$$\frac{5/1}{\alpha} = \frac{\omega_2 - \omega_1}{t} = \frac{900 - 300}{6/60} = 6000 \text{ rev/min}^2$$

$$\omega_2^2 = \omega_1^2 + 2\alpha\theta, \quad \theta = N = \frac{\omega_2^2 - \omega_1^2}{2\alpha}$$

$$= \frac{(900)^2 - (300)^2}{2(6000)} = \frac{60 \text{ rev}}{2}$$

5/2 (a)
$$v_{A} = \omega \times r_{A/o} = -6k \times 45i$$

$$= \frac{270i \text{ mm/s}}{270i \text{ mm/s}}$$

$$q_{A} = \propto \times r_{A/o} - \omega^{2} r_{A/o} = 4k \times 45i - 6^{2} (45i)$$

$$= -180i - 1620i \text{ mm/s}^{2}$$
(b) $v_{B} = \omega \times r_{B/o} = -6k \times (-30i + 45i)$

$$= \frac{270i + 180i \text{ mm/s}}{270i + 45i}$$

$$q_{B} = \propto \times r_{B/o} - \omega^{2} r_{B/o}$$

$$= 4k \times (-30i + 45i) - 6^{2} (-30i + 45i)$$

$$= 900i - 1740i \text{ mm/s}^{2}$$

5/3
$$w = 12 - 3t^2$$
; when $w = 0$, $t^2 = 4$, $t = 2s$

$$\int_{0}^{4\theta} \int_{0}^{t} w dt$$
; $\Delta\theta = \int_{0}^{3} (12 - 3t^2) dt = [12t - t^3]_{0}^{3}$

$$= \frac{9 \text{ rad}}{2}$$

$$\theta_{1} = \int_{0}^{3} (12 - 3t^2) dt = [12t - t^3]_{0}^{2} = 16 \text{ rad (cw)}$$

$$\theta_{2} = \int_{0}^{3} (12 - 3t^2) dt = [12t - t^3]_{2}^{3} = -7 \text{ rad (ccw)}$$
The total number of turns is
$$N = (16 + 7) / 2\pi = 3.66 \text{ rev}$$

5/4 Let k be a unit vector out of paper.

(a) $v_A = \omega \times r_{A/0} = 3k \times (-0.4e_n) = 1.2e_t m/s$ $a_A = \alpha \times r_{A/0} - \omega^2 r_{A/0} = -14k \times (-0.4e_n) -3^2 (-0.4e_n)$ $= -5.6e_t + 3.6e_n m/s^2$

(b)
$$v_B = \omega \times r_{B/o} = 3k \times (-0.4e_n + 0.1e_t)$$

= 1.2e_t + 0.3e_n m/s

$$a_{B} = \alpha \times \frac{r_{B/o}}{-\omega^{2} r_{B/o}}$$

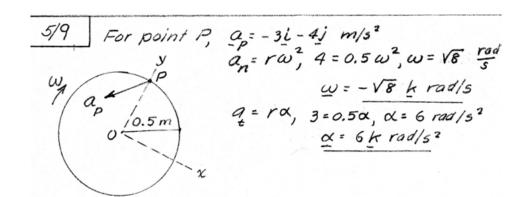
$$= -14 k \times (-0.4 e_{n} + 0.1 e_{t}) - 3^{2} (-0.4 e_{n} + 0.1 e_{t})$$

$$= -6.5 e_{t} + 2.2 e_{n} \text{ m/s}^{2}$$

5/5 For v constant $a_{\pm} = 0 \ d = a_n = \frac{v^2}{r}$ $\left(\frac{v^2}{r}\right)_A = \frac{2}{3} \left(\frac{v^2}{3}\right)_B , \frac{r}{2} = \frac{4.5 \text{ in.}}{2}$

5/6 For $\theta = 90^{\circ}$, $a = -a_{t}i - a_{n}j$ so $a_{t} = r\alpha = 1.8 \text{ m/s}^{2}$, $\alpha = \frac{1.8}{0.3} = \frac{6 \text{ rad/s}^{2}}{0.3}$ $4a_{n} = r\omega^{2} = 4.8 \text{ m/s}^{2}, \ \omega = \sqrt{4.8/0.3} = \frac{4 \text{ rad/s}}{0.3}$

 $a_t = r\alpha$: $\alpha = 1.803/0.3 = 6.01 \text{ rad/s}^2$ $a_n = r\omega^2$: $\omega^2 = 2.92/0.3 = 9.72 (rad/s)^2$, $\omega = 3.12 \text{ rad/s}$



5/10 All lines including OC have the same $a_{1} = \frac{2}{3}(0.150)\frac{\sqrt{3}}{2} = 0.0866 \text{ m}$ $a_{2} = \frac{1}{3} = \frac{2}{3}(0.150)\frac{\sqrt{3}}{2} = 0.0866 \text{ m}$ $a_{3} = \frac{1}{3} = \frac{2}{3}(0.150)\frac{\sqrt{3}}{2} = 0.0866 \text{ m}$ $a_{4} = \frac{1}{3} = \frac{1}{3}(0.0866)$ $a_{5} = \frac{1}{3} = \frac{1}{3}(0.0866)$ $a_{7} = \frac{1}{3} = \frac{1}{3}$

5/11
$$\omega_{av} = \frac{\Delta\theta}{\Delta t} \quad \text{where} \quad \Delta\theta = \frac{\pi}{2} \quad \text{rad}$$

$$\Delta t = \frac{\Delta s}{v} = \frac{40}{10} = 4 \text{ sec}$$

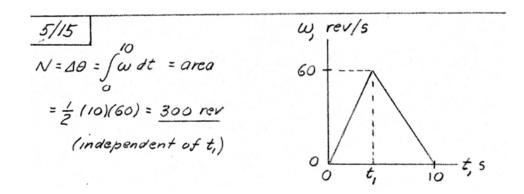
$$So \quad \omega_{av} = \frac{\pi/2}{4} = 0.393 \quad \text{rad/sec}$$

Note that \underline{r} could have been taken as $0.5\underline{i} + 0.2\underline{j}$ m. The magnitudes of the above results are $v_p = 1.077$ m/s and $v_p = 2.69$ m/s².

These majnitudes check with
$$v_p = r_{xy} \omega = \sqrt{0.5^2 + 0.2^2} (2) = 1.077 \text{ m/s}^2$$
and $a_p = \sqrt{a_t^2 + a_n^2} = \sqrt{(r_{xy} \alpha)^2 + (r_{xy} \omega^2)^2}$

$$= \sqrt{0.5^2 + 0.2^2} \sqrt{3^2 + 2^4} = 2.69 \text{ m/s}^2$$

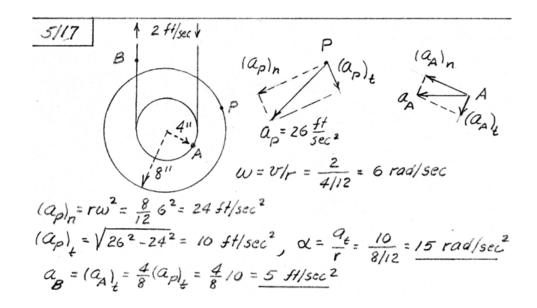
5/14 $\omega_{0A} = \omega_{Bc} = -6k \text{ rad/s}$ $\Gamma_A = 0.3 i + 0.28 j \text{ m}$ $U_A = \omega \times \Gamma_A = -6k \times (0.3 i + 0.28 j) = -1.8 j + 1.68 i \text{ m/s}$ $U_A = i \times I_A = -6k \times (0.3 i + 0.28 j) = -1.8 j + 1.68 i \text{ m/s}$ $U_A = i \times I_A + \omega \times V_A = 0 + (-6k) \times (1.68 i - 1.8 j)$ $U_A = i \times I_A + \omega \times V_A = 0 + (-6k) \times (1.68 i - 1.8 j)$ $U_A = -10.8 i - 10.08 j \text{ m/s}^2$



$$5/16$$
 At B, $\sigma = \frac{50}{30}44 = 73.3 \text{ ft/sec}, r = 180 - \frac{18}{12} = 178.5 \text{ ft}$

$$\omega = \sigma/r = 73.3/178.5 = 0.411 \ rad/sec$$

Between A & B
$$\omega_{av} = \frac{\Delta\theta}{\Delta t} = \frac{30}{180} \pi / 1.52 = 0.344 \text{ rad/sec}$$



 $5/19 \quad \Delta\theta = (30-0)2\pi = 60\pi \text{ rad}$ $\alpha = 10 + k\theta, \quad 20 = 10 + 60\pi k, \quad k = \frac{1}{6\pi}$ $50 \quad \alpha = 10 + \frac{\theta}{6\pi}$ $\int_{\omega}^{90} d\omega = \int_{0}^{60\pi} (10 + \frac{\theta}{6\pi}) d\theta, \quad (90)^{2} - \omega_{0}^{2} = 2 \left[10\theta + \frac{\theta^{2}}{12\pi}\right]_{0}^{60\pi}$ $\omega_{0}^{2} = 8100 - 2 \left[600\pi + 300\pi\right] = 2445, \quad \omega_{0} = 49.4 \text{ rad/s}$

$$5/20 \quad (\alpha) \qquad \alpha = -0.05\omega = \frac{d\omega}{dt}$$

$$-0.05 \int_{0}^{\infty} dt = \int_{0}^{\omega} \frac{d\omega}{\omega}$$

$$-0.05 \int_{0}^{\infty} dt = \int_{0}^{\omega} \frac{d\omega}{\omega}$$

$$-0.05t = \ln \left(\frac{\omega}{\omega_{0}}\right)$$

$$-0.05t = \ln \left(\frac{\omega}{\omega_{0}}\right)$$

$$\omega = 100e^{-0.05(10)} = 60.7 \frac{rod}{s}$$

$$(b) \quad \alpha = -0.05\omega = \omega \frac{d\omega}{d\theta}$$

$$-0.05d\theta = d\omega$$

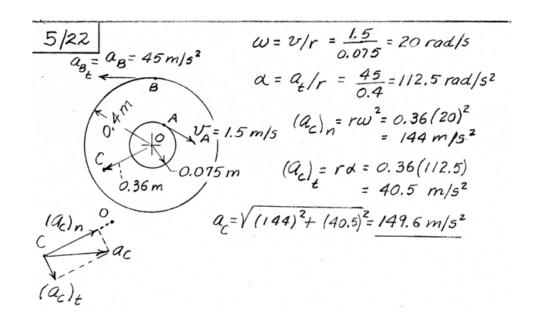
$$-0.05d\theta = d\omega$$

$$-0.05\theta = \omega - \omega_{0}$$

$$\omega = \omega_{0} - 0.05\theta, \quad \omega = 100 - 0.05 \left(10 \cdot 2\pi\right)$$

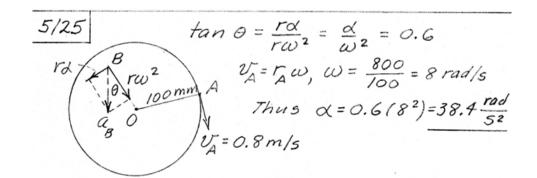
$$= \frac{96.9 \quad rod \mid s}{}$$

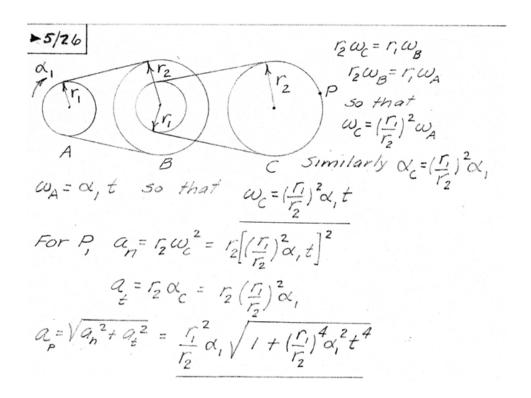
5/21
$$\omega d\omega = \alpha d\theta$$
 $\frac{d\omega}{d\theta} = k$, so $\frac{\alpha}{\omega} = k$, $\frac{d\omega}{dt} = k$, \frac



 $5/23 \quad \omega = \frac{V_A/\Gamma_A}{8/12} = \frac{10}{8/12} = 15 \text{ rad/sec}, \quad \omega = 15 \text{ trad/sec}$ $\alpha = \frac{(\alpha_A)_t}{\Gamma_A} = \frac{24}{8/12} = 36 \text{ rad/sec}^2, \quad \alpha = -36 \text{ trad/sec}^2$ $\alpha_B = \alpha \times \Gamma_B + \omega \times (\omega \times \Gamma_B)$ $= -36 \text{ trad/sec}^2$ $= -36 \text{ trad/sec}^2$ $= -36 \text{ trad/sec}^2$

5/24 For gear A, $\Delta \omega = \int_{2}^{6} \alpha_{A} dt$, $N_{A} = 2N_{B}$ $(N_{A} - 600) \frac{2\pi}{60} = \frac{4+8}{2} (6-2), N_{A} = 600 + 229 = 829 \text{ rev/min}$ so at t = 6s, $N_{B} = \frac{829}{2} = 415 \text{ rev/min}$





$$\frac{5/27}{y_{B}} \frac{\chi_{A}}{\sin \theta} = \frac{L}{\sin 60^{\circ}}$$

$$\frac{\chi_{A}}{\sin \theta} = \frac{L}{\sin 60^{\circ}}$$

$$\chi_{A} = \frac{2}{\sqrt{3}} L \sin \theta$$

$$\chi_{A} = 0 = \frac{2}{\sqrt{3}} L \cos \theta \dot{\theta}$$

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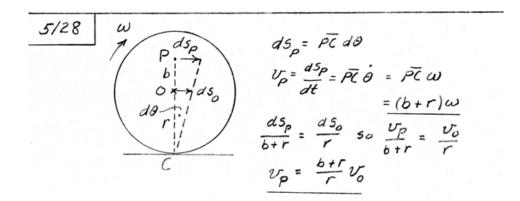
$$\chi_{A} = 0 = \frac{2}{\sqrt{3}} L \cos \theta \dot{\theta}$$

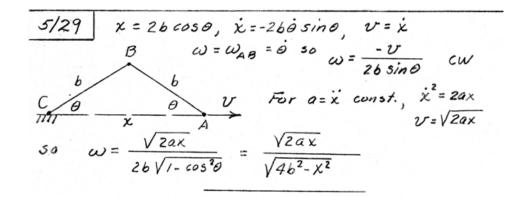
$$\chi_{A} = 0 = \frac{2}{\sqrt{3}} L \cos \theta \dot{\theta}$$

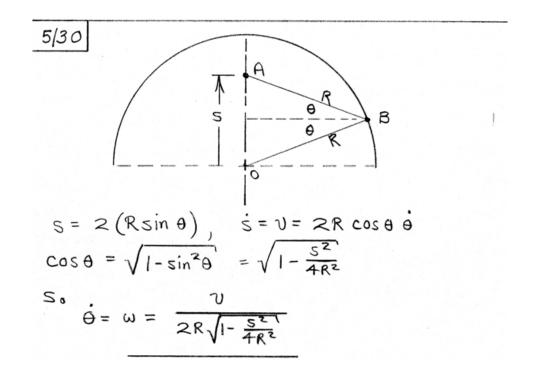
$$\chi_{A} = 0 = \frac{2}{\sqrt{3}} L \cos \theta \dot{\theta}$$

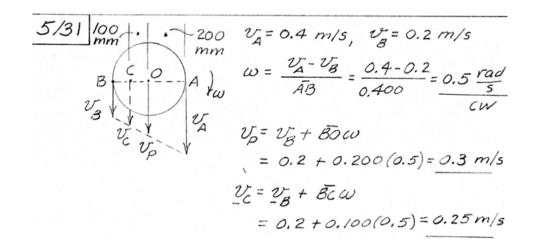
$$\chi_{A} = 0 = \frac{2}{\sqrt{3}} L \cos \theta \dot{\theta}$$

$$\chi_{A} = 0$$

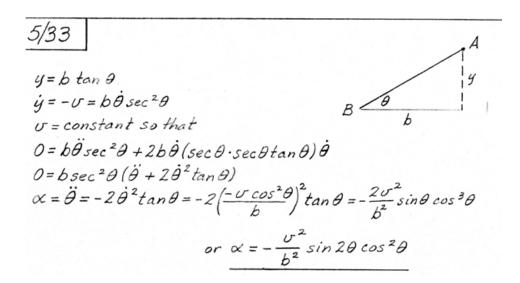


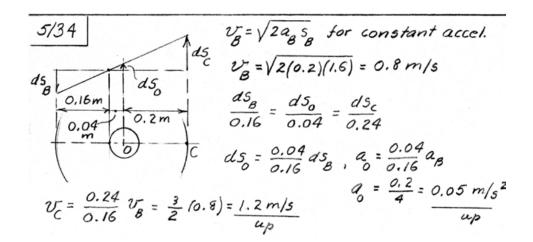


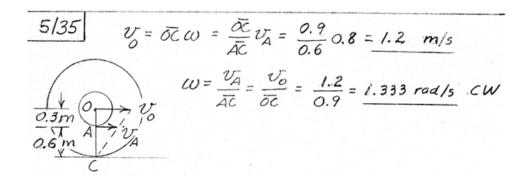


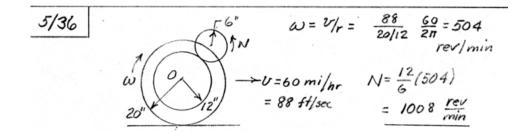


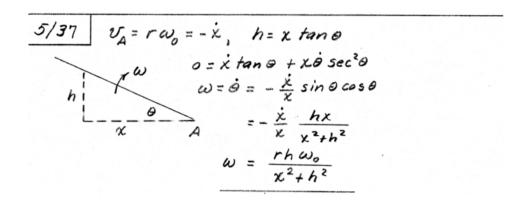
 $5/32 \quad Coordinates of A are$ $x = x_0 - r\cos\theta$ $y = r + r\sin\theta$ $\dot{x} = \dot{x}_0 + r\dot{\theta}\sin\theta = v_0(1 + \sin\theta)$ $\dot{y} = r\dot{\theta}\cos\theta = v_0\cos\theta$ $v = \sqrt{\dot{x}^2 + \dot{y}^2} = v_0\sqrt{(1 + \sin\theta)^2 + \cos^2\theta} = v_0\sqrt{2(1 + \sin\theta)} \quad v_0$ $\dot{x} = v_0\dot{\theta}\cos\theta = v_0\left(\frac{v_0}{r}\right)\cos\theta = \frac{v_0^2}{r}\cos\theta$ $\ddot{y} = -v_0\dot{\theta}\sin\theta = -v_0\left(\frac{v_0}{r}\right)\sin\theta = -\frac{v_0^2}{r}\sin\theta$ $a = \sqrt{\dot{x}^2 + \dot{y}^2} = \frac{v_0^2}{r}\sqrt{\cos^2\theta + \sin^2\theta} = \frac{v_0^2}{r} + toward 0$ $\ddot{y} = v_0\dot{y} = v_0\dot{y} + toward 0$ $\ddot{y} = v_0\dot{y} = v_0\dot{y} + toward 0$

