12)

$$
T = G I_p \frac{\mathrm{d}\theta}{\mathrm{d}z}
$$

as in S.3.1. From Eqs (3.19)

$$
\tau_{zx} = G \frac{\mathrm{d}\theta}{\mathrm{d}z}(-y) = -\frac{Ty}{I_p}
$$

and

$$
\tau_{zy} = G \frac{\mathrm{d}\theta}{\mathrm{d}z}(x) = \frac{Tx}{I_p}
$$

which are identical to Eqs (vii) and (vi) in S.3.1. Hence

$$
\tau_{zs}=\tau=\frac{Tr}{I_p}
$$

as in S.3.1.

### **S.3.3**

Since  $\psi = kxy$ , Eq. (3.20) is satisfied. Substituting for  $\psi$  in Eq. (3.21)

$$
(kx + x)m + (ky - y)l = 0
$$

or, from Eqs (3.6)

$$
-x(k+1)\frac{\mathrm{d}x}{\mathrm{d}s} + y(k-1)\frac{\mathrm{d}y}{\mathrm{d}s} = 0
$$

or

$$
\frac{d}{ds} \left[ -\frac{x^2}{2}(k+1) + \frac{y^2}{2}(k-1) \right] = 0
$$

so that

$$
-\frac{x^2}{2}(k+1) + \frac{y^2}{2}(k-1) = \text{constant on the boundary of the bar}
$$

Rearranging

$$
x^{2} + \left(\frac{1-k}{1+k}\right)y^{2} = \text{constant}
$$
 (i)

Also, the equation of the elliptical boundary of the bar is

$$
\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1
$$

or

$$
x^{2} + \frac{a^{2}}{b^{2}}y^{2} = a^{2}
$$
 (ii)

Comparing Eqs (i) and (ii)

$$
\frac{a^2}{b^2} = \left(\frac{1-k}{1+k}\right)
$$

from which

$$
k = \frac{b^2 - a^2}{a^2 + b^2} \tag{iii}
$$

and

$$
\psi = \frac{b^2 - a^2}{a^2 + b^2} xy \tag{iv}
$$

Substituting for  $\psi$  in Eq. (3.23) gives the torsion constant, *J*, i.e.

$$
J = \iint_A \left[ \left( \frac{b^2 - a^2}{a^2 + b^2} + 1 \right) x^2 - \left( \frac{b^2 - a^2}{a^2 + b^2} - 1 \right) y^2 \right] dx dy
$$
 (v)

Now  $\iint_A x^2 dx dy = I_y = \pi a^3 b/4$  for an elliptical cross-section. Similarly  $\iint_A y^2 dx dy =$  $I_x = \pi ab^3/4$ . Equation (v) therefore simplifies to

$$
J = \frac{\pi a^3 b^3}{a^2 + b^2} \tag{vi}
$$

which are identical to Eq. (v) of Example 3.1.

From Eq. (3.22) the rate of twist is

$$
\frac{d\theta}{dz} = \frac{T(a^2 + b^2)}{G\pi a^3 b^3}
$$
 (vii)

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The shear stresses are obtained from Eqs (3.19), i.e.

$$
\tau_{zx} = \frac{GT(a^2 + b^2)}{G\pi a^3 b^3} \left[ \left( \frac{b^2 - a^2}{a^2 + b^2} \right) y - y \right]
$$

so that

$$
\tau_{zx} = -\frac{2Ty}{\pi ab^3}
$$

and

$$
\tau_{zy} = \frac{GT(a^2 + b^2)}{G\pi a^3 b^3} \left[ \left( \frac{b^2 - a^2}{a^2 + b^2} \right) x + x \right]
$$

i.e.

$$
\tau_{zy} = \frac{2Tx}{\pi a^3 b}
$$

which are identical to Eq. (vi) of Example 3.1.

From Eq. (3.17)

$$
w = \frac{T(a^2 + b^2)}{G\pi a^3 b^3} \left(\frac{b^2 - a^2}{a^2 + b^2}\right) xy
$$

i.e.

$$
w = \frac{T(b^2 - a^2)}{G\pi a^3 b^3} xy
$$
 (compare with Eq. (viii) of Example 3.1)

## **S.3.4**

The stress function is

$$
\phi = -G \frac{d\theta}{dz} \left[ \frac{1}{2} (x^2 + y^2) - \frac{1}{2a} (x^3 - 3xy^2) - \frac{2}{27} a^2 \right]
$$
 (i)

Differentiating Eq. (i) twice with respect to  $x$  and  $y$  in turn gives

$$
\frac{\partial^2 \phi}{\partial x^2} = -G \frac{d\theta}{dz} \left( 1 - \frac{3x}{a} \right)
$$

$$
\frac{\partial^2 \phi}{\partial y^2} = -G \frac{d\theta}{dz} \left( 1 + \frac{3x}{a} \right)
$$

Therefore

$$
\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = -2G \frac{d\theta}{dz} = \text{constant}
$$

and Eq. (3.4) is satisfied.

Further

on AB, 
$$
x = \frac{-a}{3}
$$
  $y = y$   
on BC,  $y = \frac{-x}{\sqrt{3}} + \frac{2a}{3\sqrt{3}}$   
on AC,  $y = \frac{x}{\sqrt{3}} - \frac{2a}{3\sqrt{3}}$ 

Substituting these expressions in turn in Eq. (i) gives

$$
\phi_{AB} = \phi_{BC} = \phi_{AC} = 0
$$

so that Eq. (i) satisfies the condition  $\phi = 0$  on the boundary of the triangle.

