$$\frac{4/1}{\Gamma} = \frac{\sum mi \zeta i}{\sum m_i} = \frac{m(di) + 2m(2di) + 4m(1.5dk)}{m + 2m + 4m}$$

$$= \frac{d}{T} \left(\frac{i}{i} + 4j + 6k \right)$$

$$\frac{d}{T} = \frac{\sum mi r_i}{\sum m_i} = \frac{m(2Vj) + 2m(3Vk) + 4m(Vi)}{7m}$$

$$= \frac{V}{T} \left(4i + 2j + 6k \right)$$

$$\frac{d}{T} = \frac{\sum m_i}{\sum m_i} = \frac{Fk}{7m}$$

$$T = \sum \frac{1}{2} m_i V_i^T = \frac{1}{2} \left[m(2V)^2 + 2m(3V)^2 + 4m(V)^2 \right]$$

$$= \frac{13mV^2}{mVd}$$

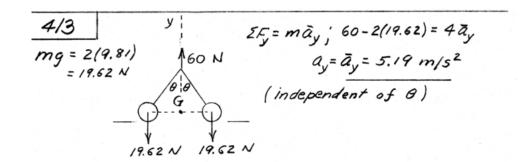
$$H_0 = \sum r_i \times m_i V_i = 2mVdk + 12mVdi + 6mVdj$$

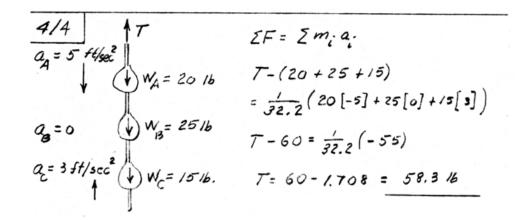
$$= mVd \left(12i + 6j + 2k \right)$$

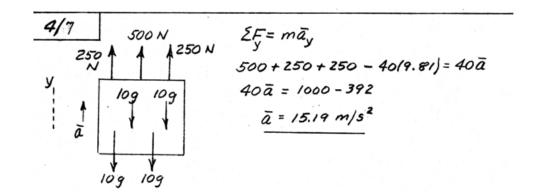
$$H_0 = \sum M_0 = -Fdj$$

From Eq. 4/10 with P replaced by

0: $H_0 = H_0 + \overline{Y} \times \sum m_i \overline{y}$ or $H_0 = H_0 - \overline{Y} \times \sum m_i \overline{y}$ $H_0 = H_0 - \overline{Y} \times \sum m_i \overline{y}$ $H_0 = M_0 - \overline{Y} \times \sum m_i \overline{y}$ $H_0 = M_0 + M_0 +$



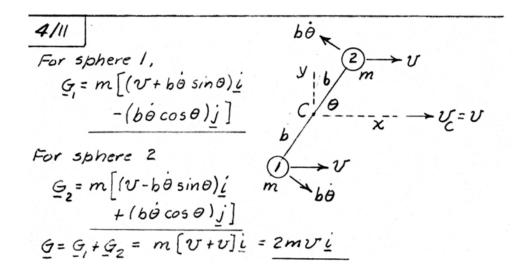


4/5 $\Sigma F = m\bar{a}$: 6.4 = (0.8 + 0.5 + 0.3) \bar{a} $\bar{a} = 4 \, m/s^2$ 

The principle of the motion of the mass center gives $F=m\bar{a}$ for each case, so the mass-center accelerations are identical. In the two cases of hinged members, however, the mass center is not a point attached to a member, and for these two cases the accelerations of the members will differ.

 $\frac{4/9}{\Delta t} = \frac{\Delta G}{\Delta t} = \left[(3.7-3.4) \underline{i} + (-2.2+2.6) \underline{j} + (4.9-4.6) \underline{k} \right] / 0.2$ $= 1.5 \underline{i} + 2.0 \underline{j} + 1.5 \underline{k} \quad N$ $F = |F_{av}| = \sqrt{1.5^2 + 2.0^2 + 1.5^2} = 2.92 \quad N$

4/10 For system, $\Delta T + \Delta V_g = 0$ $\Delta T = 3(\frac{1}{2}mv^2) - 0 = \frac{3}{2}mv^2$ $\Delta V_g = 0 - mg\frac{b}{\sqrt{2}} - mg\frac{2b}{\sqrt{2}} = -\frac{3b}{\sqrt{2}}mg$ Thus $\frac{3}{2}mv^2 - \frac{3b}{\sqrt{2}}mg = 0$, $v^2 = bg\sqrt{2}$ $v = \sqrt{bg\sqrt{2}}$



4/12

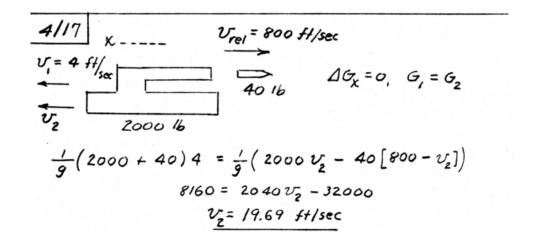
 $H_0 = H_G + \bar{\Gamma} \times G , G = 3(3\underline{i} + 4\underline{i}) \text{ kg·m/s}$ $= 1.20\underline{k} + (0.4\underline{i} + 0.3\underline{i}) \times 3(3\underline{i} + 4\underline{i})$ $= 1.20\underline{k} + 3(1.6\underline{k} - 0.9\underline{k})$ $= 1.20\underline{k} + 3(0.7\underline{k}) = 3.3\underline{k} \text{ kg·m}^2/\text{s}$

4/13 Mass center is center of middle bar, so Eq. 4/1 for the entire system gives $\Sigma F = m\bar{a}: 10 = 3 \frac{8}{32.2} a, \quad \underline{a} = 13.42 \text{ ft/sec}^2$

4/14

 $EM_0 = H_0$ where 0-0 is the axis of rotation $M = \frac{dH_0}{dt}, \quad \int_0^t M dt = \int_0^{H_0} H_0 = H_0$ $Mt = 4m (rw)r, \quad t = \frac{4mr^2w}{M}$

5/15 $\sum M_0 = H_0 = \frac{dH_0}{dt}$, $\sum M_0 dt = \Delta H_0$ $M_0 t = \Delta \left| \sum m_i r_i (\underline{r_i \dot{\theta}}) \right| = \sum m_i r^2 \Delta \dot{\theta}$ $30 \times 5 = \left[3(0.5)^2 + 4(0.4)^2 + 3(0.6)^2 \right] (\dot{\theta}' - 20)$ $150 = 2.47 (\dot{\theta}' - 20)$, $\dot{\theta}' = 60.7 + 20 = 80.7 \frac{r_0 d}{5}$ $\frac{4/16}{\int_{0}^{t} M_{z} dt} = H_{z_{2}} - H_{z_{1}}, H_{z} = \sum_{i=1}^{t} m_{i} r_{i} (r_{i} \dot{\theta})$ $H_{z} = 2(3)(0.3)^{2} \dot{\theta} + 2(3)(0.5)^{2} \dot{\theta} = 2.04 \dot{\theta}$ $50 \quad 30 t = 2.04 (20 - [-20]) = 81.6$ t = 2.72 s