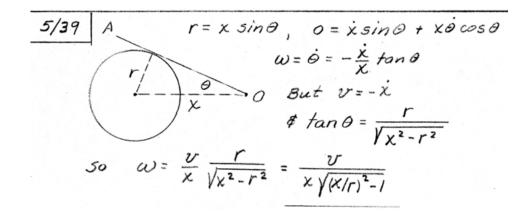


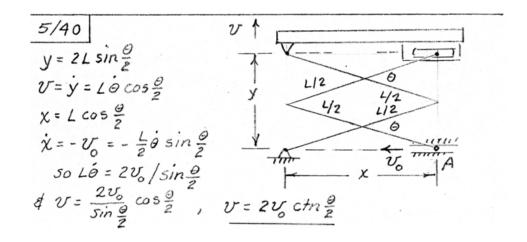












5/42 $y = 0.5 \text{ tan } \theta$ $\dot{y} = 0.5 \text{ sec}^2 \theta \dot{\theta}$ $\dot{y} = 0 = \text{Sec } \theta (\text{tan } \theta \text{ sec } \theta) \dot{\theta}^2$ $+ 0.5 \text{ sec}^2 \theta \dot{\theta}$ $\dot{\theta} = -2 \text{ tan } \theta \dot{\theta}^2$ For y = 0.6 m, $\text{tan } \theta = \frac{0.6}{0.5} = 1.2$, $\theta = 50.2^\circ$ $\text{Sec } \theta = 1.562$ So for $\dot{y} = 0.2 \text{ m/s}$, $\dot{\theta} = \frac{2(0.2)}{(1.562)^2} = 0.1639 \text{ rad/s}$ $\ddot{\theta} = -2(1.2)(0.1639)^2 = -0.0645 \text{ rad/s}^2$

$$\frac{5/43}{Also} \quad v_{B} = \frac{30(4) = 120 \text{ mm/s}}{dt} = \frac{40 d\theta}{dt} = \frac{40 \omega}{dt}, \quad w = \frac{120}{40} = 3 \text{ rad/s} \text{ CW}$$

$$v_{A} = \frac{ds_{A}}{dt} = 160 \frac{d\theta}{dt} = 160 \omega = 160(3) = \frac{480 \text{ mm/s}}{40 \text{ mm/s}} = \frac{40 \text{ mm/s}}{40 \text{ mm/s}}$$

$$v_{O} = \frac{ds_{O}}{dt} = 60 \frac{d\theta}{dt} = 60 \omega = 60(3) = \frac{180 \text{ mm/s}}{40 \text{ mm/s}} = \frac{40 \text{ mm/s}}{40 \text{ mm/s}}$$
From Sample Problem $5/4$ $a_{C} = r\omega^{2} = 60(3^{2}) = \frac{540 \text{ mm/s}^{2}}{40 \text{ mm/s}}$

 $y = 2b \sin \theta$ $V = \dot{y} = 2b \theta \cos \theta$ $\int_{\theta}^{2} \int_{\theta}^{2} \int_{\theta}^{2}$

5/45 Low of sines
$$\frac{8}{\sin\beta} = \frac{16}{\sin(\theta - \beta)}$$

$$A = \frac{(\theta - \beta)\cos(\theta - \beta)}{2\cos\beta} = 2\beta\cos\beta$$

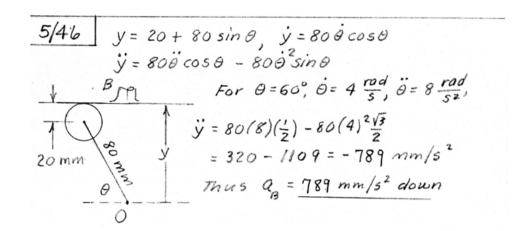
$$B = \frac{\cos(\theta - \beta)}{2\cos\beta} + \cos(\theta - \beta)$$

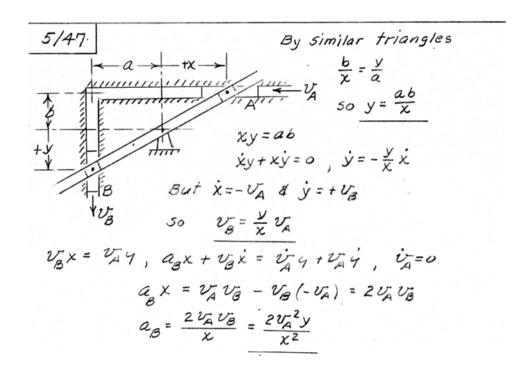
$$A = \frac{8\sin\theta}{16+8\cos\theta}, For \theta = 60^{\circ}, tan \beta = \frac{8\sin60^{\circ}}{16+8\cos60^{\circ}}$$

$$\theta - \beta = 60 - 19.11 = 40.9^{\circ} = 0.346, \beta = 19.11^{\circ}$$

$$\cos(\theta - \beta) = 0.756, \cos\beta = 0.945$$

$$\omega = \beta = \frac{0.756}{2(0.945) + 0.756} = \frac{600(2\pi)}{60} = \frac{17.95 \text{ rad/sec. CW}}{60}$$





$$\begin{array}{c|c}
\hline
5/48 & \chi = L\cos\theta \\
\hline
\dot{x} = -U = -L\dot{\theta}\sin\theta \\
\dot{\omega} = \dot{\theta} = \frac{U_0}{L\sin\theta} \\
\text{where } L\sin\theta = y = \sqrt{L^2 - \chi^2} \\
\hline
x = \dot{\theta} = \frac{U_0}{\sqrt{L^2 - \chi^2}} \\
\dot{\alpha} = \dot{\theta} = \frac{U_0}{L} \frac{d}{dt} \csc\theta = \frac{U_0}{L} \left(-\cot\theta \csc\theta\right)\dot{\theta} \\
&= -\frac{U_0}{L} \frac{\chi}{y} \frac{L}{y} \dot{\theta} = \frac{-\chi U_0^2}{y^2 \sqrt{L^2 \chi^2}} \\
&= \frac{-\chi U_0^2}{(L^2 - \chi^2)^{3/2}}
\end{array}$$

For vertical motion only

of B, its horizontal coordinate remains constant so $\frac{d}{dt} \left\{ (L+x)\cos\theta \right\} = 0$ $cor - (L-x)\dot{\theta}\sin\theta + \dot{x}\cos\theta = 0,$ $\dot{x} = (L+x)\dot{\theta}\tan\theta$ $cor = 2b^2\dot{\theta}\sin(\theta+\delta), \ \dot{\theta} = \frac{c\dot{c}}{b^2\sin(\theta+\delta)} = \frac{\sqrt{2}\sqrt{1-\cos(\theta+\delta)}}{b\sin(\theta+\delta)} \dot{c}$ Thus $\dot{x} = (L+x)\tan\theta \frac{\sqrt{2}\sqrt{1-\cos(\theta+\delta)}}{b\sqrt{1-\cos^2(\theta+\delta)}} \dot{c}$ $= \frac{L+x}{b}\tan\theta \frac{\sqrt{2}}{\sqrt{1+\cos(\theta+\delta)}} \dot{c} = \frac{L+x}{b}\frac{\tan\theta}{\cos\frac{1}{2}(\theta+\delta)} \dot{c}$ where $\delta = \sin^{-1}\frac{h}{b}$

5/50 Belt velocity is the same for both pulleys

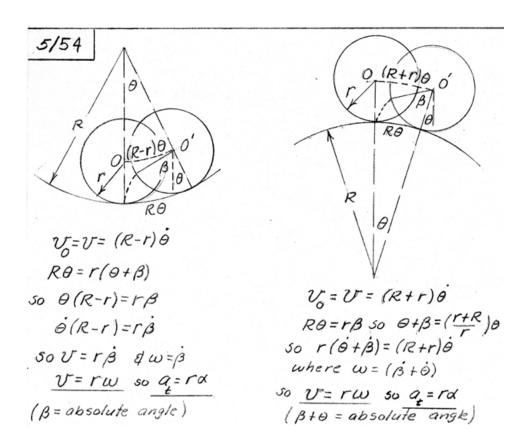
so $r_i \omega_i = r_2 \omega_2$ Thus $r_i \omega_i + r_i \dot{\omega}_i = r_2 \omega_2 + r_2 \dot{\omega}_2$ For $\dot{\omega}_i = 0$ # $\alpha_2 = \dot{\omega}_2$, we have $\alpha_2 = \dot{\alpha}_2 = \frac{r_i \omega_i - r_2 \omega_2}{r_2} = \frac{r_i r_2 - r_i r_2}{r_2^2} \omega_i$

5/52 Let ds = differential movement $\frac{ds_o}{60} = \frac{ds_A}{90}$ So $\frac{V_o}{60} = \frac{V_A}{90}$, $V_o = \frac{2}{3} V_A$ Pitch (distance between teeth) of A

large gear is $M = \frac{300}{48} = 19.63 \text{ mm}$ 19.63 mm is the advancement per revolution of worm.

Thus $V_A = \frac{19.63}{3} \left(\frac{120}{60} \right) = 39.3 \text{ mm/s}$ So $V_o = \frac{2}{3} (39.3) = \frac{26.2 \text{ mm/s}}{3}$

5/53 Given 5 = 0.260 m/s $5 = 2(0.2) \sin \frac{\theta}{2}$ $5 = 0.20 \cos \frac{\theta}{2}$ For $\theta = 60^{\circ}$ $5 = 0.260 = 0.20 \cos \frac{60^{\circ}}{2}$ $\theta = \omega_{AC} = \frac{0.260}{0.2 \cos 30^{\circ}} = 1.501 \text{ rad/s}$ $AC = \sqrt{0.3^2 + 0.15^2} = 0.335 \text{ m}$ $AC = \sqrt{0.3^2 + 0.15^2} = 0.335 \text{ m}$ $AC = 0.335 (1.501)^2 = 0.756 \text{ m/s}^2$



$$\frac{5/55}{\tan \beta} = \frac{2.5 \sin \theta}{9 - 2.5 \cos \theta}$$

$$\theta = \frac{2\pi N}{60} = \frac{120}{30} \pi = 12.57 \text{ rad/s}$$

$$\frac{(9 - 2.5 \cos \theta)}{2.5 \cos \theta} = 2.5 \sin \theta (2.5 \theta \sin \theta)$$

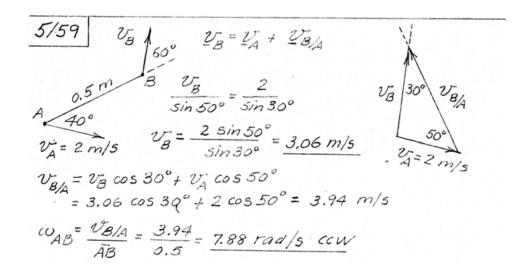
$$Sec^{2}\beta \dot{\beta} = \frac{(9-2.5\cos\theta)2.5\dot{\theta}\cos\theta - 2.5\sin\theta(2.5\dot{\theta}\sin\theta)}{(9-2.5\cos\theta)^{2}}$$
$$= \frac{22.5\cos\theta - 6.25}{(9-2.5\cos\theta)^{2}}\dot{\theta}$$

$$\dot{\beta} = \frac{22.5 \cos \theta - 6.25}{(9 - 2.5 \cos \theta)^2} \dot{\theta} \cos^2 \beta$$

But
$$\cos^2\beta = \frac{(9-2.5\cos\theta)^2}{9^2+2.5^2-2(9)(2.5)\cos\theta}$$

so
$$\hat{\beta} = \frac{22.5\cos\theta - 6.25}{87.2 - 45\cos\theta} / 2.57 \text{ or } \hat{\beta} = \frac{12.57\cos\theta - 0.278}{2} \frac{\text{rad}}{1.939 - \cos\theta} \frac{12.57\cos\theta - 0.278}{\text{sec}}$$

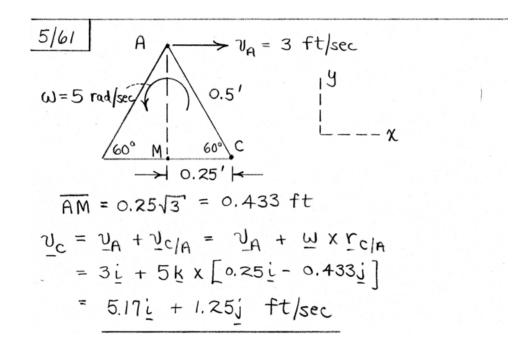
 $\begin{array}{lll}
\bullet 5/58 & l \sin \beta = r \sin \theta, \ l \beta \cos \beta = r \theta \cos \theta \\
\omega_{AB} & l & so \\
A & \omega_{AB} & \beta = \frac{r}{l} \theta \frac{\cos \theta}{\cos \beta} = \frac{r}{l} \omega_{0} \frac{\cos \theta}{\sqrt{1 - (\frac{r}{l} \sin \theta)^{2}}} \\
l \beta \cos \beta - l \beta^{2} \sin \beta = -r \theta^{2} \sin \theta, \quad \theta = \omega_{0} = 0 \\
\omega_{AB} & \beta = \frac{l \beta^{2} \sin \beta - r \theta^{2} \sin \theta}{l \cos \beta} = \frac{r \omega_{0}^{2}}{l} \sin \theta \frac{\frac{r^{2}}{l^{2}} - l}{(1 - \frac{r^{2}}{l^{2}} \sin^{2} \theta)^{3/2}}
\end{array}$

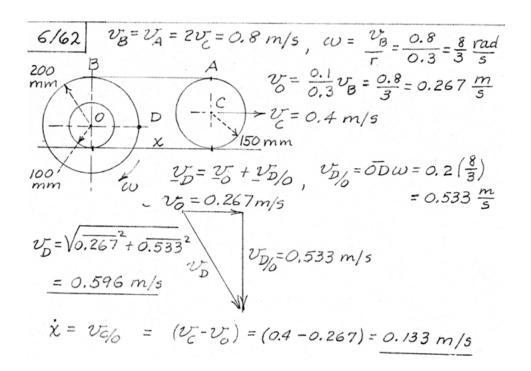


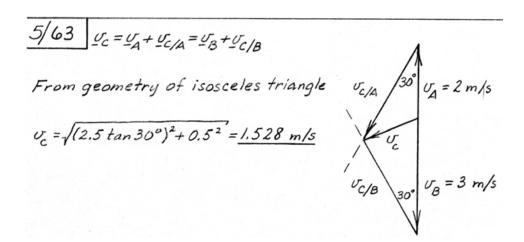
5/60
$$V_A = V_O + V_{A/O}$$
 where $V_{A/O} = \overline{AO} \omega = \frac{10}{12} \omega \frac{ft}{sec}$
(a) $V_A = 4 V_O = 4$ $U_O = 4 \frac{8}{10/12} = 9.6 \frac{rad}{sec}$, $N = 9.6 \frac{60}{2\pi} = 91.7 \frac{rev}{min}$ CCW

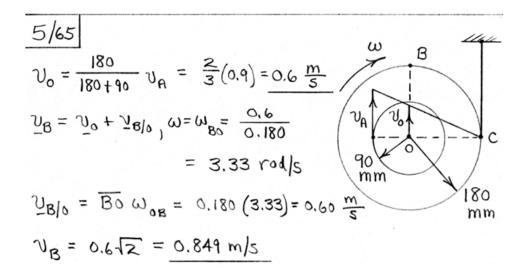
(b)
$$\frac{V_0=4}{M_0=4}$$
 $V=0$, $\omega=\frac{4}{10/12}=4.8\frac{rad}{sec}$, $N=45.8\frac{rev}{min}$ CCW

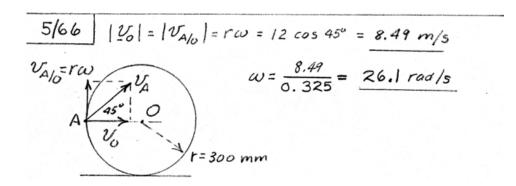
(c)
$$\frac{U_0=4}{V_A=8 \text{ ft/sec}} = \frac{4}{10/12} = 4.8 \frac{rod}{sec}$$
, $N=45.8 \frac{rev}{min} \text{ cw}$