From Eqs (3.2) and (i)

$$
\tau_{zy} = -\frac{\partial \phi}{\partial x} = G \frac{d\theta}{dz} \left( x - \frac{3x^2}{2a} + \frac{3y^2}{2a} \right)
$$
 (ii)

and

$$
\tau_{zx} = \frac{\partial \phi}{\partial y} = -G \frac{d\theta}{dz} \left( y + \frac{3xy}{a} \right)
$$
 (iii)

At each corner of the triangular section  $\tau_{zv} = \tau_{zx} = 0$ . Also, from antisymmetry, the distribution of shear stress will be the same along each side. For AB, where  $x = -a/3$ and  $y = y$ , Eqs (ii) and (iii) become

$$
\tau_{zy} = G \frac{d\theta}{dz} \left( -\frac{a}{2} + \frac{3y^2}{2a} \right)
$$
 (iv)

and

$$
\tau_{zx} = 0 \tag{v}
$$

From Eq. (iv) the maximum value of  $\tau_{zy}$  occurs at  $y = 0$  and is

$$
\tau_{zy}(\text{max}) = -\frac{Ga}{2}\frac{d\theta}{dz} \tag{vi}
$$

The distribution of shear stress along the *x* axis is obtained from Eqs (ii) and (iii) in which  $x = x$ ,  $y = 0$ , i.e.

$$
\tau_{zy} = G \frac{d\theta}{dz} \left( x - \frac{3x^2}{2a} \right)
$$
 (vii)  

$$
\tau_{zx} = 0
$$

From Eq. (vii)  $\tau_{zy}$  has a mathematical maximum at  $x = +a/3$  which gives

$$
\tau_{zy} = \frac{Ga}{6} \frac{d\theta}{dz}
$$
 (viii)

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which is less than the value given by Eq. (vi). Thus the maximum value of shear stress in the section is (−*Ga/*2)d*θ/*d*z*.

The rate of twist may be found by substituting for  $\phi$  from Eq. (i) in (3.8). Thus

$$
T = -2G \frac{d\theta}{dz} \iint \left[ \frac{1}{2} (x^2 + y^2) - \frac{1}{2a} (x^3 - 3xy^2) - \frac{2}{27} a^2 \right] dx dy
$$
 (ix)

The equation of the side AC of the triangle is  $y = (x - 2a/3)/\sqrt{3}$  and that of BC, *y* = −(*x* − 2*a*/3)/ $\sqrt{3}$ . Equation (ix) then becomes

$$
T = -2G \frac{d\theta}{dz} \int_{-a/3}^{2a/3} \int_{(x-2a/3)/\sqrt{3}}^{-(x-2a/3)/\sqrt{3}} \left[ \frac{1}{2} (x^2 + y^2) - \frac{1}{2a} (x^3 - 3xy^2) - \frac{2}{27} a^2 \right] dx dy
$$

which gives

$$
T = \frac{Ga^4}{15\sqrt{3}}\frac{d\theta}{dz}
$$

so that

$$
\frac{d\theta}{dz} = \frac{15\sqrt{3}T}{Ga^4} \tag{x}
$$

From the first of Eqs (3.10)

$$
\frac{\partial w}{\partial x} = \frac{\tau_{zx}}{G} + \frac{d\theta}{dz}y
$$

Substituting for  $\tau_{zx}$  from Eq. (iii)

$$
\frac{\partial w}{\partial x} = -\frac{d\theta}{dz} \left( y + \frac{3xy}{a} - y \right)
$$

i.e.

$$
\frac{\partial w}{\partial x} = -\frac{3xy}{a} \frac{d\theta}{dz}
$$

whence

$$
w = -\frac{3x^2y}{2a} \frac{d\theta}{dz} + f(y)
$$
 (xi)

Similarly from the second of Eqs (3.10)

$$
w = -\frac{3x^2y}{2a}\frac{d\theta}{dz} + \frac{y^3}{2a}\frac{d\theta}{dz} + f(x)
$$
 (xii)

Comparing Eqs (xi) and (xii)

$$
f(x) = 0
$$
 and  $f(y) = \frac{y^3}{2a} \frac{d\theta}{dz}$ 

Hence

$$
w = \frac{1}{2a} \frac{d\theta}{dz} (y^3 - 3x^2 y).
$$

### **S.3.5**

The torsion constant, *J*, for the complete cross-section is found by summing the torsion constants of the narrow rectangular strips which form the section. Then, from Eq. (3.29)

$$
J = 2\frac{at^3}{3} + \frac{bt^3}{3} = \frac{(2a+b)t^3}{3}
$$

Therefore, from the general torsion equation (3.12)

$$
\frac{d\theta}{dz} = \frac{3T}{G(2a+b)t^3}
$$
 (i)

The maximum shear stress follows from Eqs (3.28) and (i), hence

$$
\tau_{\text{max}} = \pm G t \frac{\mathrm{d}\theta}{\mathrm{d}z} = \pm \frac{3T}{(2a+b)t^2}.
$$

# **Solutions to Chapter 4 Problems**

### **S.4.1**

Give the beam at D a virtual displacement  $\delta_D$  as shown in Fig. S.4.1. The virtual displacements of C and B are then, respectively,  $3\delta_{\rm D}/4$  and  $\delta_{\rm D}/2$ .



#### **Fig. S.4.1**

The equation of virtual work is then

$$
R_{\rm D}\delta_{\rm D} - \frac{2W\delta_{\rm D}}{2} - \frac{W3\delta_{\rm D}}{4} = 0
$$

from which

$$
R_{\rm D}=1.75W
$$

It follows that

$$
R_{\rm A}=1.25W.
$$