4/18 For entire system $\Delta G_{\chi} = 0$, x horiz. (300 + 400 + 100) V $- (300 \times 0.6 - 400 \times 0.3 + 100 \times 1.2 \cos 30^{\circ}) = 0$ 800 V = 163.9, V = 0.205 m/s

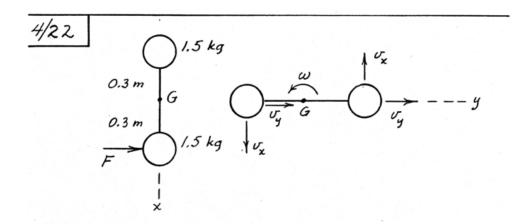
Momentum is conserved regardless of sequence of events, so final velocity would be the same.

4/19 2 milhr 1 milhr 1.5 milhr $W_A = W_B = W_C = 130,000 16 100,000 16 150,000 16$ $\Sigma F_{\chi} = 0$ for system so $\Delta G_{\chi} = 0$ $(130 \times 2 + 100 \times 1 - 150 \times 1.5) \frac{44}{30} \frac{10^3}{32.2}$ $-(130 + 100 + 150) V \frac{44}{30} \frac{10^3}{32.2} = 0$ $V = \frac{260 + 100 - 225}{130 + 100 + 150} = 0.355 \text{ milhr}$ $0/0 | loss of energy = \frac{T_1 - T_{\chi}}{T_1} | loo = 100 \left(1 - \frac{T_{\chi}}{T_1}\right) = n$ $n = 100 \left\{1 - \frac{19}{29} \left(130 + 100 + 150\right) \left(0.355\right)^2 + 100 \left(1 - \frac{47.96}{957.5}\right) \right\}$ n = 95.0 %

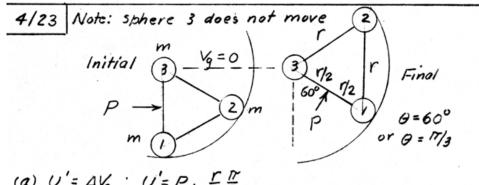
4/21 With neglect of hydroulic forces linear momentum is conserved & velocity $V_2 = V_1 = 1$ knot. Center of mass does not change position with respect to reference axes moving with constant speed of 1 knot.

Thus $(\Sigma m_i X_i)_1 = (\Sigma m_i X_i)_2$ $\frac{1}{32.2} \left[120(12) + 180(8) + 160(16) + 300(5) \right]$ $= \frac{1}{32.2} \left[120(14+x) + 180(4+x) + 160(10+x) + 300(5+x) \right]$ 4240 = 4000 + 760x, $x = \frac{240}{760} = 0.316$ ft

Timing & sequence of changed positions does not affect final result because all forces are internal.



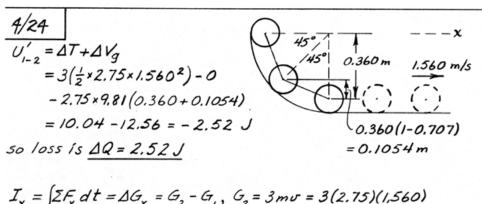
$$\begin{split} \int & \sum F_{x} \, dt = 0 \quad so \quad \Delta G_{x} = 0 \\ & \int & \sum F_{y} \, dt = \Delta G_{y} : \quad IO = 2(1.5) v_{y} \,, \quad v_{y} = 3.33 \, \text{m/s} \\ & \int & \sum M_{G} \, dt = \Delta H_{G} : \quad IO(0.3) = 2(1.5) v_{x}(0.3), \quad v_{x} = 3.33 \, \text{m/s} \\ & v = 3.33 \sqrt{2} = 4.71 \, \text{m/s} \, \text{ both spheres} \end{split}$$



(a)
$$U' = \Delta V_g : U' = P_{min} \frac{r}{2} \frac{R}{3}$$

 $\Delta V_g = mg (r + \frac{r}{2}) = \frac{3}{2} mgr$
Thus $\frac{\pi r}{6} P_{min} = \frac{3}{2} mgr$, $P_{min} = \frac{9}{17} mg$

(b)
$$U'=\Delta \Gamma + \Delta V_g$$
 with $P=2P_{min}=\frac{18}{\pi}mg$ $U'=\frac{18}{\pi}mg\frac{\Gamma}{2}\frac{\Pi}{3}=3mg\Gamma$, $\Delta V_g=\frac{3}{2}mg\Gamma$ $\Delta \Gamma=2(\frac{1}{2}mU^2)=mU^2$ Thus $3mgr=mV^2+\frac{3}{2}mgr$, $V=\sqrt{3gr/2}$

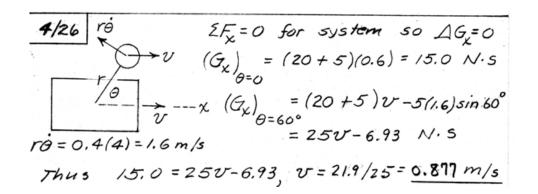


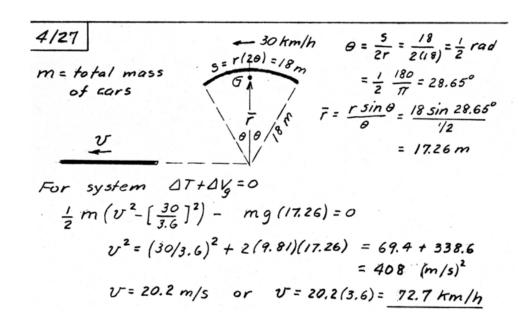
$$I_{x} = \int \Sigma F_{x} dt = \Delta G_{x} = G_{2} - G_{1}, G_{2} = 3m\sigma = 3(2.75)(1.560)$$