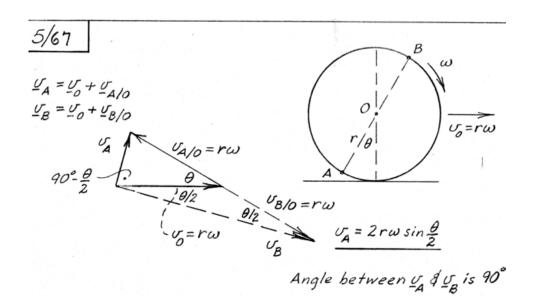


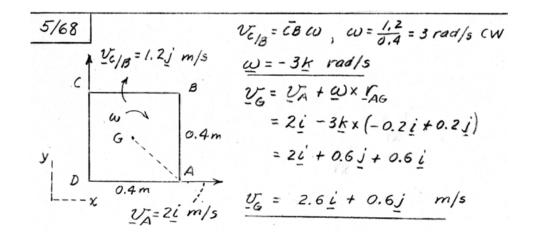


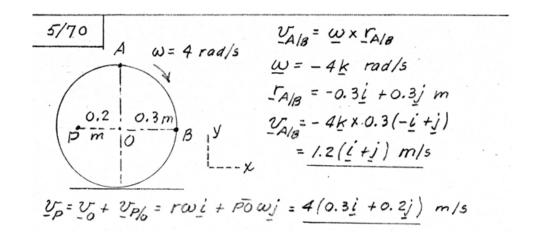


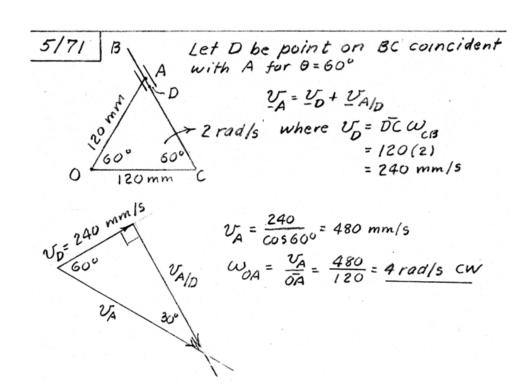


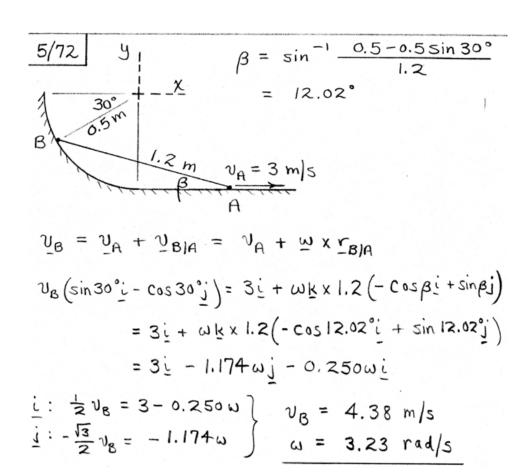


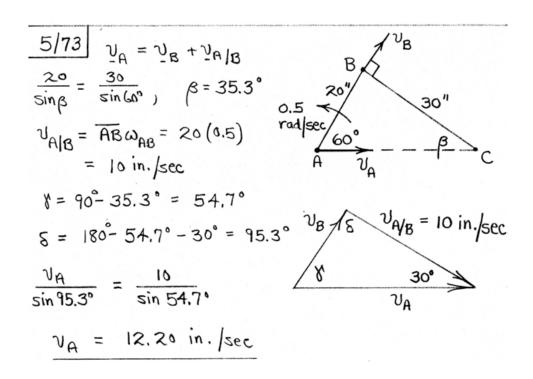


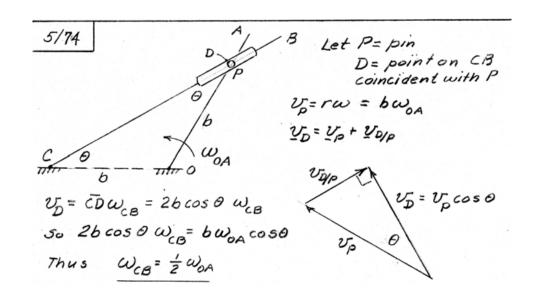


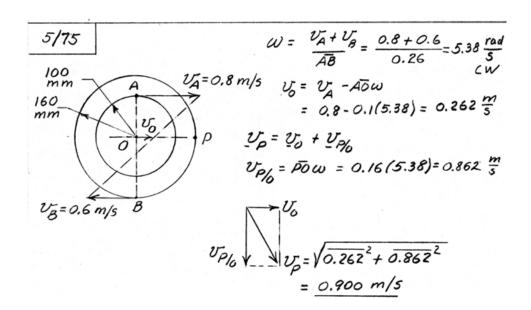


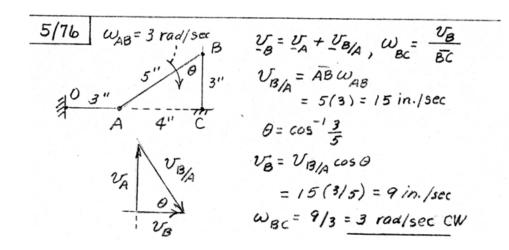






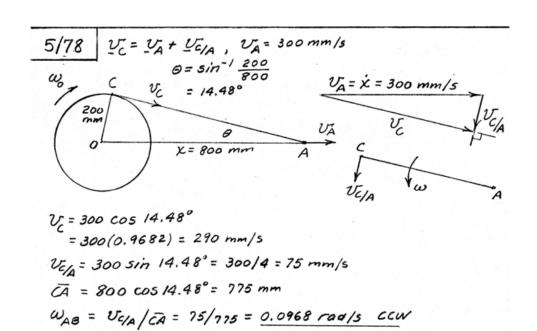






5/77 Let D be point on BC coincident with A

6 rad/sec $V_D = V_A + V_{D/A}$, $V_A = r \cdot \omega = 4(6)$ = 24 in./sec $V_{D/A}$ $V_A = 24 \frac{\text{in.}}{\text{sec}}$ $V_D = 30 + \beta$ $= 43.19^\circ$ $V_D = V_A \cos \gamma = 24 \cos 43.19^\circ = 17.50 \text{ in./sec}$ $V_{CB} = \sqrt{\frac{17.50}{8.77}} = \frac{2.00 \text{ rad/sec}}{2.00 \text{ rad/sec}}$ Coincident with A $V_D = V_A \cos \phi = 4(6)$ $V_D = V_D \cos \phi = 4(6)$ $V_D = 24 \sin \phi = 4(6)$ $V_D = 30 + \beta = 43.19^\circ =$

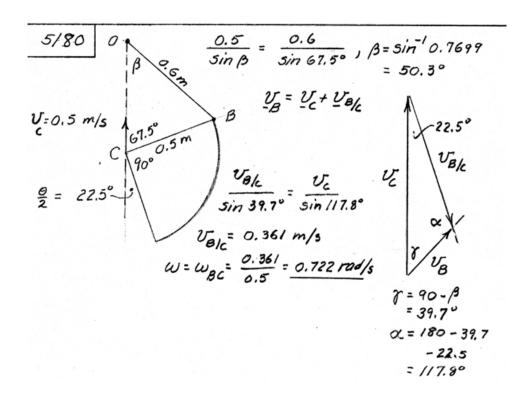


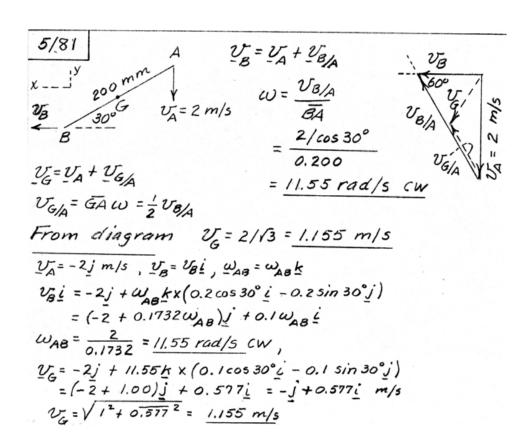
Wo = Vc/co = 290/200 = 1.452 rad/s CW

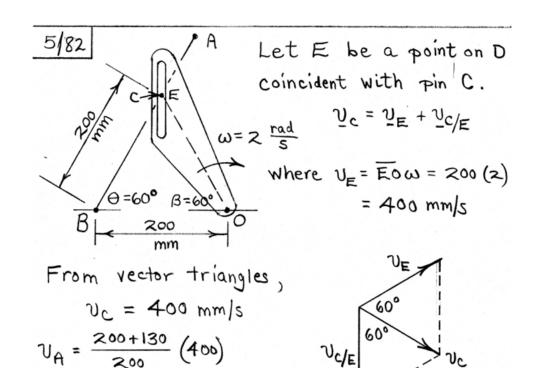
5/79 (a)
$$v_{A} = v_{B} = r\omega$$
 (right)

$$\omega_{BC} = \frac{v_{B}}{BC} = \frac{r\omega}{r}$$

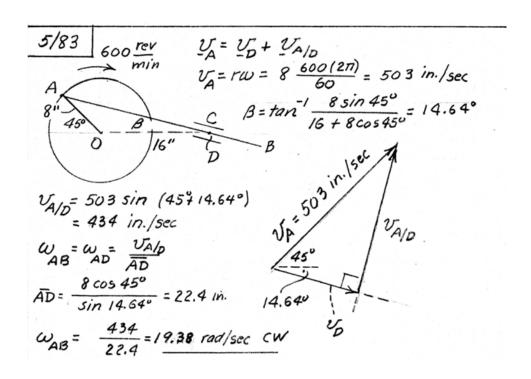
$$= \omega \quad CCW$$
(b) $v_{A} = v_{B} = z_{r}\omega$ (right)
$$\omega_{BC} = \frac{v_{B}}{BC} = \frac{z_{r}\omega}{r} = z_{r}\omega \quad CCW$$

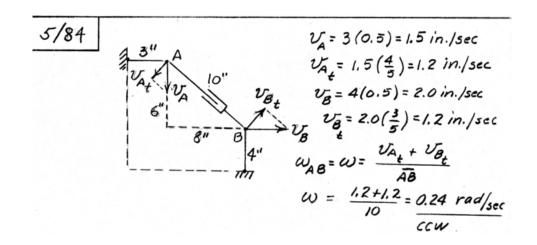


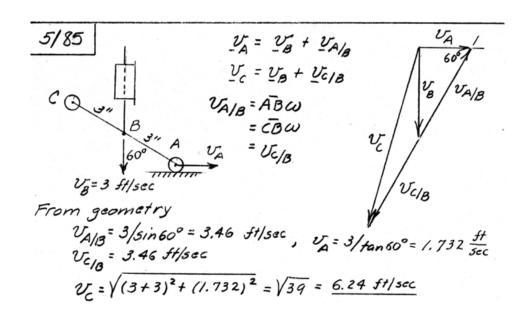


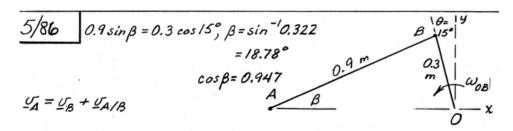


= 660 mm/s







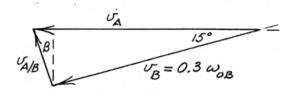


 $I \text{ (Vector algebra) } \underline{\sigma_A} = \underline{\sigma_A} \underline{i}, \underline{\sigma_B} = \underline{\omega_{OB}} \times \underline{r_{OB}}$ $= \underline{\omega_{OB}} \underline{k} \times (-0.3 \times 0.259 \underline{i} + 0.3 \times 0.966 \underline{j}) = \underline{\omega_{OB}} (-0.0776 \underline{j} - 0.290 \underline{i})$ $\underline{\sigma_{A/B}} = \underline{\omega_{AB}} \times \underline{r_{AB}} = -0.086 \underline{k} \times 0.9 (-0.947 \underline{i} - 0.322 \underline{j}) = 0.0733 \underline{j} - 0.0249 \underline{i} \text{ m/s}$ $So \ \underline{\sigma_A} \underline{i} = -0.0776 \underline{\omega_{OB}} \underline{j} - 0.290 \underline{\omega_{OB}} \underline{i} + 0.0733 \underline{j} - 0.0249 \underline{i}$ $\underline{j} - terms: \ \underline{\omega_{OB}} = \frac{0.0733}{0.0776} = \underline{0.944} \text{ rad/s } \underline{CCW}$ $\underline{i} - terms: \ \underline{\sigma_A} = -0.290 (0.944) - 0.0249 = -0.298 \underline{m/s} \text{ (neg. x-dir)}$

II(Vector geometry)

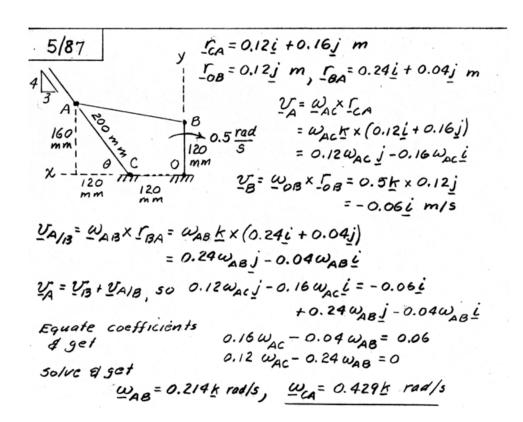
U_{A/8} = 0.9(0.086)

= 0.0774 m/s

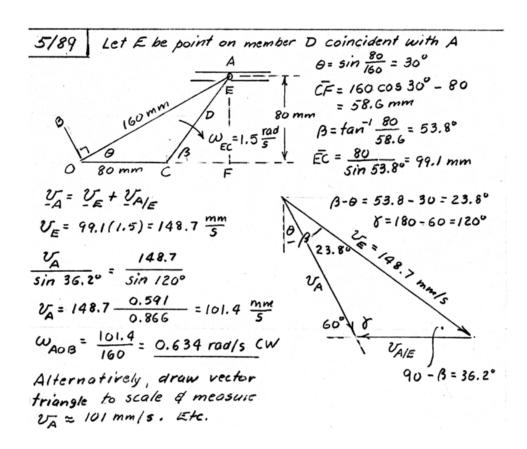


Law of sines: $\frac{0.0774}{\sin 15^{\circ}} = \frac{0.3 \,\omega_{oB}}{\sin (90^{\circ}-18.78^{\circ})}, \frac{\omega_{oB} = 0.944 \,\text{rad/s CCW}}{\cos (90^{\circ}-18.78^{\circ})}$

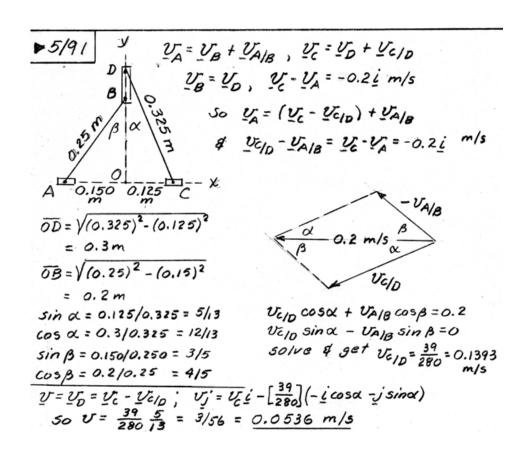
 $\sigma_A = 0.3(0.944)\cos 15^{\circ} + 0.0774 \sin 18.78^{\circ},$ $\sigma_A = 0.298 \text{ m/s to the left}$



5/88 ω_{AB} ω_{AB



 $5/90 \quad \omega_{CB} = -\frac{2\pi}{2} \frac{rod}{s} \text{ or } \quad \omega_{CB} = -\pi \frac{1}{K} \frac{rod}{s}$ $D \quad f_{OA} = -0.1 \underline{i} + 0.2 \underline{j} \quad m, \quad f_{CB} = 0.05 \underline{j} \quad m$ $\int_{BA} = -0.3 \underline{i} + 0.05 \underline{j} \quad m, \quad f_{OD} = 0.6 \underline{j}, \quad \omega_{AB} \underline{k} \times (-0.3 \underline{i} + 0.05 \underline{j})$ $0.6 \quad = -0.3 \omega_{AB} \underline{j} - 0.05 \omega_{AB} \underline{i}$ $U_{A} = \omega_{OA} \underline{k} \times (-0.1 \underline{i} + 0.2 \underline{j})$ $= -0.1 \omega_{OA} \underline{j} - 0.2 \omega_{OA} \underline{i}$ $B \quad U_{A} = U_{B} + U_{A} \underline{j} \quad so$ $0.2 \quad 0.1 \quad mC \quad -0.1 \omega_{OA} \underline{j} - 0.2 \omega_{OA} \underline{i} = 0.05 \pi \underline{i}$ $0.1 \quad mC \quad -0.1 \omega_{OA} \underline{j} - 0.2 \omega_{OA} \underline{i} = 0.05 \pi \underline{i}$ $0.1 \quad mC \quad -0.1 \omega_{OA} \underline{j} - 0.2 \omega_{OA} \underline{i} = 0.05 \pi \underline{i}$ $0.1 \quad mC \quad -0.1 \omega_{OA} \underline{j} - 0.2 \omega_{OA} \underline{i} = 0.05 \pi \underline{i}$ $0.1 \quad mC \quad -0.1 \omega_{OA} \underline{j} - 0.2 \omega_{OA} \underline{i} = 0.05 \pi \underline{i}$ $0.1 \quad mC \quad -0.2 \omega_{OA} + 0.05 \omega_{AB} \underline{i} = 0.05 \pi$ $me ters \quad -0.1 \omega_{OA} + 0.3 \omega_{AB} = 0$ $Solve \notin get \quad \omega_{AB} = -0.0909 \pi \underline{k} = -0.286 \underline{k} \quad rod/s \quad (Cw)$ $\omega_{OA} = -0.273 \pi \underline{k} = -0.857 \underline{k} \quad rod/s \quad (Cw)$ $U_{E} = U_{D} = 0.6 \omega_{OB} = 0.6 \omega_{OA} = 0.6 \quad (0.857) = 0.514 \quad m/s$

