

Continuity equation Two-Dimensional streamline condition

Velocity potential

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{V}) = 0$$

$$v dx = u dy$$

Stream function

$$u = \frac{\partial \phi}{\partial x}, \quad v = \frac{\partial \phi}{\partial y}, \quad w = \frac{\partial \phi}{\partial z}$$

Vorticity

$$\xi = \nabla \times \mathbf{V}$$

Circulation

$$\Gamma = - \oint_C \mathbf{V} \cdot d\mathbf{s}$$

$$\rho u = \frac{\partial \bar{\psi}}{\partial y}, \quad \rho v = - \frac{\partial \bar{\psi}}{\partial x}$$

$$V_r = \frac{d\phi}{dr}, \quad V_\theta = \frac{1}{r} \frac{d\phi}{d\theta}$$

condition of irrotationality
for two-dimensional flow

$$\frac{\partial v}{\partial x} = \frac{\partial u}{\partial y}$$

$$V_r = \frac{1}{r} \frac{d\psi}{d\theta}, \quad V_\theta = - \frac{d\psi}{dr}$$

Continuity & Bernoulli

$$V_1 = \sqrt{\frac{2(p_1 - p_2)}{\rho \left(\frac{A_1}{A_2} - 1 \right)}}$$

Flow type	Velocity	Velocity potential	Stream function
Uniform flow in x -direction	$u = V_\infty$ $v = 0$	$\phi = V_\infty x$	$\psi = V_\infty y$
Source/Sink	$V_r = \frac{\Lambda}{2\pi r}$ $V_\theta = 0$	$\phi = \frac{\Lambda}{2\pi} \ln r$	$\psi = \frac{\Lambda}{2\pi} \theta$
Doublet	$V_r = -\frac{\kappa \cos \theta}{2\pi r^2}$ $V_\theta = -\frac{\kappa \sin \theta}{2\pi r^2}$	$\phi = \frac{\kappa}{2\pi} \frac{\cos \theta}{r}$	$\psi = -\frac{\kappa}{2\pi} \frac{\sin \theta}{r}$
Vortex	$V_r = 0$ $V_\theta = -\frac{\Gamma}{2\pi r}$	$-\frac{\Gamma}{2\pi} \theta$	$\psi = \frac{\Gamma}{2\pi} \ln r$

Kutta-Joukowski Theorem

$$L' = c_l q_\infty c = \frac{\Gamma}{RV_\infty} \frac{1}{2} \rho_\infty V_\infty^2 2R = \rho_\infty V_\infty \gamma \quad c_l = \frac{\Gamma}{RV_\infty}$$

$$C_p = 1 - \left(2 \sin \theta + \frac{\Gamma}{2\pi RV_\infty} \right)^2$$

$$\text{where } R = \frac{1}{2}c$$

$$\Gamma = \int_a^b \gamma ds$$

Pressure coefficient

$$C_p = \frac{p - p_\infty}{q_\infty} = 1 - \left(\frac{V}{V_\infty} \right)^2$$

Energy equation

$$\nabla \cdot \left(\rho \left(e + \frac{V^2}{2} \right) \mathbf{V} \right) = -\nabla \cdot (p\mathbf{V})$$

Substantial derivative

$$\frac{Dx}{Dt} = \frac{\partial x}{\partial t} + (\nabla \cdot \mathbf{V}) x$$

Divergence of velocity

$$\nabla \cdot \mathbf{V} = \frac{1}{\nu} \frac{D\nu}{Dt}$$

Cambered airfoils

$$\frac{dz}{dx} = \alpha - A_0 + \sum_{n=1}^{\infty} A_n \cos n\theta_0$$

$$\alpha_{opt} = \frac{1}{\pi} \int_0^\pi \frac{dz}{dx} \theta_0$$

$$(c_l)_{design} = \pi A_1 = 2 \int_0^\pi \frac{dz}{dx} \cos \theta_0 d\theta_0$$

$$c_l = \pi(2A_0 + A_1), \quad c_{m,c/4} = \frac{\pi}{4} (A_2 - A_1)$$

$$\text{Mach angle} \quad \sin \mu = \frac{at}{Vt} = \frac{a}{V} = \frac{1}{M}$$

wave angle $\beta > \mu$ Shock wave: pressure, density and temp. increase
Expansion wave: pressure, density and temp. decrease

Nozzle back pressure

- If $p_B > p_{e,6}$, overexpanded oblique shock waves
- If $p_B < p_{e,6}$, underexpanded expansion waves
- If $p_B = p_{e,6}$, without any waves

Prandtl-Glauert correction

$$C_p = \frac{C_{p,0}}{\sqrt{1 - M_\infty^2}}$$

Karman-Tsien

$$C_p = \frac{C_{p,0}}{\sqrt{1 - M_\infty^2} + \frac{M_\infty^2}{1 + \sqrt{1 - M_\infty^2}} \frac{C_{p,0}}{2}}$$

Biot-Savart

$$v = \frac{\Gamma}{4\pi r} [\cos A - \cos B]$$

Prandtl relation for normal shock wave

$$M_2^2 = \frac{2 + (\gamma - 1) M_1^2}{2\gamma M_1^2 - (\gamma - 1)}$$

If $M_1 > 1$ we have $M_2 < 1$

If $M_1 = 1$, then also $M_2 = 1$

$$c_{m,le} = -\frac{1}{4} c_l$$

Three-Dimensional Wings

Angles of attack

$$\alpha = \alpha_{eff} + \alpha_i$$

$$\alpha_i(y_0) = \frac{1}{4\pi V_\infty} \int_{-\frac{b}{2}}^{\frac{b}{2}} \frac{\left(\frac{d\Gamma}{dy} \right) dy}{(y_0 - y)}$$

$$\alpha_{eff}(y_0) = \frac{\Gamma(y_0)}{\pi V_\infty c(y_0)} + \alpha_{L=0}$$

$$\text{Aspect ratio} \quad A = \frac{b^2}{S}$$

$$\text{Lift coefficient} \quad C_L = A_1 \pi A$$

$$\text{Induced drag} \quad D'_i(y) = L' \alpha_i = \rho_\infty V_\infty \Gamma \alpha_i$$

$$C_{D,i} = \frac{C_L^2}{\pi Ae}$$

$$e = A_1^2 \left(\sum_1^N n A_n^2 \right)^{-1}$$

Lift and Drag Coefficients of a Flat Plate

$$C_{p,l} = \frac{2\alpha}{\sqrt{M_\infty^2 - 1}} \quad \text{and} \quad C_{p,u} = -\frac{2\alpha}{\sqrt{M_\infty^2 - 1}}$$

$$c_n = \frac{1}{c} \int_0^c (C_{p,l} - C_{p,u}) dx = \frac{4\alpha}{\sqrt{M_\infty^2 - 1}}$$

$$c_l = c_n \cos \alpha \quad \text{and} \quad c_d = c_n \sin \alpha$$

$$c_l = \frac{4\alpha}{\sqrt{M_\infty^2 - 1}} \quad \text{and} \quad c_n = \frac{4\alpha^2}{\sqrt{M_\infty^2 - 1}}$$