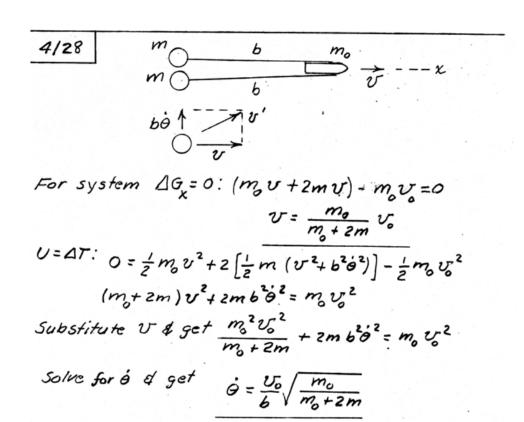
$$= 12.87 \text{ N·s}, G_{1} = 0$$

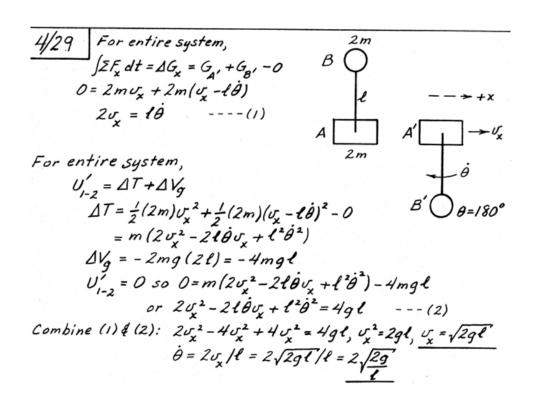
$$I_{x} = 12.87 \text{ N·s}$$

4/25 (a) $\Sigma F_x = m\bar{a}_x$; $F = 2m\bar{a}$, $\bar{a} = F/2m$ (b) $H_g = 2m(\frac{L}{2})^2\dot{\theta}$, $H_g = mL^2\ddot{\theta}/2$ $\Sigma M_g = H_g$; $Fb = mL^2\ddot{\theta}/2$, $\ddot{\theta} = \frac{2Fb}{mL^2}$



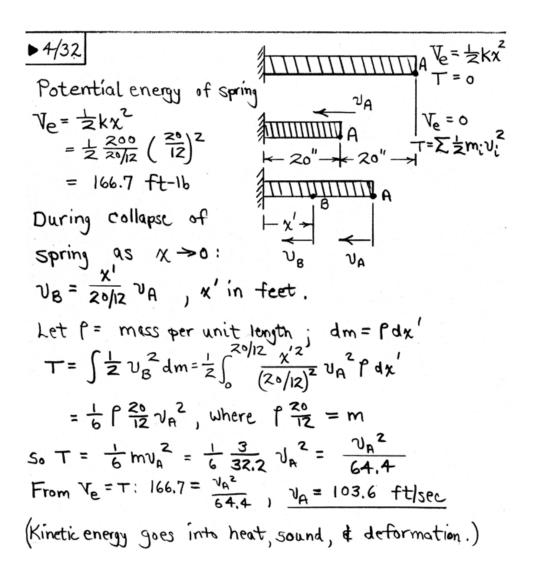




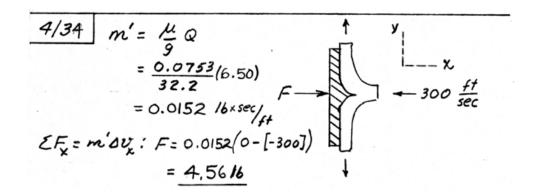


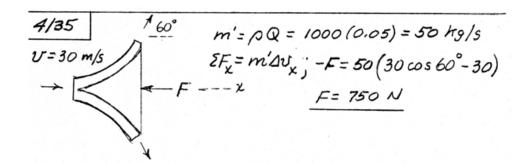
Flotcar; $\Delta T = \frac{1}{2}mv^2 - 0$ $= \frac{1}{2}\frac{50,000}{32.2}v^2$ $\Delta V_g = 0$ Vehicle; $\Delta T = \frac{1}{2}mv^2 - 0 = \frac{1}{2}\frac{15000}{32.2}\left[(\dot{s}\cos 5^\circ - v)^2 + (\dot{s}\sin 5^\circ)^2\right]$ $\Delta V_g = -W\Delta h = -15,000 (40 \sin 5^\circ)$ Thus $776.4 v^2 + 232.9\left[(\dot{s}\cos 5^\circ - v)^2 + (\dot{s}\sin 5^\circ)^2\right]$ -52290 = 0Also for system, $E_X = 0$ so $\Delta G_X = 0$ $\frac{15,000}{32.2}(\dot{s}\cos 5^\circ - v) - \frac{50,000}{32.2}v = 0$ $\dot{s}\cos 5^\circ - v = 3.33v$ & $\dot{s}\sin 5^\circ = 4.33v$ tan 5° Substitute into (1) & get $776.4 v^2 + 232.9\left[(3.33v)^2 + (0.379v)^2\right] - 52290 = 0$ $v^2(776.4 + 2588 + 33.5) = 52290$ $v^2 = 15.39(ft/sec)^2$ v = 3.92ft/sec

Initial energy $V_{g} = \rho g \frac{\pi r}{2} r = \rho g \frac{\pi r^{2}}{2} \frac{2r}{\pi}$ $V_{g} = \rho g \frac{\pi r}{2} r = \rho g r^{2}$ Final energy $V_{g} = \rho g \frac{\pi r}{2} \frac{2r}{\pi} = \rho g r^{2}$ Energy loss $\Delta Q = V_{g_{1}} - V_{g_{2}} = \rho g r^{2} (\frac{\pi}{2} - 1) = 0.571 \rho g r^{2}$ With $\Delta T = 0$ ($T_{z} = T_{z} = 0$) the loss of potential is dissipated into heat energy due to impact of rope against the drum.

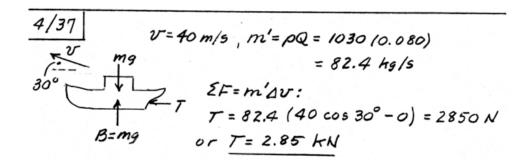


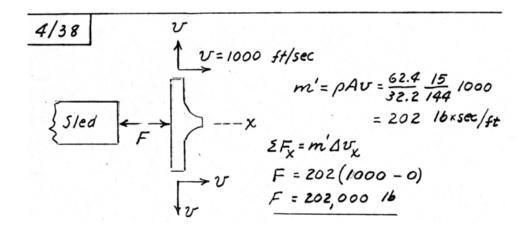
4/33 mg = 4.6(9.81) KN $R = 32 KN - \chi$ $T = m_a'(u-v) + m_f'u$ V = 1000 Km/h V = 106(680 - 1000/3.6) V = 45400 N $EF_\chi = ma_\chi = 0$; $45.4 - 32 - 4.6(9.81) sin \alpha = 0$ $Sin \alpha = 0.2960$, $\alpha = 17.22^\circ$