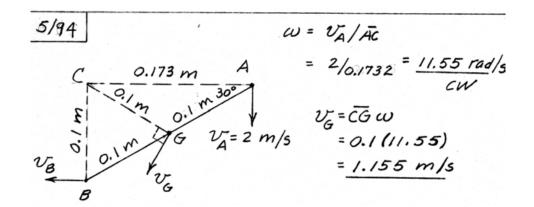


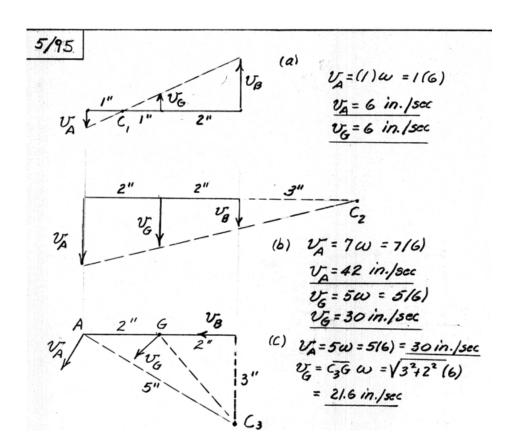
Thus $\omega = \omega_{CD} = \frac{2.26}{0.1239} = 18.22 rad/s ccw$

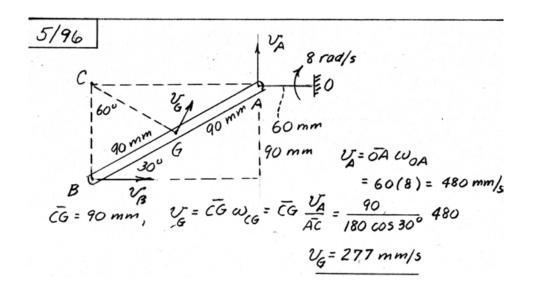
Instantaneous center C

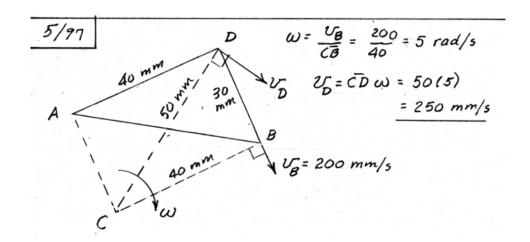
of zero velocity must lie

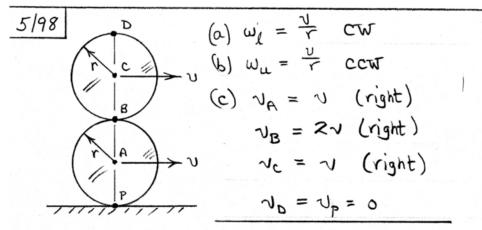
on the perpendicular to U_A at a distance from A of $U = r\omega$, $AC = r = \frac{U}{\omega} = \frac{2.8}{12}$ = 0.233 m or 233 mm $CB^2 = (160 - 233 \sin 30^\circ)^2$ $+ (233 \cos 30^\circ - 120)^2$ $= 8614 \text{ mm}^2$, CB = 92.8 mm $U_B = CB \omega = 0.0928 (12) = 1.114 \text{ m/s}$



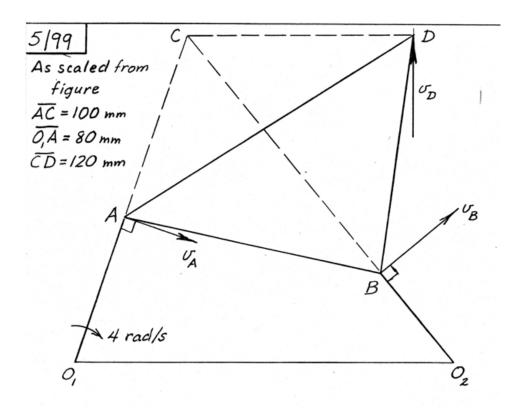






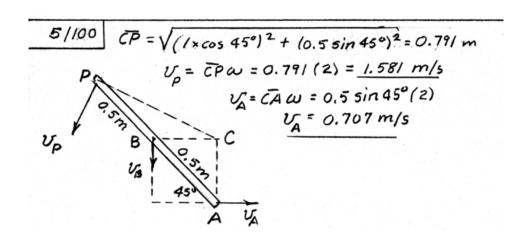


The mechanics hands have no absolute velocity!



$$U_A = O_1A \omega = 0.80(4) = 0.32 \text{ m/s}$$

$$U_D/\overline{CD} = V_A/\overline{AC}$$
, $U_D = \frac{0.120}{0.100} 0.32 = \frac{0.38 \text{ m/s}}{0.100}$



$$\frac{5/101}{V_{B}} \frac{B}{\beta \beta'} \frac{\lambda'}{\lambda'} \frac{\chi = 120^{\circ}}{\chi = 120^{\circ}} \frac{\sin 60^{\circ}}{L} = \frac{\sin \beta}{0.85L}$$

$$\beta = 47.4^{\circ}$$

$$\alpha = 180 - 60^{\circ} - 47.4^{\circ}$$

$$\alpha = 17.40^{\circ}$$

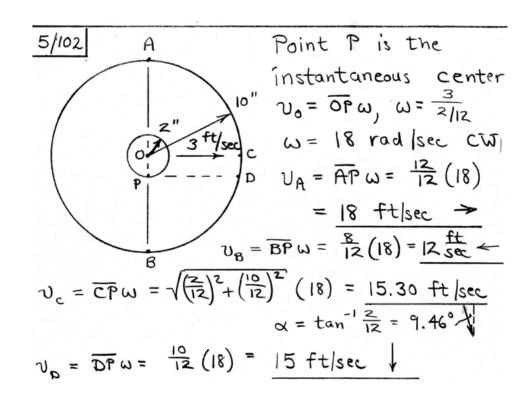
$$\beta = 42.6^{\circ}, \alpha' = 17.40^{\circ}$$

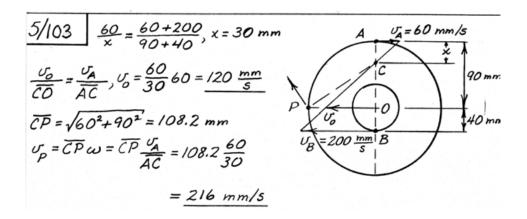
$$\frac{\sin \lambda'}{L} = \frac{\sin \alpha'}{BC}, BC = 0.782L$$

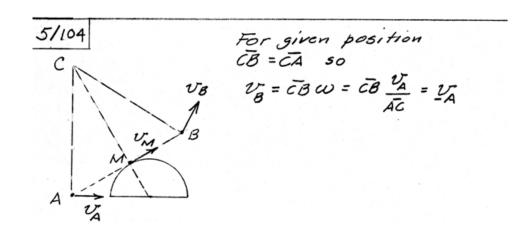
$$\frac{\sin \lambda'}{L} = \frac{\sin \alpha'}{BC}, BC = 0.345L$$

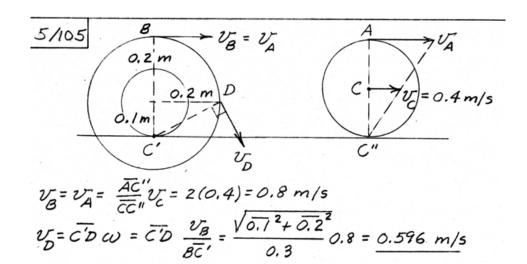
$$V_{A} = AC \omega, \omega = \frac{2}{0.782L} = \frac{2}{0.782(0.8)} = \frac{3.20 \frac{\text{rad}}{S}}{S}$$

$$V_{B} = BC \omega = 0.345(0.8)(3.20) = 0.884 \frac{\text{m/s}}{S}$$

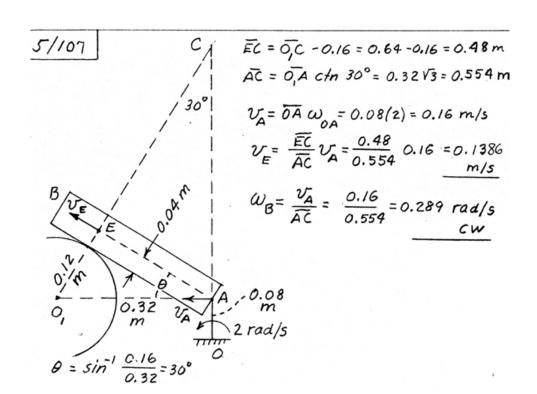




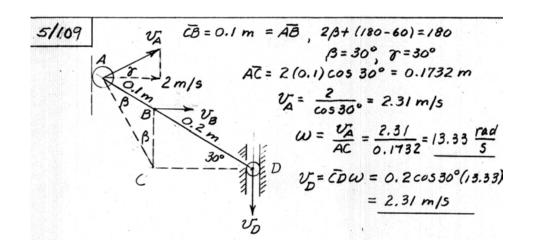


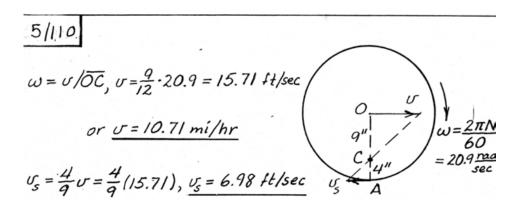


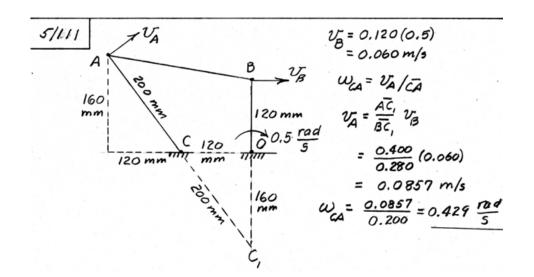
 $\sqrt[3]{106}$ C = instantaneous center $v_0 = \overline{OC}\omega = 0.75 (10^{-3}) (\frac{1800 \cdot 20}{60})$ = 0.1414 m/s

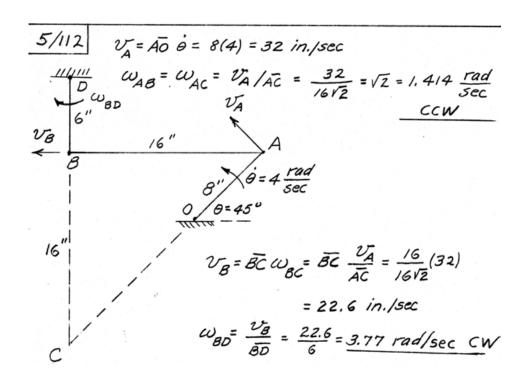


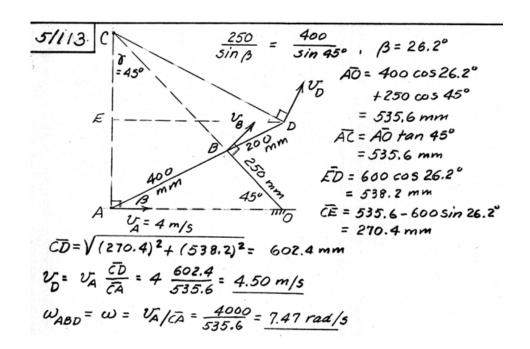
5/108 $U_{C} = \overline{CC}$, W_{AC} , $W_{AC} = W_{AB} = U_{B}/\overline{BC}$, $= \frac{3}{\frac{3}{12}} \sin 60^{\circ} = 13.86$ C $C\overline{CC}$, $= \sqrt{(3 \sin 30^{\circ})^{2} + (6 \cos 30^{\circ})^{2}} = 5.41 \text{ in.}$ $V_{C} = \frac{5.41}{12} (13.86) = 6.24 \frac{ft}{sec}$ $V_{C} = 3 \text{ ft/sec}$ $V_{C} = 3 \text{ ft/sec}$

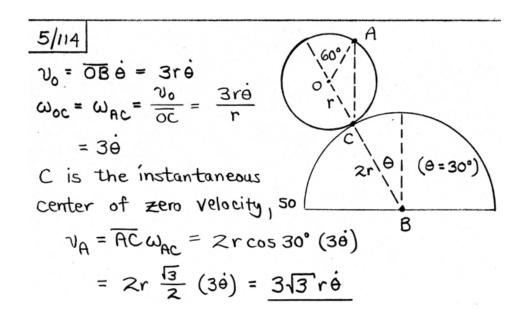


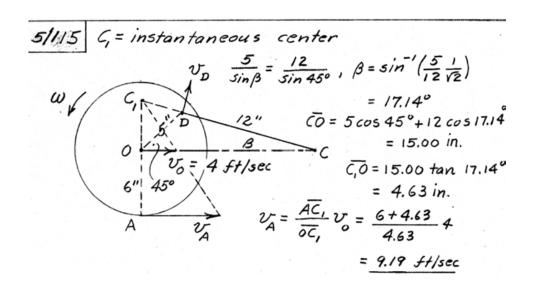


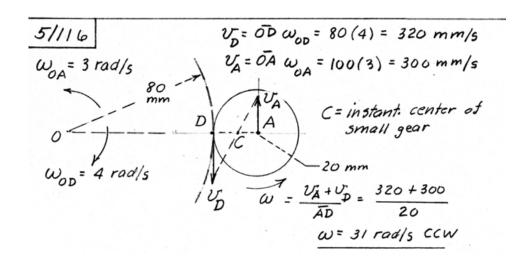


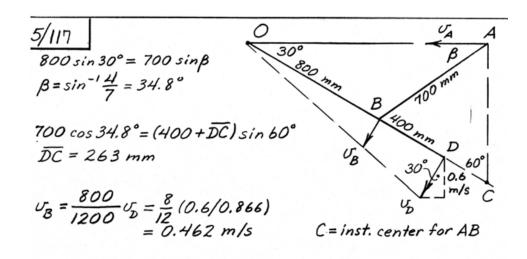




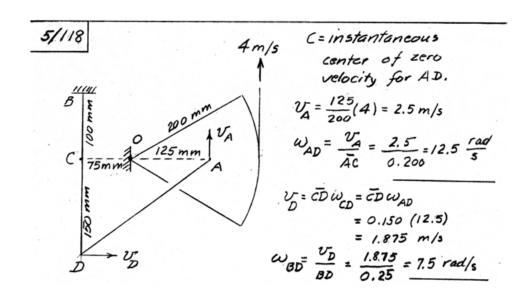








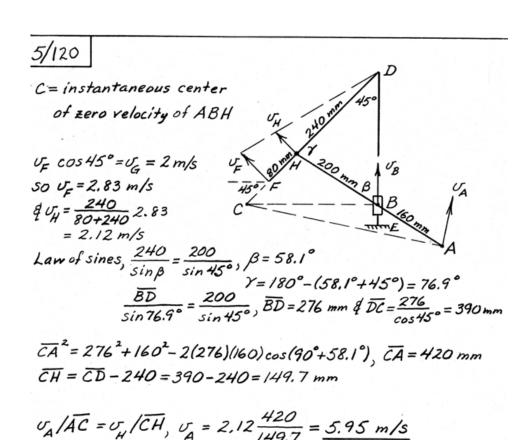
$$U_A/AC = U_B/BC$$
, $U_A = \frac{732}{400+263}$ 0.462 = 0.509 m/s

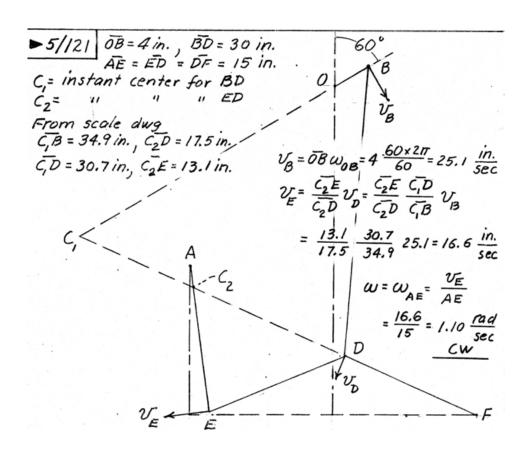


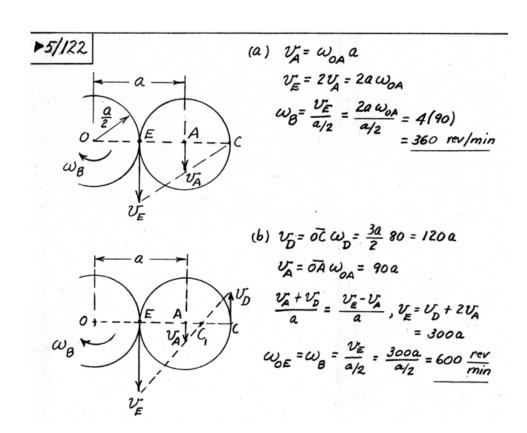
5/119 C is the instantaneous

center of Zero velocity for DBA

From geometry, $\overline{AC} = \frac{5}{3}(120) = 200 \text{ mm}$ $\overline{DC} = \sqrt{60^2 + 160^2}$ = 170.9 mm $8 = \sin^{-1}\frac{120}{200} = 36.9^{\circ}$ $9 = 90 - 36.9 - 20.6 = 32.6^{\circ}$ $9 = 90 - 36.9 - 20.6 = 32.6^{\circ}$ $9 = \frac{9}{\cos\beta} = \frac{0.2}{\cos 32.6^{\circ}} = 0.237 \text{ m/s}$ $\frac{9}{\overline{DC}} = \frac{9}{\overline{AC}}$ $\frac{9}{\overline{DC}} = \frac{9}{\overline{AC}}$ $\frac{9}{\overline{C}} = \frac{9}{\overline{C}} = \frac{$