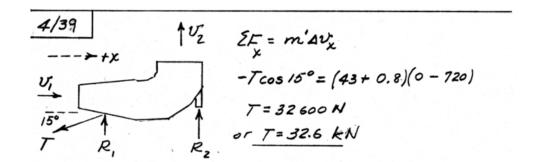


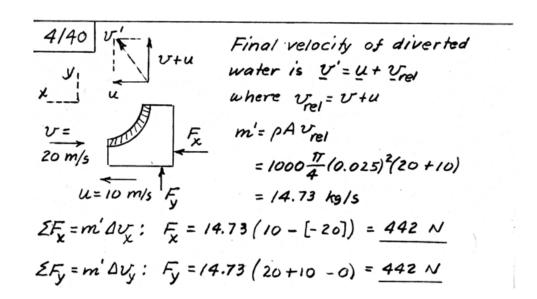


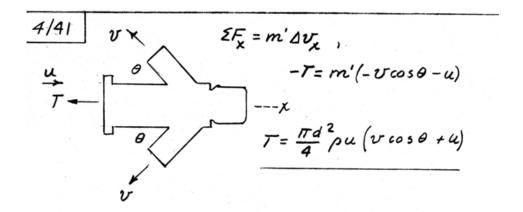
4/36 Resistance R equals not thrust T where T=m'(u-v)Nozzle relocity $u=Q/A=\frac{0.082}{17(0.050)^2}=41.8 \text{ m/s}$ Density of salt water, Table D-1, $p=1030 \text{ kg/m}^3$ m'=pQ=1030(0.082)=84.5 kg/s $v=70\frac{1000}{3600}=19.44 \text{ m/s}$ R=T=84.5(41.8-19.44)=1885 N











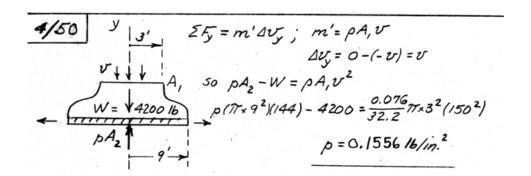
Ball & stream just under it: $\Sigma F_{y} = m' \Delta v_{y}:$ m' at ball = m' at nozzle $= \rho A v = \frac{62.4}{32.2} \frac{\pi (0.5)^{2} (1)^{2}}{4} \cdot 35$ = 0.925 lb-sec/ft $50 \text{ 0.5} = 0.925 (0 - [-v_{2}])$ $v_{2} = 5.41 \text{ ft/sec}$ For water stream $\Delta V_{g} + \Delta T = 0:$ $mgh + \frac{1}{2}m'(v_{2}^{2} - v_{1}^{2}) = 0,$ $h = \frac{1}{2 \times 32.2} (35^{2} - 5.41^{2}) = 18.57 \text{ ft}$ 4/43 $\Sigma F = \Sigma m'u$ With reversers in place, $T_R = m'_g u \sin 30^\circ + m'_a u$ $T_R = (50 + 0.65)(650) \sin 30^\circ$ + 50 (55.6 - 0) = 16460 + 2780 = 19240 NWithout reversers $T = m'_g u - m'_a u$ T = (50 + 0.65)650 - 50(55.6) = 32900 - 2780 = 30100 NSo $n = \frac{19240}{30100} = 0.638$

4/46
$$A_c = \frac{\pi 4^2}{4(144)} = 0.0873 \text{ ft}^2$$
, $A_g = 4A_c = 0.349 \text{ ft}^2$
 $T/2 B$
 C
 $m' = \rho A U$
 $m' = \frac{0.840}{32.2} (0.349) 50 = 0.455 \frac{16 - sec}{ft}$
 $m' = \frac{0.0760}{32.2} (0.0873) U_c = 2.06 (10^{-4}) U_c$
 $T/2$
 $P_c = 2 \frac{16}{in^2}$
 $m_g = m' so U_c = \frac{0.455}{2.06 (10^{-4})}$
 $W_g = 50 \text{ ft/sa}$
 $= 2210 \text{ ft/sec}$
 $EF_x = m' \Delta V_x$: $150(0.349) 144 - 2(0.0873) (144) - T$
 $= 0.455(2210 - 50)$
 $T = 6530 16$

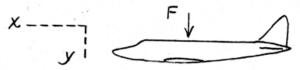
4/47 Q = AV: $\frac{1}{2}(231) = \frac{0.01^2 \pi V_1}{4}$ $V_1 = 1.471 (10^6) \text{ in./min}$ $V_2 = 1.471 (10^6) \text{ in./min}$ $V_3 = 1.471 (10^6) \text{ in./min}$ $V_4 = 1.471 (10^6) \text{ in./min}$ $V_5 = 1.471 (10^6) \text{ in./min}$ $V_7 = 1.471 (10^6) \text{ in./min}$ $V_8 = 1.471 (10^6) \text{ in./min}$ $V_9 = 1.471 (10^6)$

4/48 $EF_{\chi} = m' \Delta V_{\chi}:$ $R - m_{g} - m_{w}g = \beta Q (V \cos 45^{\circ} - V_{o})$ $M_{g} = 310 \text{ kg}$ $Mass of water m_{w} = \beta V$ $= 1000 \frac{\pi}{4} (0.2)^{2} (6)$ = 188.5 kg $Q = 0.125 \text{ m}^{3}/\text{s}$ $A = \frac{\pi}{4} (0.1)^{2} = 0.00785 \text{ m}^{2}$ $A_{o} = \frac{\pi}{4} (0.25)^{2} = 0.0491 \text{ m}^{2}$ V = Q/A = 0.125/0.00785 = 15.92 m/s V = Q/A = 0.125/0.0491 = 2.55 m/s $Thus R - (310 + 188.5) 9.81 = 1000 (0.125)(15.92 \cos 45^{\circ} - 2.55)$ = 1088 N R = 5980 N

4/49 $kx = m'\Delta v$, $m' = \rho \Delta v = 1000 \frac{\pi}{4}(0.030)^2 v$ = 0.7069 v15000 (0.150) = 0.7069 v(v-0) $v^2 = 3183$, v = 56.4 m/s $2M_A = m'vd$; $M = 15(150)(15 \sin 75^\circ - 4.8 \cos 75^\circ)$ = 2250 (13.25) = 29800 N·mor $M = 29.8 \ kN·m$



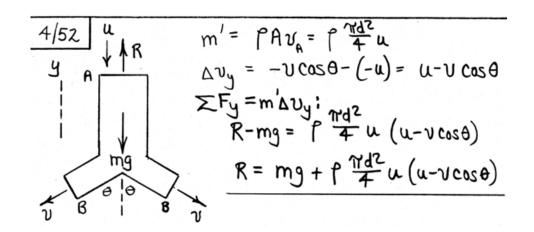
4/51 Consider motion as measured from the inertial reference of the aircraft.