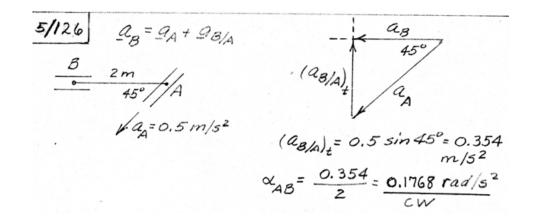


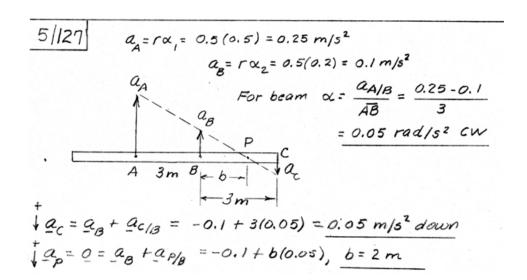
5/123 $Q_{A} = Q_{0} + (Q_{A/0})_{n} + (Q_{A/0})_{t}$ not function of W_{0} or sense $Q_{A/0} = Q_{0} = Q_{$

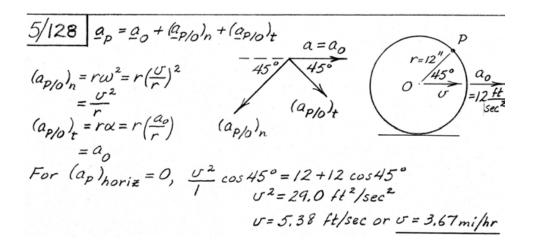
 $\frac{5/124}{\bar{Q}_{A}} = \frac{Q_{0} + (Q_{A/0})_{n} + (Q_{A/0})_{t}}{\bar{Q}_{A}}$ $\frac{\bar{Q}_{A}}{= 0.8 \text{ m}} = \frac{\bar{Q}_{0} + (Q_{A/0})_{n} + (Q_{A/0})_{t}}{\bar{Q}_{A}}$ $\frac{\bar{Q}_{0}}{= 3 \text{ m/s}^{2}} \qquad (Q_{A/0})_{t} = \bar{A}_{0} = 0.8 (5) = 4 \text{ m/s}^{2}$ $\frac{\bar{Q}_{A}}{\bar{Q}_{0}} = \frac{\bar{Q}_{0} + (Q_{A/0})_{t}}{\bar{Q}_{A/0}} = \frac{\bar{Q}_{0} + (Q_{A/0})_{t}}{\bar{Q}_{0}} = \bar{Q}_{0} = 0.8 (5) = 4 \text{ m/s}^{2}$ $\frac{\bar{Q}_{A}}{\bar{Q}_{0}} = \frac{\bar{Q}_{0} + (Q_{A/0})_{t}}{\bar{Q}_{0}} = \bar{Q}_{0} = 0.8 (5) = 4 \text{ m/s}^{2}$ $\frac{\bar{Q}_{A}}{\bar{Q}_{0}} = \frac{\bar{Q}_{0} + (Q_{A/0})_{t}}{\bar{Q}_{0}} = \bar{Q}_{0} = 0.8 (5) = 4 \text{ m/s}^{2}$

$$\frac{5/125}{r^{2}} | y \qquad a_{0} = \frac{Gm_{S}}{r^{2}} \\
= \frac{6.673(10^{-11})[5.976 \cdot 10^{24} \cdot 333000]}{[149.6(10^{9})]^{2}} \\
= 0.00593 \text{ m/s}^{2} (4) \\
R\omega^{2} = 6371(10^{3})[7.292(10^{-5})]^{2} \\
= 0.0339 \text{ m/s}^{2} (\Rightarrow)$$

$$\underline{a_{B}} = \underline{a_{0}} + \underline{a_{B/o}} = -0.00593\underline{i} + 0.0339\underline{i} \\
= 0.0279\underline{i} \text{ m/s}^{2}$$



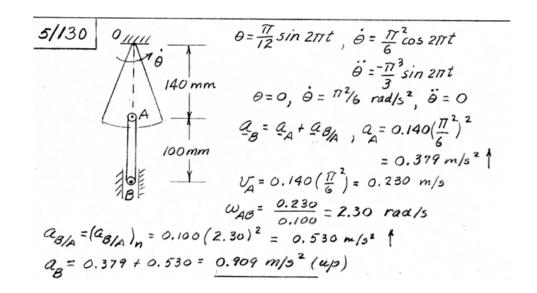


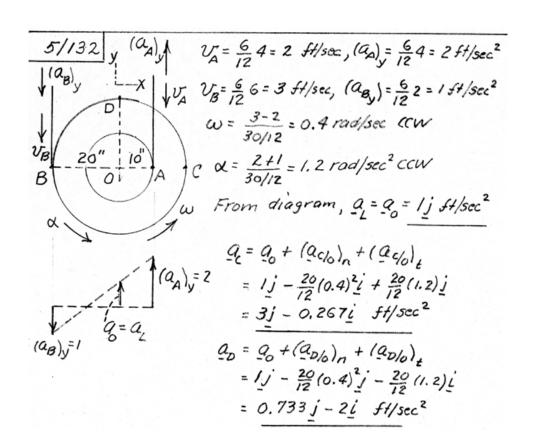


5/129 In the coordinates shown, the no-slip

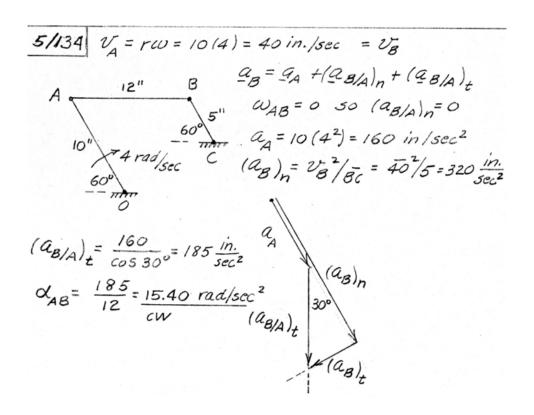
Kinematic constraints are $v_0 = -r\omega$, $q_0 = -r\omega$.

So $\omega = -\frac{y_0}{r} = -\frac{3}{0.4} = -7.5 \text{ rad/s}$ $\alpha = -\frac{q_0}{r} = -\frac{5}{0.4} = 12.5 \text{ rod/s}^2$ $y_0 = y_0 + y_0 = y_0 + \omega x y_0$ $y_0 = y_0 + y_0 = y_0 + \omega x y_0$ $y_0 = y_0 + y_0 = y_0 + \omega x y_0$ $y_0 = y_0 + y_0 = y_0 + \omega x y_0$ $y_0 = y_0 + y_0 = y_0 + \omega x y_0$ $y_0 = y_0 + y_0 = y_0 + \omega x y_0$ $y_0 = y_0 + y_0 = y_0 + \omega x y_0$ $y_0 = y_0 + y_0 = y_0 + \omega x y_0$ $y_0 = y_0 + y_0 = y_0 + \omega x y_0$ $y_0 = y_0 + y_0 = y_0 + \omega x y_0$ $y_0 = y_0 + y_0 = y_0 + \omega x y_0$ $y_0 = y_0 + y_0 = y_0$ $y_0 = y_0 + y_0$ $y_0 = y_0$

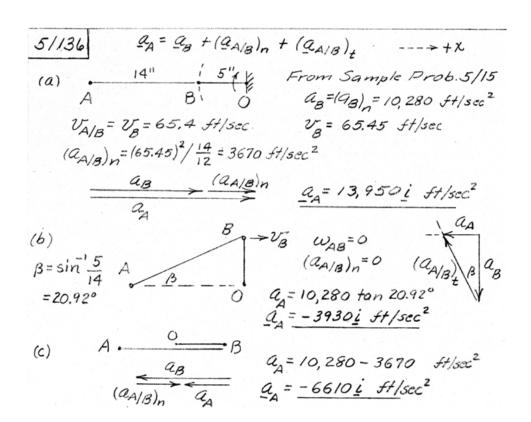


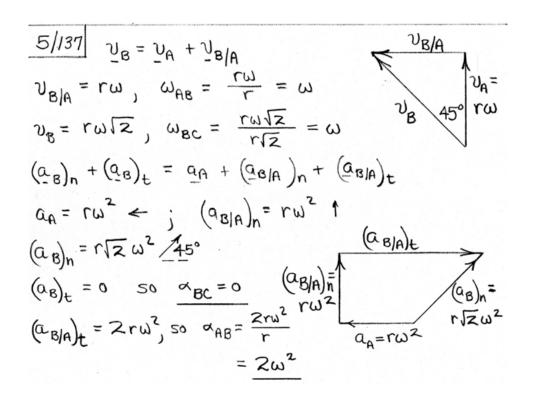


5/133 From the solution to Prob. 5/102 or from $v_0 = r\omega$, $\omega = \frac{v_0}{r} =$ $\frac{3}{2/12} = 18 \text{ rad/sec CW}.$ From $a_0 = r\alpha$, $\alpha = \frac{a_0}{r} = \frac{4}{2/12} = 24 \frac{rad}{sec^2}$ aA = a0 + aA10 = a0 + xxA10-w2rA10 $=-4i+24kx\frac{10}{12}j-18^{2}(\frac{10}{12}j)$ = - 24i - 270j ft/sec2 $a_D = a_0 + a_{D/0} = a_0 + \alpha \times r_{D/0} - \omega^2 r_{D/0}$ = - 4i + 24kx (10 cos sin 10 i - 12 j) - 182 (10 cos sin 1 70 1 - 72 1) = - 265 i + 73.6 j ft/sec2 (Could use P as a base point for ap.)



5/135
$$\frac{1}{30^{\circ}}$$
 $\frac{1}{1.2}$ $\frac{1}{1.2}$ $\frac{30^{\circ}}{1.2}$ $\frac{1}{1.2}$ $\frac{30^{\circ}}{1.2}$ $\frac{1}{1.2}$ $\frac{1}{1.2}$





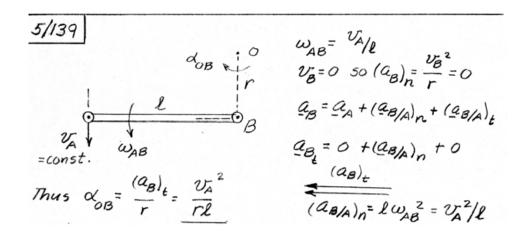
5/138
$$\omega_1 = \frac{v_B}{0.3} = \frac{v_A}{0.3} = \omega_2 = \frac{2(0.4)}{0.3} = \frac{8}{3} \operatorname{rad}/s$$

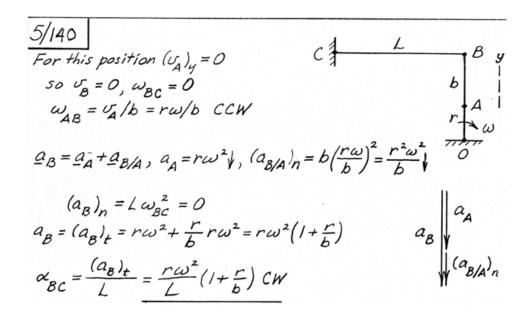
B

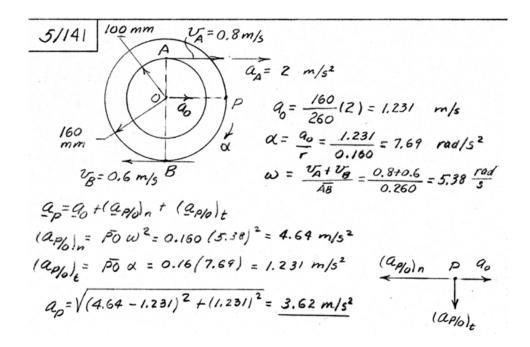
A

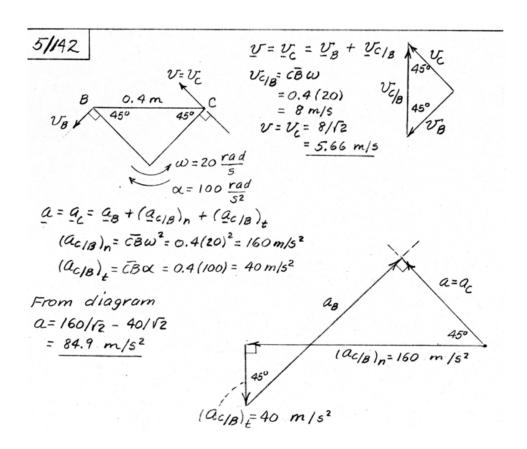
200 mm

 $v = 0.4 \text{ m/s}$
 $v = 0.4 \text{ m/s}$
 $v = 0.4 \text{ m/s}$
 $v = 0.8 \text{ m/s}^2$
 $v = 0.8 \text{ m/s}^2$

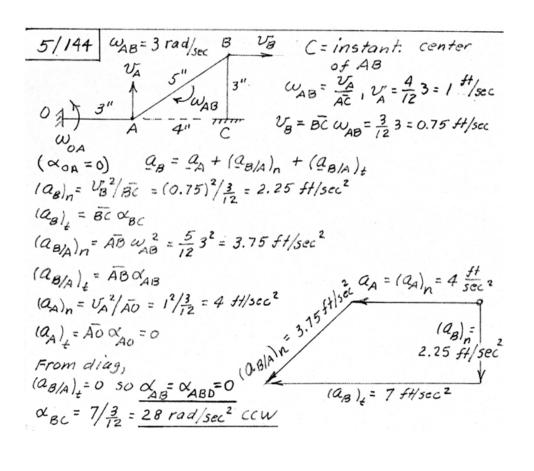








5/143 From Prob. 5/87, $\omega_{AB} = 0.214 \, \text{K}$, $\omega_{CA} = 0.429 \, \text{K}$ $\frac{rad}{s}$ $\omega = 0.5 \, \text{rad/s}$ y $\omega_{A} = \omega_{B} + (\Omega_{A}|B)_{R} + (\Omega_{A}|B)_{L} - --- (\alpha)$ $\omega = 0.5 \, \text{rad/s}$ y $\omega_{A} = \omega_{CA} \times (\omega_{CA} \times C_{A}) + \omega_{CA} \times C_{CA}$ $\omega = 0.5 \, \text{rad/s}$ y $\omega_{A} = \omega_{CA} \times (\omega_{CA} \times C_{A}) + \omega_{CA} \times C_{CA}$ ω_{CONST} : $\omega_{A} = \omega_{CA} \times (\omega_{CA} \times C_{A}) + \omega_{CA} \times C_{CA}$ ω_{CONST} : ω_{CONST} :



5/145 y ω_{AB} $\omega_{B} = \alpha_{A} + \alpha_{B/A}$ $\omega_{AB} = \omega_{B} = \alpha_{A} + \alpha_{B/A}$ $\omega_{AB} = \omega_{BC} \times (\omega_{BC} \times r_{B/C}) + \alpha_{BC} \times r_{B/C}$ $\omega_{AB} = \omega_{BC} \times (\omega_{BC} \times r_{B/C}) + \alpha_{BC} \times r_{B/C}$ $\omega_{AB} = \omega_{BC} \times (\omega_{BC} \times r_{B/C}) + \alpha_{BC} \times r_{B/C}$ $\omega_{AB} = \omega_{BC} \times (\omega_{BC} \times r_{B/C}) = 5.83 \text{ k} \times (5.83 \text{ k} \times 0.18 \text{ j})$ $\omega_{AB} = \omega_{AB} \times (\omega_{AB} \times r_{B/A}) = -6.125 \text{ j} - 0.18 \times \alpha_{BC} \cdot m/s^{2}$ $\omega_{AB} = \omega_{AB} \times (\omega_{AB} \times r_{B/A}) = 10 \text{ k} \times (10 \text{ k} \times [-0.06 \text{ i} + 0.08 \text{ j}])$ $\omega_{AB} = \omega_{AB} \times (\omega_{AB} \times r_{B/A}) = 2.5 \text{ k} \times (2.5 \text{ k} \times [0.24 \text{ i} + 0.1 \text{ j}])$ $\omega_{AB} = \omega_{AB} \times (\omega_{AB} \times r_{B/A}) = 2.5 \text{ k} \times (2.5 \text{ k} \times [0.24 \text{ i} + 0.1 \text{ j}])$ $\omega_{AB} = \omega_{AB} \times (0.24 \text{ i} + 0.1 \text{ j}) = -0.1 \times \omega_{AB} \cdot v_{AB} \cdot v_{AB}$

$$\frac{5/|A6|}{\omega_{CD}} \frac{U_{C}}{|\overline{CD}|} = \frac{1(0.4)}{3}$$

$$= 0.1333 \text{ rad/sec}$$

$$\frac{a_{C}}{a_{C}} = \frac{q_{D}}{|C|} + (\frac{q_{C}}{|C|})_{H} + (\frac{q_{C}}{|C|})_{H}$$

$$\frac{a_{C}}{|C|} = \frac{q_{D}}{|C|} + (\frac{q_{C}}{|C|})_{H} + (\frac{q_{C}}{|C|})_{H}$$

$$\frac{a_{C}}{|C|} = \frac{q_{D}}{|C|} + (\frac{q_{C}}{|C|})_{H} + (\frac{q_{C}}{|C|})_{H}$$