F= m'Av, where $\Delta v_j = 0 - 20 = -20$ ft/sec Volume of water striking horizontal surface per second is $Q = Av_j = (2960 \text{ ft}^2)(\frac{1}{12} \frac{\text{ft}}{\text{hr}})(\frac{1}{3600} \frac{1}{\text{sec/hr}})$ = 0.0685 ft³/sec

 $m' = \rho Q = \frac{62.4}{32.2} (0.0685) = 0.1328 /b-sec/ft$ (s/ugs/sec)

 $F=m'|\Delta v_{y}|$ F=0.1328(20) = 2.66 16



4/53
$$Q = 1.6 \text{ ft}^3/\text{sec}$$
 $U_1 = \frac{Q}{A_1} = \frac{1.6}{20/144} = 11.52 \text{ ft/sec}$

$$U_2 = \frac{Q}{A_2} = \frac{1.6/2}{3.2/144} = 36 \text{ ft/sec}$$

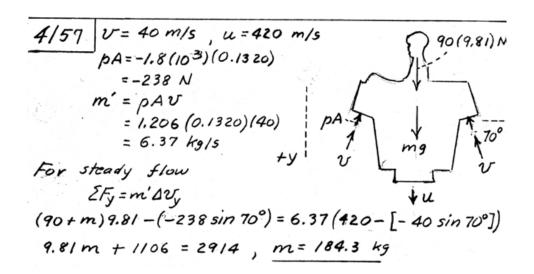
$$m' = \rho Q = \frac{64.4}{32.2} 1.6 = 3.2 \text{ 16-sec/ft}$$

$$U_2 = \frac{1.6}{20.2} = \frac{1.6}{3.2} =$$

4/55 For the truck and plow as a system: $\Sigma F_X = m \Delta V_X$: $P = \frac{60000}{60} \left[\frac{20}{3.6} - 0 \right] = 5560 \text{ N}$ or P = 5.56 kN $\Sigma F_Y = m \Delta V_Y$: $R = \frac{60000}{60} \left[12\cos 45^\circ - 0 \right] = 8490 \text{ N}$ or R = 8.49 kN 4/56 $M = M_0 = m'(v_2d_2 - 0)$ $v_2 = \frac{Q}{A} = \frac{16}{\pi(0.150)^2/4} \frac{1}{60} = 15.09 \frac{m}{3}$ From Table D-1, air

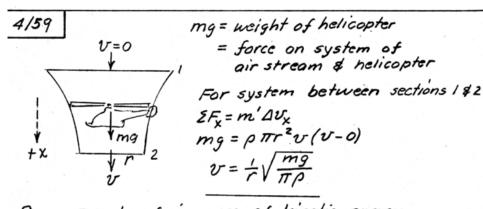
density is 1.206 kg/m³

50 $m' = \rho Q = 1.206 (16)/60 = 0.322 \text{ kg/s}$ $M_0 = 0.322(15.09 \times 0.2 - 0) = 0.97/ \text{ N·m}$ $P = 0.32 + M_0 \omega/1000 = 0.32 + 0.971 \frac{(3450 \times 2\pi/60)}{1000}$ P = 0.32 + 0.351 = 0.67/ kW



4/58

$$tx - - - \frac{106}{a}$$
 $tx - - - \frac{106}{a}$
 $tx - - \frac{106}{32.2}$
 $tx - \frac{106}{4/5 \text{sec}}$
 $tx $tx - \frac{106}{4/5 \text{sec}}$



Power = rate of increase of kinetic energy $P = \frac{1}{2}m'(v_2^2 - v_i^2) = \frac{1}{2}m'v^2 = m'v\frac{v}{2} = mg\frac{v}{2}$ $P = \frac{mg}{2r}\sqrt{\frac{mg}{\pi\rho}}$

Simulated FBD $m'_a v'_o$ $m'_a v'_o$ m'

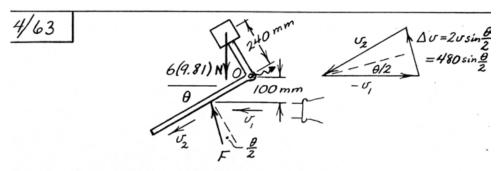
4/61
$$m'_{air} = \frac{18(2000)}{32.2} \frac{1}{3600} = 0.3/06 \text{ s/ugs/sec}$$
 R_y $m'_{wh} = \frac{150(2000)}{32.2} \frac{1}{3600} = 2.588 \text{ s/ugs/sec}$
 R_x C $V_z^{=}$ $R_z = 0.3/06 + 2.588 (124 \sin 60^{\circ} - 0)$
 $R_y = (0.3/06 + 2.588)(-124 \cos 60^{\circ} - 124)$
 $V_z^{=} = 124 \text{ f/sec}$ $V_z^{=} = -539 \text{ f/s}$
 $V_z^{=} = -539 \text{ f/s}$

Forces acting on pipe bend 4 mass within it

1) tension $PA = 4.42 \frac{TT(14)}{4} = 680 \text{ f/s}$ due to vocuum

- 1) weight of bend
- 5) balance of external support forces from crane
- 6) shear force and bending moment at C

4/62 For entire system $\sum M = m'(v_1d_2 - v_1d_1)$ Let u = Velocity of water relativeto nozzle = $\sqrt[4]{4A}$ w = pQ $-M = pQ(r^2w + b^2w - \frac{Q}{4A}r - 0)$ $w = pQ(\frac{Qr}{4A} - [r^2 + b^2]w)$ $w = pQ(\frac{Qr}{4A} - [r^2 + b^2]w)$ Components of absolute velocity of water at exit



 $F = m'\Delta v$: $m' = pAv = 1.206 \frac{\pi \times 0.040^2}{4} 240 = 0.364 \text{ kg/s}$

 $F = 0.364 \times 480 \sin \frac{\theta}{2} = 174.6 \sin \frac{\theta}{2} N$

For vane:

 $ZM_0 = 0: 174.6 \sin \frac{\theta}{2} \cos \frac{\theta}{2} \left(\frac{0.100}{\sin \theta} \right) - 6 (9.81)(0.240 \sin \theta) = 0$

 $87.3 \times 0.100 = 6(9.81)(0.240 \sin \theta)$ $\sin \theta = 0.618, \ \theta = 38.2^{\circ}$

Assumption: Entire air stream is diverted downward along the vane, with no flow toward O.