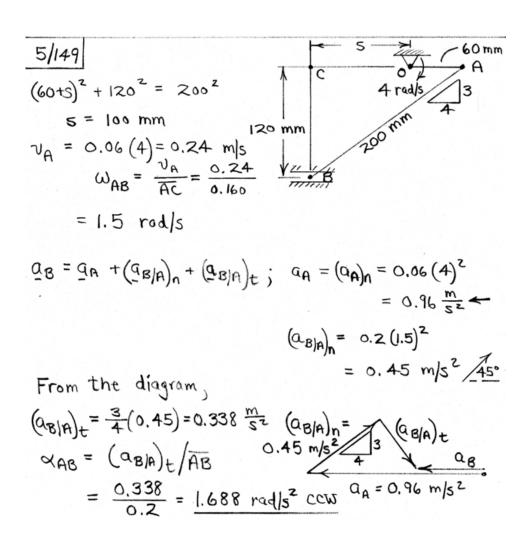
$$\frac{a_{C}}{|C|} = \frac{q_{D}}{|C|} + (\frac{q_{C}}{|C|})_{H}$$

$$\frac{a_{C}}{|C|} = \frac{q_{C}}{|C|} = \frac{q_{C}}{|C|}$$

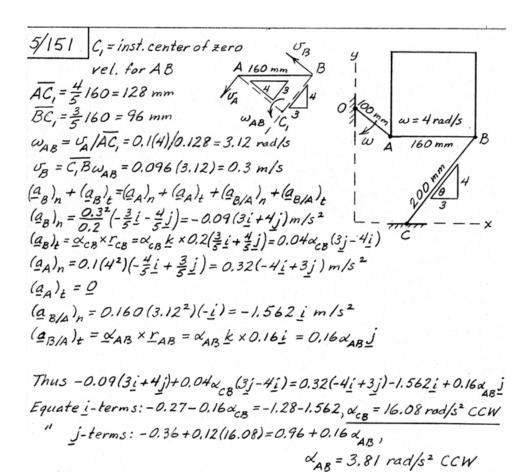
$$\frac{a_{C}}{|C|} = \frac{q_{C}}{|C|}$$

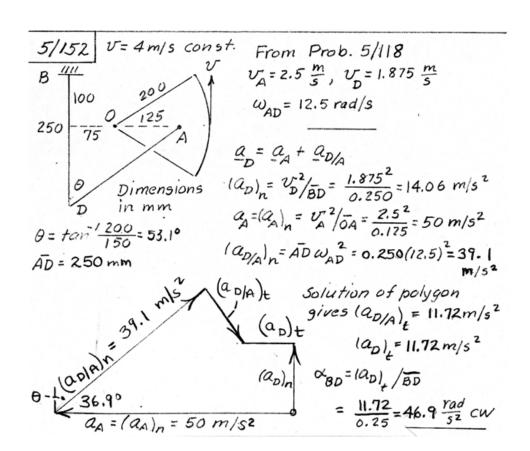
$$\frac{a_{C}}{|C$$

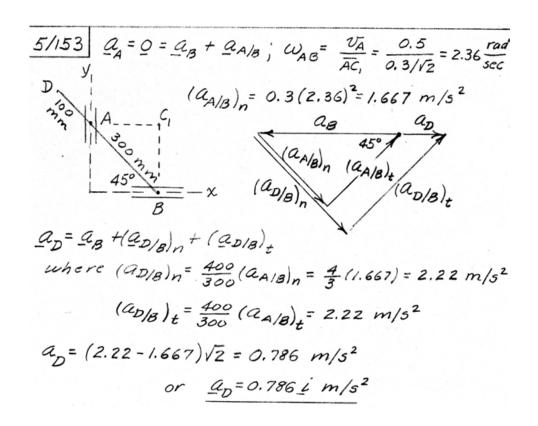
5/147 $U_B = U_A = \overline{OA} \omega_{OA} = 0.06(3) = 0.18 \, \text{m/s}^2$ WDB = UB /DB = 0.18/0.24 = 0.75 rad/s QB = QA + QB/A 0.24 m $\underline{a}_{\mathcal{B}_n} + \underline{a}_{\mathcal{B}_t} = \underline{a}_{A_n} + \underline{a}_{A_t} + \underline{a}_{\mathcal{B}/A_n} + \underline{a}_{\mathcal{B}/A_t}$ $\alpha_{B_n} = \overline{DB} \omega_{DB}^2 (-j) = 0.24(0.75)^2 (-j)$ = - 0.135 j m/s2 $a_{B_{+}} = \overline{DB} \propto_{DB} (-\underline{i}) = -0.24 \propto_{DB} \underline{i}$ an = OA wa (-j) = 0.06(32)(-j) = -0.54j m/s2 QA = OA doA (-i) = 0.06(10)(-i) = -0.6 i m/s2 $(a_{B/A})_n = \overrightarrow{BA} \omega_{AB}^2 = 0$ since $\omega_{AB} = 0$ (aB/A) = dAB k × AB = dAB k × (-0.24 i +0.18 j) = -0.24 dAB j -0.18 dAB i -0.135j-0.242 =-0.54j-0.6i+0-0.242 j-0.182 i j-terms: -0.135 = -0.54-0.24 dAB, dAB = -1.688 rad/s2 (CW) i-terms: -0.24 2 = -0.6-0.18(-1.688) dp8 = 1,234 rad/s + CCW



5/150 C= instantaneous center of zero velocity for AB $\frac{\sqrt{1450}^2 + (100)^2 + 439 \text{ mm}}{450 \text{ mm}} = \frac{B}{100} = \frac{\sqrt{18}}{439} = \frac{\sqrt{18}}{60} = \frac{\sqrt{18}}{60} = \frac{\sqrt{18}}{60} = \frac{\sqrt{18}}{60} = \frac{\sqrt{18}}{439} = \frac{\sqrt{18}}{60} =$





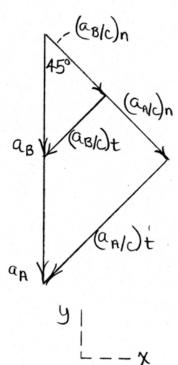


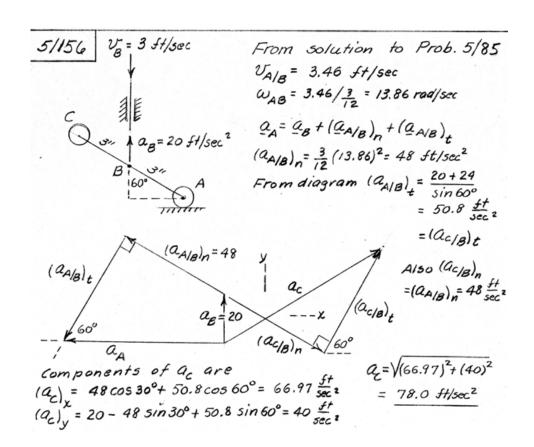
A By inspection using instant center, 5/154 WAB = 2 2 k = 20 k rad/s 2 m/s $a_8 = a_A + (a_{8/A})_n + (a_{8/A})_{+}, a_A = 0$ Vector algebra: Q= QBL, (QBA) = WABX (WABX [AB) =(20)2K×[K×0.2(13i-2j)] = 40 (- V3i + j) m/52 (a8/A) = 0 AB × [AB = 0 AB K × 0.2(1/2 i - 2j) = \(\alpha \(B \(\sqrt{3} \) + \(\infty \) Thus Qui = 0 + 40 (- V3 i + j) + 20 (V3 j + i) So a8 = - 40 + CLAB & 0 = 40 + CLAB V3 giving and = - 400 rad/s 2 & 98 = - 160 m/s2 Q= QA + QG/A = 0 + \(\frac{1}{2} (Q B/A)_n + \(\frac{1}{2} (Q B/A)_L = \frac{20}{3} (-13 \div + \div) - \frac{20}{3V3} (13 \div + \div) = - 80 i = - 15,40 i m/s2 Vector geometry: (28/A)n=0.2(20/73)2= 80/3 m/s2 (aB/A) = 0.2 aAB (ag/A)n= 1/2 (aB/A)n= 40/3 m/s2 (a_{G/A}),= 1/2 (a_{8/A}), = 0.1 ×_{AB} ag = 40 2 = 15.40 m/s2

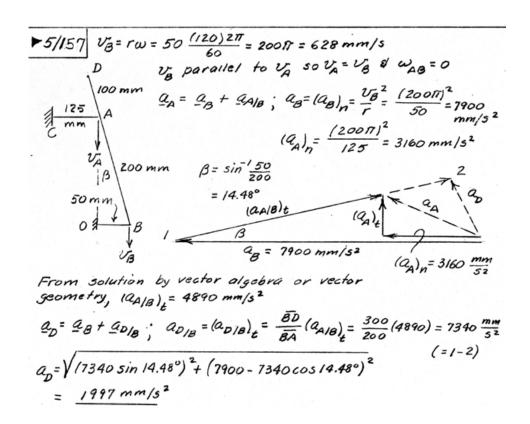
5/155 Q is instantaneous center of zero

Position of the sero of

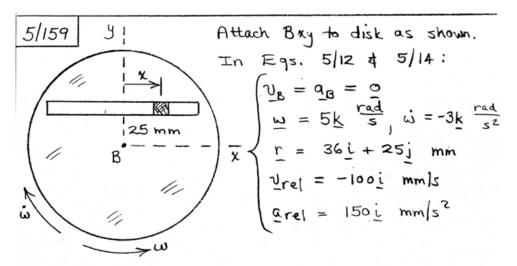
 $a_{B} = a_{C} + (a_{B/C})_{n} + (a_{B/C})_{t}$ $(a_{B/C})_{n} = BC \omega_{AC}^{2} = \frac{4}{12} (2.55)^{2}$ $= 2.16 \text{ ft/sec}^{2}$ $a_{BC} = \frac{(a_{B/C})_{t}}{BC} = \frac{2.16}{4/12}$ $= 6.48 \text{ rod/sec}^{2} \text{ CCW}$ $a_{A} = a_{C} + (a_{A/C})_{n} + (a_{A/C})_{t}$ $(a_{A/C})_{n} = AC \omega_{AC}^{2} = \frac{8}{12} (2.55)^{2}$ $= 4.32 \text{ ft/sec}^{2}$ $(a_{A/C})_{t} = 4.32 \text{ ft/sec}^{2}$ $(a_{A/C})_{t} = 4.32 \text{ ft/sec}^{2}$ $(a_{A/C})_{t} = 6.11 \text{ ft/sec}^{2}$







ω_{CR} = - πk rad/s , roa = -0.1i + 0.2j m $r_{cB} = 0.05j \text{ m}, r_{BA} = -0.3i + 0.05j \text{ m}$ $r_{oD} = 0.6j \text{ m}, v_{B} = 0.05\pi i \text{ m/s}$ (Dim. in m) UA/B = WABKX (-0.31 +0.05) = -0.3 WAB j - 0.05 WAB i $\frac{1}{100} = 0.05 \quad v_A = \omega_{0A} k \times (-0.1i + 0.2j)$ $= -0.1 \omega_{0A} j - 0.2 \omega_{0A} i$ From UA = VB + VAB: -0.1 WOA j - 0.2 WOA i = 0.05 mi - 0.3 WAB j - 0.05 WAB Equate like coefficients: [WAB = - 0.286 k rad/s (WOA = - 0.857k rad/s Now, an = aB + (aA/B)n + (aA/B)+ aA = - WOA TOA + YOA X YOA = $0.734(0.1i - 0.2j) + \alpha_{00}(-0.1j - 0.2i)$ (QA/B) = - WABTBA = 0.0816 (0.31-0.051) m/s2 (QAIB) = XABX TBA = XAB (-0.3j-0.05i) m/s2 Substitute into * equatelike coefficients, & obtain QE = (QD)n+(QD)t+(QE/D)n+(QE/D)t, (QE/D)n=0 since wo =0 a= = -0.6 (0.857) +0.6 (0.0519) + 4 ED KX (10.12 - 0.2) Solve to obtain <=== 1.272 rad/s, Q== 0.285 m/s2

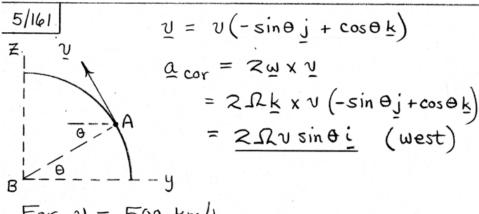


(5/12):
$$v_A = v_B + w_X r + v_{rel}$$
 gives $v_A = -225i + 180j$ mm/s

(5/14):
$$a_A = a_B + \omega \times \underline{r} + \omega \times (\omega \times \underline{r}) + 2\omega \times \underline{v}_{rel} + \underline{a}_{rel}$$
gives $a_A = -675\underline{i} - 1733\underline{j} \quad mm/s^2$

5/160 For the coordinates $\frac{19}{4}$ The no-slip constraints are $v_0 = -r\omega$ is $a_0 = -r\alpha$. So $\omega = -\frac{y_0}{r} = -\frac{3}{0.30} = 10 \text{ rad/s}$ $\omega = -\frac{y_0}{r} = -\frac{5}{0.30} = -16.67 \text{ rad/s}^2$ Use the frame $0 \times y$ as disk-fixed.

(5/12): $v_0 = v_0 + \omega \times r + v_{rel}$ (5/14): $v_0 = v_0 + \omega \times r + v_{rel}$ (5/14): $v_0 = v_0 + v_0 \times r + v_0 \times v_{rel} + v_0 \times v_{rel} + v_0 \times v_$



For v = 500 km/h,

- (a) Equator, $\theta = 0$: $a_{cor} = 0$ (b) North pole, $\theta = 90^{\circ}$: $a_{cor} = 2(7.292 \cdot 10^{-5}) \frac{500}{3.6}$ = 0.0203 m/s2

The track provides the necessary westward acceleration so that the velocity vector is properly rotated and reduced in magnitude. 5/162 $a_{cor} = 2 \omega \times vre|_{= 2 \omega k \times uj} = -2 \omega ui$ B

Change-of-direction effect is in -x direction: $a_{u} = -x$ Change-of-magnitude effect is in -x direction: $\omega(d+ad) + \omega L$ $\omega(d+ad)$

(a) North pole

2wx Vrel

Aw

Only horizontal component of accederation

is |2wx Vrel| = 2(0.7292)(10-4)(15) = 0.00219 m/s²

EF= ma; R= 50000 (0.00219) = 109.4 N

(b) Equator

Vrel

Vrel

Vrel

W

A w

A vrel

Vrel

Vrel

Vrel

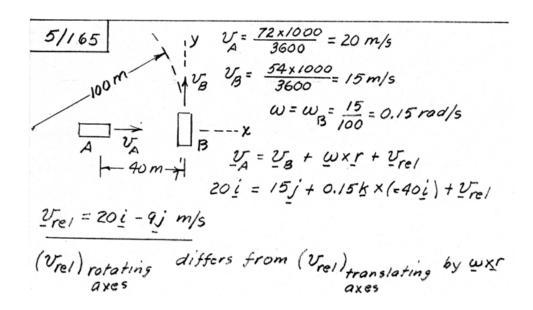
So 2wx Vrel = 0 & there

N-S

Is no other horizontal

accederation so R=0

5/164 $V_c = 25000/3600 = 6.94 \text{ m/s}$ $W = V_c/p = 6.94/60$ 10m 10m = 0.1157 rad/s W = 0.1157 rad/s



5/166 From Prob. 5/165 $V_{rel} = 20i - 9j \, m/s$ $\omega = 0.15 \, k \, rad/s$ $Q_A = Q_B + \omega \times (\omega \times r) + \omega \times r + 2\omega \times V_{rel} + Q_{rel}$ $Q_A = 0$, $Q_B = \frac{V_B^2}{R}(-i) = -\frac{15^2}{100}i = -2.25i \, m/s^2$ $\omega \times (\omega \times r) = 0.15 \, k \times (0.15 \, k \times [-40i] = 0.90i \, m/s^2$ $\dot{\omega} \times \dot{r} = 0$ $2\omega \times V_{rel} = 2(0.15 \, k) \times (20i - 9j) = 2.7i + 6j \, m/s^2$ Thus $0 = -2.25i + 0.90i + 0 + 2.7i + 6j + Q_{rel}$ $Q_{rel} = -1.35i - 6j \, m/s^2$

5/167 $x = 2 \sin 4\pi t$, $\dot{x} = 8\pi \cos 4\pi t$, $\dot{x} = -32\pi^2 \sin 4\pi t$ $\theta = 0.2 \sin 8\pi t$, $\dot{\theta} = 1.6\pi \cos 8\pi t$, $\ddot{\theta} = -12.8\pi^2 \sin 8\pi t$ (a) For x = 0 & \dot{x} (+); t = 0, $v_{rel} = \dot{x} = 8\pi$ in./sec $a_A = 2\omega \times v_{rel} + a_{rel}$ $a_{rel} = \ddot{x} = 0$ $= 2(1.6\pi)(8\pi)j + 0$ $\omega = \dot{\theta} = 1.6\pi$ rad/sec = 253j in./sec² $\dot{\omega} = \ddot{\theta} = 0$ (b) For x = +2 in., $\sin 4\pi t = 1$, $\cos 4\pi t = 0$, t = 1/8 sec $\theta = 0$ $v_{rel} = \dot{x} = 0$, $\ddot{x} = -32\pi^2$ in./sec² $\omega = \dot{\theta} = -1.6\pi$ rad/sec $\dot{\omega} = \dot{\theta} = 0$ $a_A = \dot{\omega} \times r + \dot{\omega} \times (\dot{\omega} \times r) + 2\dot{\omega} \times v_{rel} + a_{rel}$ $\dot{\omega} \times r = 0$, $\dot{\omega} \times (\dot{\omega} \times r) = -2(1.6\pi)^2 i = -5.12\pi^2 i$ in./sec² $2\omega \times v_{rel} = 0$, $a_{rel} = \ddot{x}i = -32\pi^2 i$ in./sec² $a_B = -5.12\pi^2 i - 32\pi^2 i = -366i$ in./sec² 5/168 Let P be a point on the road coincident with A. $Q = Q_p + 2\omega \times V_{re} + Q_{re}$ E A 2 $\omega \times V_{re}$ For zero vertical acceleration,

The property of V_{re} V_{re}

5/169 $|2\omega \times v_{re}||$ For zero vertical accel, $|E|| |v_{re}|| ||2\omega \times v_{re}|| = |R\omega|^2 + |v_{re}|^2 ||R||$ $|V_{re}|| ||2\omega \times v_{re}|| = |R\omega|^2 + |v_{re}|^2 ||R||$ $|V_{re}|| = |V_{re}|| + |V_{$

 5/171 $v_A = 72 \text{ km/h}, \quad v_A = v_B + \omega \times r + v_{rel}$ Angular velocity of axes

is $\omega = \frac{72/3.6}{100} = 0.2 \text{ rad/s}$ $v_B = 72 \text{ km/h} - v_B$ $v_B = 72/3.6 = 0.2 \text{ rad/s}$ $v_B = 72$

5/172 Refer to figure and solution for Prob. 5/171 where $v_{rel} = -46i$ m/s w = 0.2k rad/s const. $Q_A = Q_B + \omega \times (\omega \times r) + \omega \times r + 2\omega \times v_{rel} + 2v_{rel}$ $Q_A = (v^2/\rho)(-j) = -\frac{20}{100}j = -4j$ m/s², $(Q_A)_{t} = 0$ $Q_B = (v^2/\rho)(+j) = +4j$ m/s² $(Q_B)_{t} = 0$ $\omega \times (\omega \times r) = 0.2k \times (0.2k \times [-30j]) = 1.2j$ m/s² $\omega \times r = 0$ $2\omega \times v_{rel} = 2(0.2k) \times (-46i) = -18.4j$ m/s²

50 Qrel = -4j-4j-1.2j + 18.4j = 9.2j m/s2

 $\frac{5/173}{U_{B} = 480 \frac{44}{30}} = 704 \text{ ft/sec}$ $U_{A} = 360 \frac{44}{30} = 528 \text{ ft/sec}$ $\underline{U_{A}} = \underline{U_{B}} + \underline{\omega} \times \underline{r} + \underline{U_{rel}}$ Angular vel. of axes = $\underline{\omega} = \frac{U_{B}(-\underline{k})}{P_{red}}$ $= \frac{-704}{9 \times 5280} \underline{k} = -0.01481 \underline{k}^{P} \text{ rad/sec}$ $\underline{U_{rel}} = \text{vel. of A rel. to B}$ $\underline{r} = 5(5280)\underline{i} = 26,400\underline{i} \text{ ft}$ Thus $528(-0.707\underline{i} - 0.707\underline{j}) = 704\underline{j} - 0.01481 \underline{k} \times 26,400 \underline{i} + \underline{U_{rel}}$ $\underline{U_{rel}} = -373\underline{i} - 686\underline{j} \text{ ft/sec} \text{ with } \underline{U_{rel}} = 781 \text{ ft/sec}$ or 533 mi/hr

5/174 Refer to solution for Prob. 5/173.

 $\underline{a}_{A} = \underline{a}_{B} + \underline{\omega} \times \underline{r} + \underline{\omega} \times (\underline{\omega} \times \underline{r}) + 2\underline{\omega} \times \underline{\sigma}_{rel} + \underline{a}_{rel}$

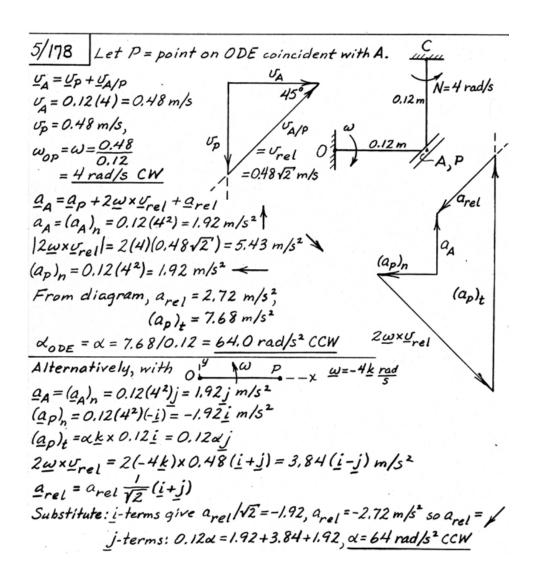
 $a_{A} = 0$, $a_{B} = \frac{\sigma_{B}^{2}}{\rho} i = \frac{704^{2}}{9 \times 5280} i = 10.43 i \text{ ft/sec}^{2}$ $\dot{\omega} \times r = 0$

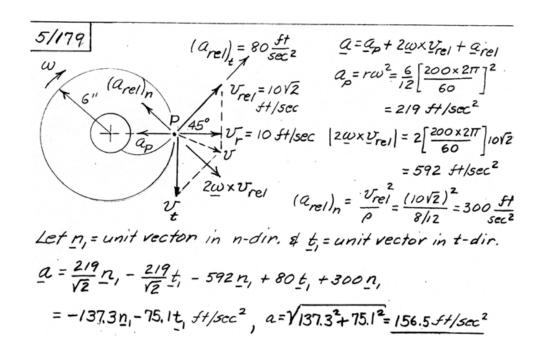
 $\omega \times (\omega \times r) = -0.01481 \, \underline{k} \times (-0.01481 \, \underline{k} \times 26,400 \, \underline{i}) = -5.79 \, \underline{i} \, H/sec^2$ $2\omega \times \underline{\nu}_{rel} = 2(-0.1481 \, \underline{k}) \times (-373 \, \underline{i} - 686 \, \underline{j}) = 11.05 \, \underline{j} - 23.0 \, \underline{i} \, H/sec^2$

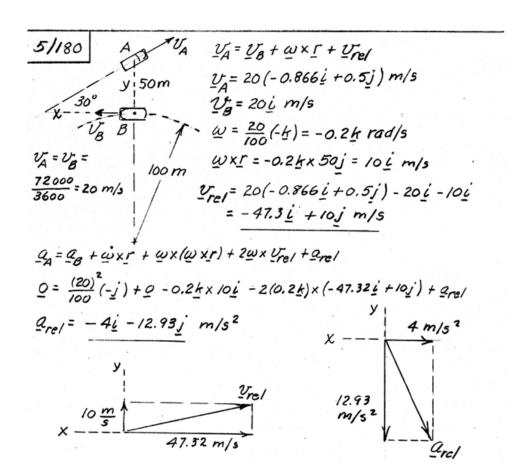
 $a_{rel} = 0 - 10.43i - 0 + 5.79i - 11.05j + 20.3i = 15.69i - 11.05j ft/sec^2$ where $a_{rel} = 19.19 \text{ ft/sec}^2$

5/175 Attach x-y axes to earth with \overline{z} -axis pointing toward N-pole. Angular velocity of hour hand y way we Equator relative to clock is $\omega_r = 2\pi/12$ cw $\omega_r = 2\pi/24$ ccw $\omega_r = 2\pi/24$ cc

 $\frac{5/176}{2}$ $\frac{1}{2}$ $\frac{1}{2}$







5/182 $y A_b(\theta=90^\circ)$; $A_a(\theta=0)$ For circular orbit $V=R\sqrt{9/r}$ $A_b V_A$ $A_b V_A$

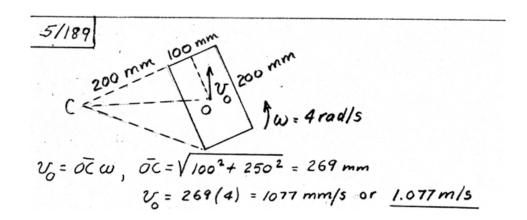
(b) 0=90°, [= (42171-30000)] = 12171] km 2[= = -11070] - (-13125] - 0.4375 k × 12171] = 7380 i km/h 5/183 x-y axes are attached to $V_{p} = 200(10) = 2000 \text{ mm/s}$ attached to $V_{p} = 2000(\frac{1}{2}) = 1000 \text{ mm/s}$ $V_{p} = 2000(\frac{1}{2}) = 1000 \text{ mm/s}$ $V_{p} = 2000(\frac{1}{2}) = 1000 \text{ mm/s}$ $V_{p} = 2000(\frac{1}{2}) = 1732 \frac{\text{mm}}{\text{s}}$ $V_{p} = 2000(\frac{1}{2}) = 0$ $V_{p} = 2000(\frac{1}{2}) = 1732 \frac{\text{mm}}{\text{s}}$ $V_{p} = 2000(\frac{1}{2}) = 0$ $V_{p} = 2000(\frac{1}{2}) = 2000(\frac{1}{2}) = 0$ $V_{p} = 2000(\frac{1}{2}) = 2000($

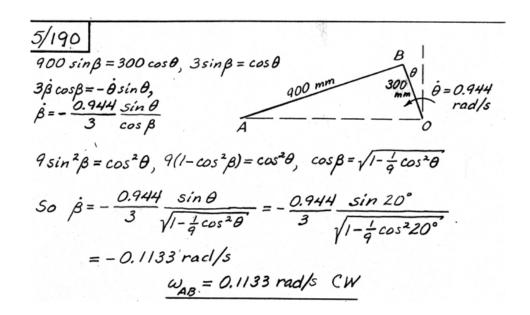
 $\begin{array}{c} \omega = \omega k = \partial k, \ \alpha = \omega k \\ \\ \omega = \omega k = \partial k, \ \alpha = \omega k \\ \\ \omega = \omega k = \partial k, \ \alpha = \omega k \\ \\ \omega = \omega k = \partial k, \ \alpha = \omega k \\ \\ \omega = \omega k = \partial k, \ \alpha = \omega k \\ \\ \omega = \omega k = \partial k, \ \alpha = \omega k \\ \\ \omega = \omega k = \partial k, \ \alpha = \omega k \\ \\ \omega = \omega k = \partial k, \ \alpha = \omega k \\ \\ \omega = \omega k \\ \\$

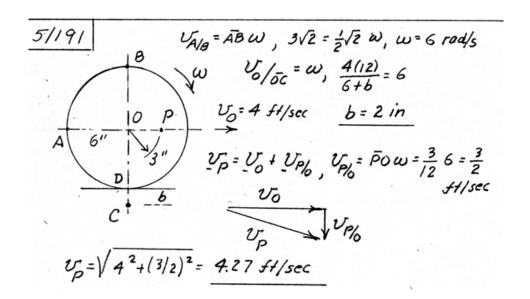
▶5/185 Let B = point on DO coincident UA = UB + VAIR UB = 6 2 = 1 +1/sec VAIB = Vrel = Va /tan 300 VA = 2 H/sec Vrej = V3 H/sec W = 2 rad/sec a = a + wxr + wx(wxr) + 2wxve + arel Q0=0, Wxr=6kx 6 i = 3j ft/sec2 wx(wxr) = 2k x(2k x 6 i) = -2i ft/sec2 2wx Vre1 = 4k x (-13i) = -413j ft/sec2 (are1) = Vrei(-j) = - 3/6/12 j = - 6j ft/sec2 QA = -8 cos 60° i - 8 sin 60° j ft/sec 2 an = an cos 30° i - an sin 30° j substitute & get QA, \frac{\sqrt{3}}{2}i - QA, \frac{1}{2}j - 4i - 8\frac{\sqrt{3}}{2}j = 3j - 2i - 4\sqrt{3}j - 6j + (Q_{rel}) \frac{1}{2}i Equate & s terms & get (and) = 3.20 ft/scc2 (QA) = 6 H/sec 2 so d = 6/6/12 = 12 rad/sec 2 CCW

► 5/186 For circular orbit; At equator $g = 9.8/4 \, m/s^2$ $V_A = RVg/(R+h) = 6378V \frac{9.814/1000}{6378 + 240} (3600) = 27960 \frac{km}{h}$ $240 \, km$ $Q_A = \frac{V_A^2}{R+h} = 9 \left(\frac{R}{R+h}\right)^2 = 9.814 \left(\frac{6378}{6378 + 240}\right)^2 = 9.115 \, m/s^2$ $V_B = Rw = 6378 (0.7292)(10^{-4})(3600) = 1674 \, km/h$ $R = 6378 \, km$ $V_A = V_B + w \times \Gamma + V_{rel}$ $w = 0.7292(10^{-4})(3600)(240)(-i)$ $v = 0.7292(10^{-4})(3600$

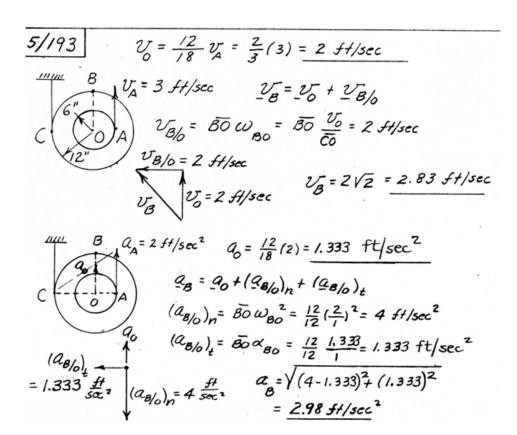
5/187 $\omega \times r = U$; $2k \times (\chi_i + y_j) = -0.8i - 0.6j$ $2\chi_j - 2yi = -0.8i - 0.6j$ $50 \ 2\chi = -0.6$, $\chi = -0.3 \ m$ -2y = -0.8, y = 0.4m $r = \sqrt{0.3^2 + 0.4^2} = 0.5m$ 5/188 $\omega = 3 \frac{1}{2} \frac{rad/s}{c}$ $\alpha = -6 \frac{1}{2} \frac{rad/s}{c}$ $\Gamma_p = \Gamma = -0.1 \frac{1}{2} + 0.15 \frac{1}{2} \frac{rad/s}{c}$ $U = \omega \times \Gamma = 3 \frac{1}{2} \times (-0.1 \frac{1}{2} + 0.15 \frac{1}{2}) = -0.45 \frac{1}{2} - 0.3 \frac{1}{2} \frac{rad/s}{c}$ $\Omega = \omega \times \Gamma = -6 \frac{1}{2} \times (-0.1 \frac{1}{2} + 0.15 \frac{1}{2}) = 0.9 \frac{1}{2} + 0.6 \frac{1}{2} \frac{rad/s}{c}$ $\Omega = \omega \times U = 3 \frac{1}{2} \times (-0.45 \frac{1}{2} - 0.3 \frac{1}{2}) = 0.9 \frac{1}{2} - 1.35 \frac{1}{2} \frac{rad/s}{c}$

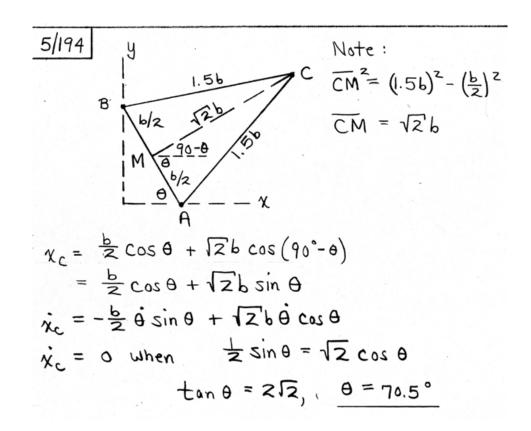


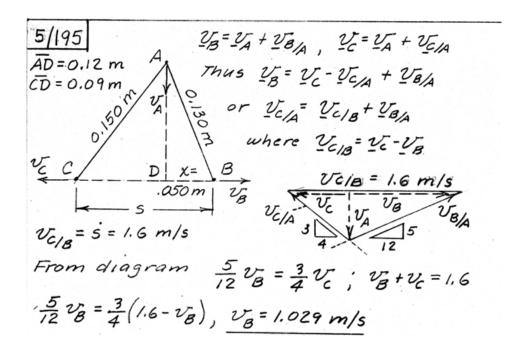


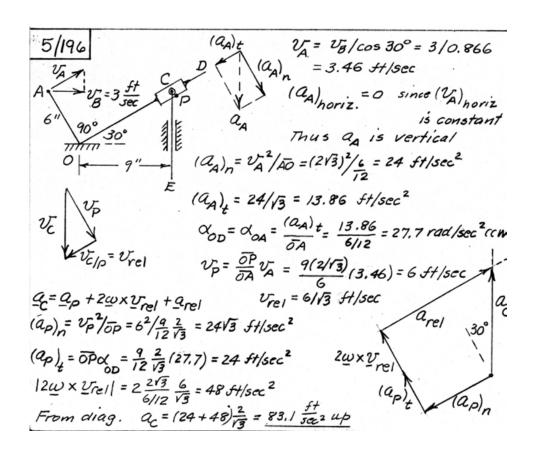


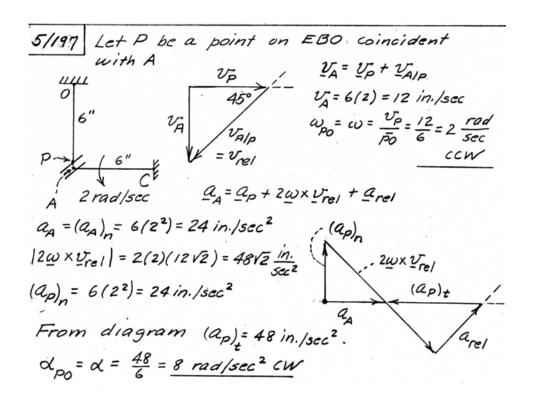
5/192 Displacement, velocity, 4 acceleration of truck are 20/40 = 0.5 of x, v_0 , a_0 $v_0 \ a_0$ Thus $a_0 = 2(a_{truck})$ $= 2(2) = 4 \text{ ff/sec}^2$ $v_0 = 2a_0x = 2(4)(6) = 48(\frac{ft}{sec})^2$ $a_p = a_0 + (a_{p/0})_n + (a_{p/0})_t$ -x = 6 $(a_{p/0})_n = Po(a) = Po(\frac{v_0}{Po})^2 = \frac{48}{40/12} = 14.4 \text{ ff/sec}^2$ $(a_{p/0})_t = Po(a) = a_0 = 4 \text{ ff/sec}^2$ $a_0 = a_0 = 4 \text{ ff/sec}^2$