Flow rate $Q = \frac{340 \times 231}{1728 \times 60} = 0.758 \frac{ft^3}{sec}, m' = \rho Q = \frac{62.4}{32.2} 0.758 = 1.468 \frac{16-sec}{ft}$ Flow area $A_A = \frac{\pi 2^2}{4} / 144 = 0.0218 \quad ft^2, \quad A_B = \frac{\pi n/2}{4} / 144 = 0.00545 \quad ft^2$ Velocity $U_A = \frac{Q}{A_A} = \frac{0.758}{0.0218} = 34.7 \frac{ft}{sec}, \quad U_B = \frac{Q}{A_B} = \frac{0.758}{0.00545} = 138.9 \frac{ft}{sec}$ $U_A = 34.7 \frac{ft}{sec} \longrightarrow V_B = 138.9 \quad ft/sec$ $U_A = 34.7 \frac{ft}{sec} \longrightarrow V_B = 138.9 \quad ft/sec$ $U_A = 106.4 \quad ft/sec$ U_A

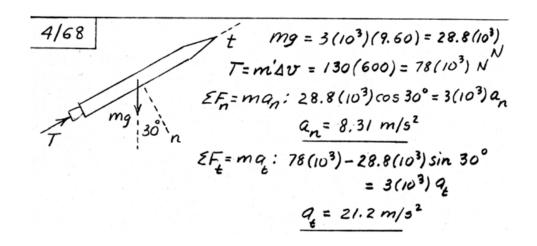
#\(\(\begin{align*} \int \text{Prom Part (b) of Sample Problem } & m' = pA(\superscript{u}-u) \\ &= (1000) \frac{\pi \times 0.140^2}{4} (150-u) \\ &= 15.39 (150-u) \times 4/5 \\ &= pA(\superscript{u}-u)^2 (1-(-0.5)) \\ &= 15.39 (150-u)^2 (1-(-0.5)) \\ &= 23.1 (150-u)^2 - 1373 \\ &= 1400 \times \\ &\superscript{u} &= 131.0 \times \\ &\superscript{u} &\superscript{u} &\superscript{u} &\superscript{0.1(1400)(9.81)} \\ &\superscript{N} &\superscript{u} &\superscript{0.1(1400)(9.81)} \\ &\superscript{N} &\superscript{u} &\supersc

4/67

$$\sum F_{g} = ma + mu : -9.8/m = 6.80m - 220(820) + y$$

$$m = 10.86 (10^{3}) kg$$
or $m = 10.86 Mg$

$$u = 820 m/s$$



4/69 $mg = 2.04(10^6)(9.81) = 20.0(10^6) N$ $3P_1 = 3(2.00)(10^6) = 6.00(10^6) N$ $2P_2 = 2(11.80)(10^6) = 23.6(10^6) N$ $3P_2 = 2(11.80)(10^6) = 23.6(10^6) N$ $3P_3 = 3(2.00)(10^6) = 23.6(10^6) N$ $3P_4 = 3(2.00)(10^6) = 23.6(10^6) N$ $3P_4 = 3(2.00)(10^6) = 23.6(10^6) N$ $3P_4 = 455 \text{ s}$ $4P_4 = 455 \text{ s}$ $4P_$

4/70

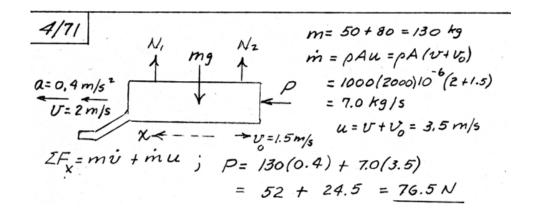
$$\sum F_{x} = m\dot{v} + mu$$

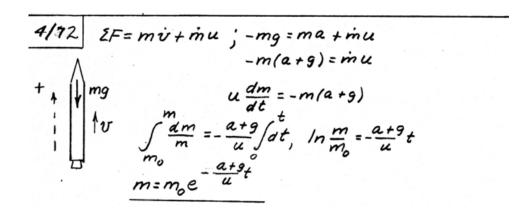
$$u = 60 \text{ ft/sec}$$

$$a = 2 \text{ ft/sec}^{2} \quad \dot{m} = -\frac{80}{32.2} = -2.48 \frac{\text{s/ugs}}{\text{sec}}$$

$$m = \frac{20,000}{32.2} = 621 \text{ s/ugs}$$
(a) Water on; $P = 621(2) - 2.48(60)\cos 30^{\circ}$

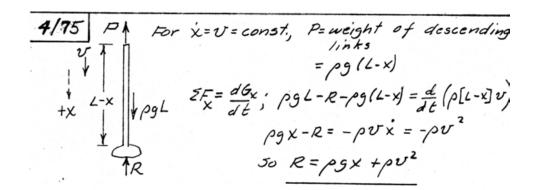
$$= 1242 - 129 = 1/13 \text{ /b}$$
(b) Water off; $\dot{m} = 0$, $P = 1242 \text{ /b}$



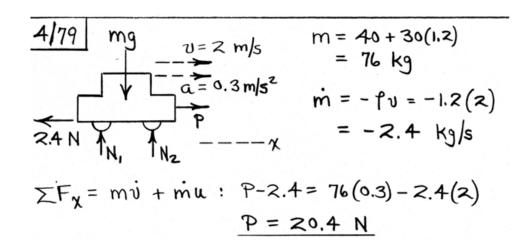


 $F = \frac{1}{\sqrt{3}}$ $F = \frac{1}{\sqrt{3}}$ F =

mg With added moisture particles
initially at rest, relative velocity
of attachment of mass is u = vThus with $\Sigma F = mv + mu$ we have $\Sigma F = mv + mv = \frac{d}{dt}(mv)$ V where $\Sigma F = mg - R$



 $\frac{4/76}{2F_{x} = 380 - 200 = 180 \text{ lb}} = \frac{12000 + 4(220)}{32.2}$ $= \frac{12000 + 4(220)}{32.2}$ $= \frac{400 \text{ lb-sec}^{2}/\text{ft}}{\text{at } t = 4 \text{ sec.}}$ $m = \frac{220/32.2 = 6.83 \text{ lb-sec}/\text{ft}}{\text{l.5 mi/hr}} = 2.20 \text{ ft/sec}$ $u = 2.20 - 10 \cos 60^{\circ} = -2.80 \text{ ft/sec}$ $So 180 = 400 \dot{v} + 6.83(-2.80), a = \dot{v} = 0.498 \text{ ft/sec}^{2}$



For constant initial speed

propeller thrust T

= drag R.

Added power = $\Delta T \cdot \sigma$, $\Delta T \times \frac{280 \times 1000}{3600} = 223.8 (10^3) \text{ watts (joules/second)}$ $\Delta T = 2880 \text{ N}$ $\Sigma F_x = m\dot{\sigma} + m\dot{\sigma} \text{ where } \dot{m} = 4.5 \times 1000/12 = 375 \text{ kg/s},$ $u = \sigma = \frac{280 \times 1000}{3600} = 77.8 \text{ m/s}$ So $2880 = 16.4(10^3) \dot{\sigma} + 375(77.8), \dot{\sigma} = a = -1.603 \text{ m/s}^2$

4/81

$$\frac{\chi}{2} = \frac{\chi}{2} \qquad p = 48/8 = 6 \text{ kg/m}$$

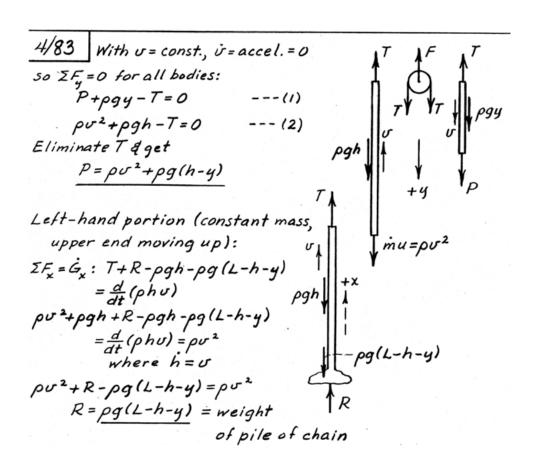
$$\dot{m} = \rho \frac{d}{dt} \left(\frac{\chi}{2}\right) = \frac{1}{2} \rho \dot{\chi} = \frac{1}{2} \rho \dot{v} = \frac{1}{2} (6)(1.5) = 4.5 \text{ kg/s}$$

$$u = v = 1.5 \text{ m/s}$$

$$\Sigma F = m \dot{v} + \dot{m} u$$
(a) $\dot{v} = 0$; $P = 0 + 4.5 (1.5) = 6.75 \text{ N}$
(b) $m = \rho \frac{\chi}{2} = 6\left(\frac{4}{2}\right) = 12 \text{ kg}$

$$20 = 12 \dot{v} + 4.5 (1.5), \quad \alpha = \dot{v} = 1.104 \text{ m/s}^2$$

 $\frac{4/82}{T} \sum F_{x} = ma_{x}: T - mg \sin \theta = ma_{x} \prod_{j=0}^{mg} x_{j}$ $T = m'u = \frac{2}{32.2} (400) = 24.8 \text{ lb constant}$ $M = m_{0} - m't = \frac{2}{32.2} (125 - 2t) \text{ lb-sec}^{2}/ft$ $Propulsion time t = \frac{20}{2} = 10 \text{ sec}$ $So m'u - (m_{0} - m't) g \sin \theta = (m_{0} - m't) \frac{dv}{dt}$ $\int_{0}^{t} \left[\frac{m'u}{m_{0} - m't} - g \sin \theta \right] dt = \int_{0}^{v} dv$ $\Rightarrow v = u \ln \left(\frac{m_{0}}{m_{0} - m't} \right) - g t \sin \theta$ $When t = 10 \text{ sec}, v = 400 \ln \left(\frac{125}{125 - 20} \right) - 32.2(10) \sin 10^{\circ}$ = 13.83 ft/sec



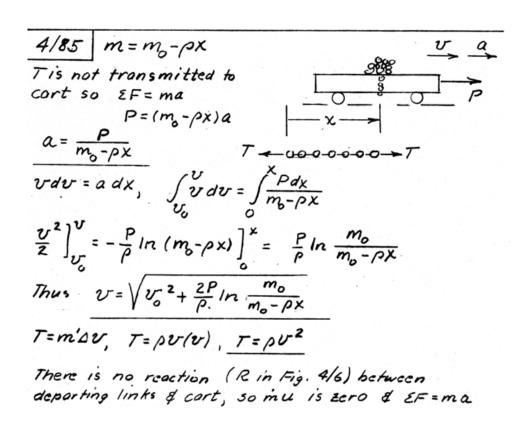
4/84 Let $m_0 = initial mass of car = 25(10^3) kg$ $\dot{m} = 4(10^3) kg/s$ The Car acquires mass which has zero initial horizontal velocity, so for horizontal x-dir, $\sum F_x = \frac{d}{dE}(mt)$

$$0 = \frac{dt}{dt} \left(m_0 + \dot{m}t \right) v \quad \left(m_0 + \dot{m}t \right) \alpha + \dot{m}v = 0$$

$$\alpha = \frac{dv}{dt} = -\frac{\dot{m}v}{m_0 + \dot{m}t}$$

$$\int_{0}^{\infty} \frac{dv}{v} = -\int_{0}^{\infty} \frac{\dot{m}}{m_0 + \dot{m}t} dt \Rightarrow v = \frac{dx}{dt} = \frac{m_0v_0}{m_0 + \dot{m}t}$$
Then
$$\int_{0}^{\infty} dx = \int_{0}^{\infty} \frac{m_0v_0}{m_0 + \dot{m}t} dt \Rightarrow x = \frac{m_0v_0}{\dot{m}} \ln \left(\frac{m_0 + \dot{m}t}{m_0} \right)$$
With
$$t = \frac{32}{4} = 8 s, \quad x = \frac{25(10^3)(1.2)}{4(10^3)} \ln \left(\frac{25 + 4(8)}{25} \right)$$

$$\chi = 6.18 \text{ m}$$



4/86 Let x be the displacement of the chain & T be the tension in the chain at the corner.

Horiz. part IF = max:

 $T = \rho(L - h - x)\ddot{x}$

Vert. part ZF = may:

pgh-T=phx Eliminate T & get

$$\ddot{x} = \frac{gh}{L - x}$$

$$\dot{x} \, d\dot{x} = \ddot{x} \, dx : \int_{0}^{\sigma_{1}^{2}} \frac{d(\dot{x}^{2})}{2} dx = \int_{0}^{L - h} \frac{gh}{L - x} dx$$

$$\frac{\dot{x}^2}{2}\Big|_{\dot{x}=0}^{\sigma_1} = -gh \ln(L-x)\Big|_{0}^{L-h}, \frac{{\sigma_1}^2}{2} = gh \ln(L-x)\Big|_{L-h}^{0} = gh \ln\frac{L}{h}$$