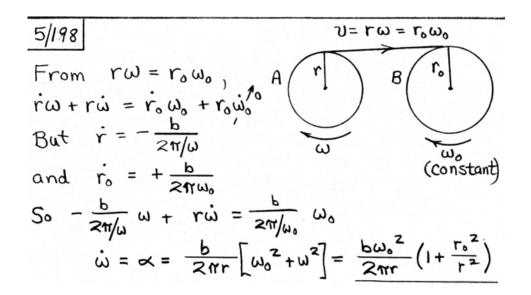


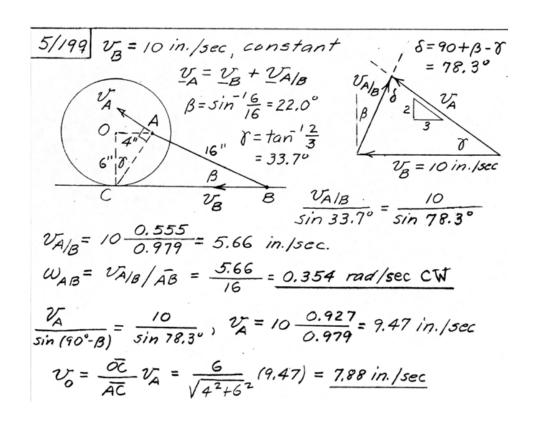


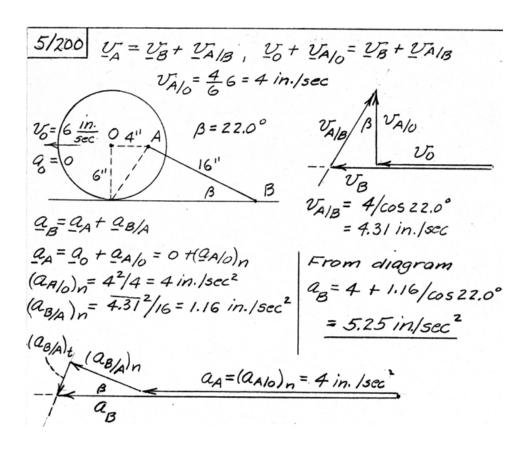


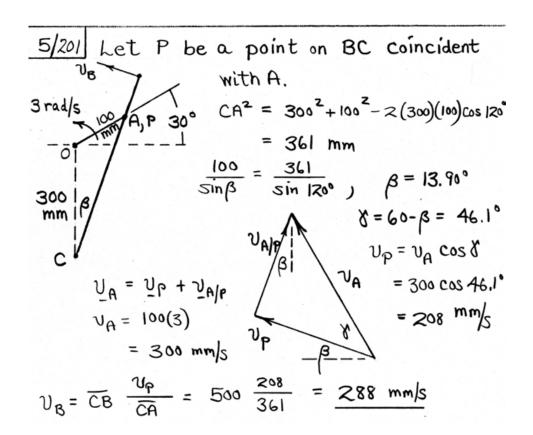


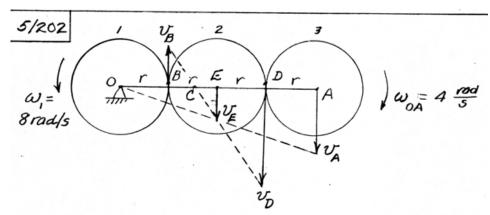








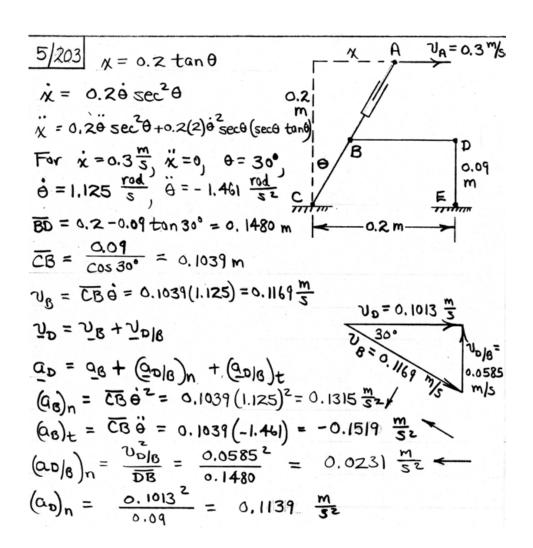


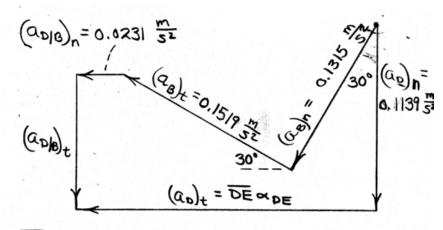


Let B be contact point common to gears 1 # 2

" D " " " " " gears 2 # 3

Point C is instantaneous center of zero velocity
for gear 2. By similar triangles, U = 3(8r) = 24r $U_B = rW_1 = 8r$ $V_A = \bar{O}AW_{OA} = 4r(4) = 16r$ $V_E = 2rW_{OA} = 8r$ $W_3 = \frac{V_{OA}}{\bar{O}A} = \frac{24r - 16r}{r} = 8 \text{ rad/s ccw}$





$$(a_0)_t = \overline{DE} \propto_{DE} = 0.1315 \sin 30^\circ + 0.1519 \cos 30^\circ + 0.0231$$

 $= 0.220 \text{ m/s}^2$
 $\propto_{DE} = \frac{0.220}{0.09} = 2.45 \text{ rod/s}^2 \text{ CCW}$

5/204 V_A E = 6378 km, h = 200 km V_A V_A

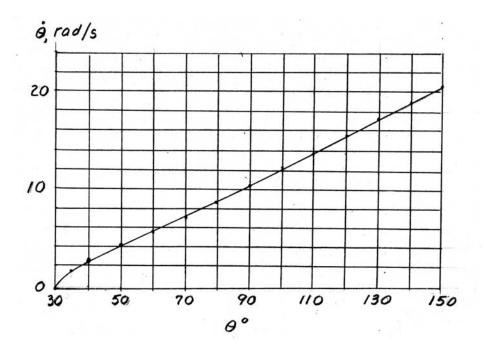
 $\frac{5/205}{a_{c} = a_{o} + (a_{c/o})_{n} + (a_{c/o})_{t}}$ $\underline{a_{c} = a_{o} + (a_{c/o})_{n} + (a_{c/o})_{t}}$ $\underline{a_{o} = r\alpha_{\underline{i}} + \frac{(r\omega)^{2}}{R-r}\underline{j}}$ $(\underline{a_{c/o}}_{n} = r\omega^{2}\underline{j}, (\underline{a_{c/o}}_{t})_{t} = -r\alpha_{\underline{i}}$ $\underline{a_{c}} = r\alpha_{\underline{i}} + \frac{(r\omega)^{2}}{R-r}\underline{j} + r\omega^{2}\underline{j} - r\alpha_{\underline{i}}, \underline{a_{c}} = \frac{r\omega^{2}}{1-r/R}\underline{i}$ $\underline{a_{c}} = r\alpha_{\underline{i}} + (\underline{a_{A/o}}_{n})_{n} + (\underline{a_{A/o}}_{t})_{t}$ $(\underline{a_{A/o}}_{n})_{n} = -r\omega^{2}\underline{j}, (\underline{a_{A/o}}_{t})_{t} = r\alpha_{\underline{i}}$ $\underline{a_{A}} = r\alpha_{\underline{i}} + \frac{(r\omega)^{2}}{R-r}\underline{j} - r\omega^{2}\underline{j} + r\alpha_{\underline{i}}, \underline{a_{A}} = 2r\alpha_{\underline{i}} + r\omega^{2}\frac{2r/R-1}{1-r/R}\underline{j}$

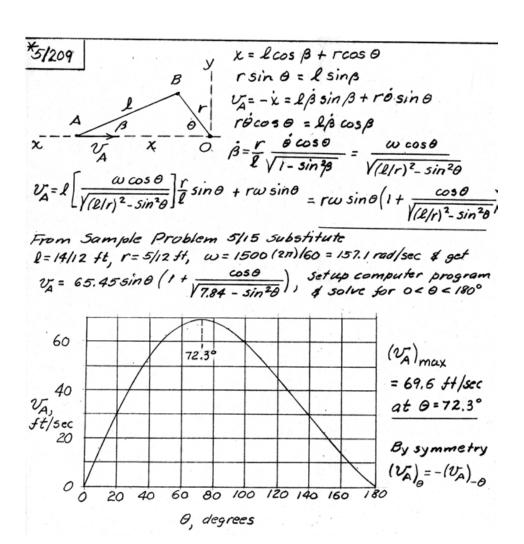
*5/206 $\dot{\theta} = 120 \frac{2\pi}{60} = 4\pi \text{ rad/sec}$ $5 \sin \theta = (25 - 5 \cos \theta) \tan \beta \quad ---(1)$ $5 \dot{\theta} \cos \theta = 5 \dot{\theta} \sin \theta \tan \beta + (25 - 5 \cos \theta) \dot{\beta} \sec^2 \beta$ $= 5 \dot{\theta} \sin \theta \tan \beta + (25 - 5 \cos \theta) \dot{\beta} (1 + \tan^2 \beta)$ $\dot{\beta} = \frac{(4\pi)(\cos \theta - \sin \theta \tan \beta)}{(5 - \cos \theta)(1 + \tan^2 \beta)}$ Substitute Eq. (1) Aget $\dot{\beta} = 4\pi \frac{5\cos\theta - 1}{26 - 10\cos\theta} = 2\pi \frac{5\cos\theta - 1}{13 - 5\cos\theta}$ Calculate & plot & vs 0: 3 Angular velocity of OB, rad/s -2 -3 Ó 100 300

Angle theta, degrees

 $3\sqrt{207}$ From Prob. 5/56 we have $\omega_2 = \frac{\partial}{\partial \cos(\theta + \beta)} \frac{\cos(\theta + \beta)}{\cos(\theta + \beta), -\sqrt{2}\cos\beta}$ where $\beta = 2\sqrt{0}2P$ Also $\tan \beta = \frac{\sin \theta}{\sqrt{2} - \cos \theta}$ For $\theta = -2 \operatorname{rad/s}$, $\omega_2 = 2\frac{\cos(\theta + \beta)}{\sqrt{2}\cos\beta - \cos(\theta + \beta)}$ Set up program to compute $\beta \notin \omega_2 \notin \text{plot}$ results.

*5/208 $\ddot{\theta} = 100(1-\cos\theta) \ rad/s^2$ $\dot{\theta} \ d\dot{\theta} = \ddot{\theta} \ d\theta \ so \ \int \dot{\theta} \ d\dot{\theta} = 100\int (1-\cos\theta) \ d\theta$ $\dot{\theta}^2 = 200 \left(\theta - \sin\theta\right) \Big|_{\pi/6}^{\theta} = 200 \left(\theta - \sin\theta - 0.0236\right)$ $\dot{\theta} = \frac{d\theta}{dt} = 10\sqrt{2}\sqrt{\theta - \sin\theta - 0.0236} \ rad/s$ $\int_{0}^{t} \frac{dt}{dt} = \int_{0\sqrt{2}}^{\pi/6} \frac{d\theta}{10\sqrt{2}\sqrt{\theta - \sin\theta - 0.0236}} \frac{\text{Numerical integration}}{\text{gives } t = 0.0701 \text{ s}}$





$$\frac{1}{4} \frac{5}{2} \frac{10}{10} = \text{From the results of 1970b.} \frac{5}{709} \text{ we may write}$$

$$\frac{1}{4} \frac{1}{2} \frac{1}{4} \frac{1}{4} \left\{ rw \sin \theta + rw \frac{\sin \theta \cos \theta}{\sqrt{(U/r)^2 - \sin^2 \theta}} \right\} = rw \left\{ \frac{1}{2} \sin 2\theta + \frac{\sin \theta \cos \theta}{\sqrt{(U/r)^2 - \sin^2 \theta}} \right\}$$

$$= rw \left\{ \frac{1}{2} \cos \theta + \frac{1}{2} \frac{1}{2} \sin^2 \theta + \frac{1}{2} \sin^2 \theta + \frac{1}{2} \sin^2 \theta}{\sqrt{(U/r)^2 - \sin^2 \theta}} \right\}$$

$$= rw^2 \left[\cos \theta + \frac{r}{\ell} \frac{1 - 2 \sin^2 \theta + \frac{r^2}{\ell^2} \sin^4 \theta}{(1 - \frac{r^2}{\ell^2} \sin^2 \theta)^{\frac{3}{2}}} \right]$$

$$= rw^2 \left[\cos \theta + \frac{r}{\ell} \frac{1 - 2 \sin^2 \theta + \frac{r^2}{\ell^2} \sin^4 \theta}{(1 - \frac{r^2}{\ell^2} \sin^2 \theta)^{\frac{3}{2}}} \right]$$

$$= rw^2 \left[\cos \theta + \frac{r}{\ell} \frac{1 - 2 \sin^2 \theta + \frac{r^2}{\ell^2} \sin^4 \theta}{(1 - \frac{r^2}{\ell^2} \sin^2 \theta + \frac{r^2}{\ell^2} \sin^4 \theta)} \right]$$

$$= rw^2 \left[\cos \theta + \frac{r}{\ell} \frac{1 - 2 \sin^2 \theta + \frac{r^2}{\ell^2} \sin^4 \theta}{(1 - \frac{r^2}{\ell^2} \sin^2 \theta + \frac{r^2}{\ell^2} \sin^4 \theta)} \right]$$

$$= rw^2 \left[\cos \theta + \frac{r}{\ell} \frac{1 - 2 \sin^2 \theta + \frac{r^2}{\ell^2} \sin^4 \theta}{(1 - \frac{r^2}{\ell^2} \sin^4 \theta + \frac{r^2}{\ell^2} \sin^4 \theta)} \right]$$

$$= rw^2 \left[\cos \theta + \frac{r}{\ell} \frac{1 - 2 \sin^2 \theta + \frac{r^2}{\ell^2} \sin^4 \theta}{(1 - \frac{r^2}{\ell^2} \sin^4 \theta + \frac{r^2}{\ell^2} \sin^4 \theta} \right]$$

$$= rw^2 \left[\cos \theta + \frac{r}{\ell} \frac{1 - 2 \sin^2 \theta + \frac{r^2}{\ell^2} \sin^4 \theta}{(1 - \frac{r^2}{\ell^2} \sin^4 \theta + \frac{r^2}{\ell^2} \sin^4 \theta} \right]$$

$$= rw^2 \left[\cos \theta + \frac{r}{\ell} \frac{1 - 2 \sin^2 \theta + \frac{r^2}{\ell^2} \sin^4 \theta}{(1 - \frac{r^2}{\ell^2} \sin^2 \theta)^{\frac{3}{2}}} \right]$$

$$= rw^2 \left[\cos \theta + \frac{r}{\ell} \frac{1 - 2 \sin^2 \theta + \frac{r^2}{\ell^2} \sin^4 \theta}{(1 - \frac{r^2}{\ell^2} \sin^4 \theta + \frac{r}{\ell^2} \sin^4 \theta} \right]$$

$$= rw^2 \left[\cos \theta + \frac{r}{\ell} \frac{1 - 2 \sin^2 \theta + \frac{r}{\ell^2} \sin^4 \theta}{(1 - \frac{r^2}{\ell^2} \sin^4 \theta + \frac{r}{\ell^2} \sin^4 \theta} \right]$$

$$= rw^2 \left[\cos \theta + \frac{r}{\ell} \frac{1 - 2 \sin^2 \theta + \frac{r}{\ell^2} \sin^4 \theta}{(1 - \frac{r}{\ell^2} \sin^4 \theta + \frac{r}{\ell^2} \sin^4 \theta} \right]$$

$$= rw^2 \left[\cos \theta + \frac{r}{\ell} \frac{1 - 2 \sin^2 \theta + \frac{r}{\ell^2} \sin^4 \theta}{(1 - \frac{r}{\ell^2} \sin^4 \theta + \frac{r}{\ell^2} \sin^4 \theta} \right]$$

$$= rw^2 \left[\cos \theta + \frac{r}{\ell} \frac{1 - 2 \sin^2 \theta + \frac{r}{\ell^2} \sin^4 \theta}{(1 - \frac{r}{\ell^2} \sin^4 \theta + \frac{r}{\ell^2} \sin^4 \theta} \right]$$

$$= rw^2 \left[\cos \theta + \frac{r}{\ell} \frac{1 - 2 \sin^2 \theta + \frac{r}{\ell^2} \sin^4 \theta}{(1 - \frac{r}{\ell^2} \sin^4 \theta + \frac{r}{\ell^2} \sin^4 \theta} \right]$$

$$= rw^2 \left[\cos \theta + \frac{r}{\ell} \frac{1 - 2 \sin^4 \theta + \frac{r}{\ell^2} \sin^4 \theta + \frac$$

O, degrecs

*5/211 240 mm Velocity of AB through collar C is 1. 12 = 2402 + 802 - 2 (240) (80) cost, 1 = 80/2/5-3000 211 = 2(240)(80) + sin + $\sqrt{2}\sqrt{5-3\cos\theta}$ mm/s, $\ell_{\text{max}} = 240 \frac{\text{mm}}{\text{s}} = 0.5$ 250 mm/s 180 O, deg