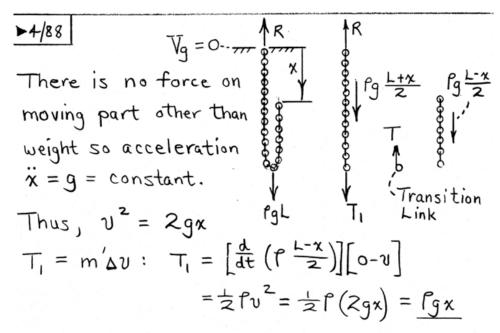
(a)
$$v_r = \sqrt{2gh \ln(L/h)}$$

(a)
$$v_1 = \sqrt{2gh \ln(L/h)}$$

(b) Free fall of end A gives $v_2^2 = v_1^2 + 2gh = 2gh \ln \frac{L}{h} + 2gh$
 $v_2 = \sqrt{2gh(I + \ln[L/h])}$

(c)
$$Q = loss of potential energy since $\Delta T = 0$
 $Q = pgh\frac{h}{2} + pg(L-h)h$, $Q = pgh(L-\frac{h}{2}) loss$$$

4/87 For airplane plus moving portion of chains $\begin{aligned} & \Sigma F = O = m\dot{v} + \dot{m} \, u = \left(m + 2\rho \frac{x}{2} \right) \dot{v} + \left[2\frac{d}{dt} \left(\rho \frac{x}{2} \right) \right] v \\ & - \left(m + \rho x \right) \frac{dv}{dt} = \rho \frac{v}{dt} \quad \frac{dv}{v} = -\frac{\rho dx}{m + \rho x} \\ & \int \frac{dv}{v} = -\int \frac{x}{m + \rho x} \, ; \quad \ln \frac{v}{v} = -\ln \frac{m + \rho x}{m} \, , \quad \frac{v}{v_o} = \frac{m}{m + \rho x} \end{aligned}$ or $v = \frac{v_o}{I + \rho x / m} \quad \text{if } \int \frac{v}{v_o} = -\ln \frac{m + \rho x}{m} \, , \quad \frac{v}{v_o} = \frac{m}{m + \rho x}$ $or \quad v = \frac{v_o}{I + \rho x / m} \quad \text{if } \int \frac{v}{v_o} = -\ln \frac{m + \rho x}{m} \, , \quad \frac{v}{v_o} = \frac{m}{I + \frac{2\rho L}{m}}$ $Also, \quad v = \frac{dx}{dt} \quad \text{so} \quad \int (I + \frac{\rho x}{m}) \, dx = \int \frac{v}{v_o} \, dt$ $x + \frac{\rho x^2}{2m} = v_o t \, , \quad x^2 + \frac{2m}{\rho} x - \frac{2m v_o t}{\rho}$ $x = -\frac{m}{\rho} \pm \frac{1}{2} \sqrt{\frac{4m^2}{\rho^2} + \frac{8m v_o t}{\rho}} \, , \quad x = \frac{m}{\rho} \left[\sqrt{I + \frac{2v_o t \rho}{m}} - I \right]$ for + root

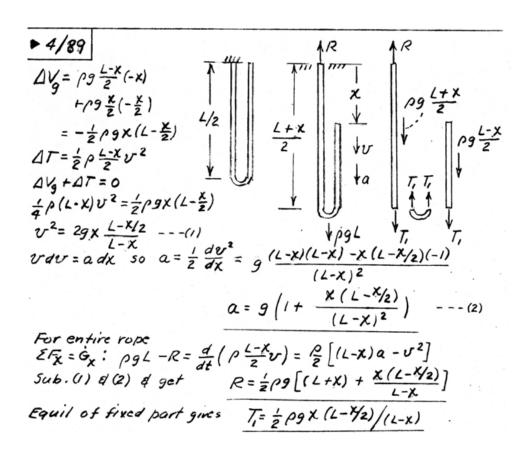


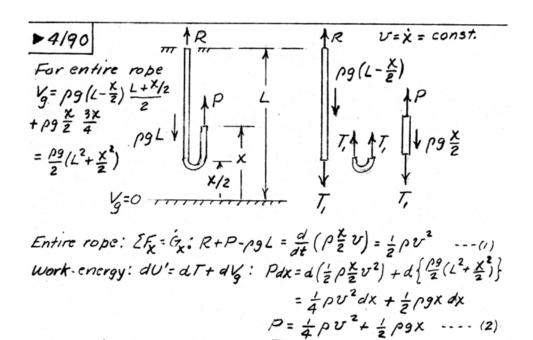
Equilibrium of links at rest:

$$\sum F_{\chi} = 0: T_{1} + f_{9} \frac{L+\chi}{2} - R = 0$$

$$\Rightarrow R = \frac{1}{2} f_{9} (L+3\chi)$$

When x > L, v > 0. The loss of potential energy equals the gain in kinetic energy, so the gain is concentrated in the last element and is lost during impact when the last element is abruptly brought to rest.





Sub. (2) into (1)

 $R = \frac{1}{4} \rho v^{2} + \rho g \left(L - \frac{x}{2} \right)$ $EF_{y} = 0: R - \rho g \left(L - \frac{x}{2} \right) - F_{z} = 0, \ F_{z} = \frac{1}{4} \rho v^{2}$

not moving EF=0: R-pg(L-

Fatire chain: $EF_{x} = G_{x}$ $R + P - pgL = \frac{1}{2}pU^{2} = 0$, $P = \frac{1}{2}p(U^{2} + gx)$ Equil. of part $F_{x} = 0$: $P - pg(L - \frac{x}{2})$ Equil. of part $F_{x} = 0$: $P - pg(L - \frac{x}{2})$ $F_{y} = 0$: $F_$

►4/92 For falling part $ZF = m\dot{v} + m\dot{u}$ Where ZF = pgx, m = px, $\dot{m} = pv$, $u = v = \dot{x}$ Thus $pgx = px\dot{v} + pv\dot{x}$, gx dt = x dv + v dxor gx dt = d(xv); $gx^2v dt = xv d(xv)$ so $gx^2dx = \frac{1}{2}d(x\dot{v})^2$ & $g\int_0^x x^2dx = \frac{1}{2}\int_0^x d(xv)^2$ $\frac{gx^3}{3} = \frac{1}{2}(xv)^2$, $v = \sqrt{\frac{2gx}{3}}$ $a = \dot{v} = \sqrt{\frac{2g}{3}}\frac{1}{2}\dot{x}^{-1/2}\dot{x} = \sqrt{\frac{2g}{3}}\frac{1}{2\sqrt{x}}\sqrt{\frac{2gx}{3}}$, $a = \frac{g}{3}$ constant $Q = -\Delta V_g - \Delta T = + \frac{pgL^2}{2} - \frac{pL}{2}V_{x=L}^2 = \frac{pgL^2}{2} - \frac{pgL^2}{3} = \frac{pgL^2}{6}$

 $\begin{array}{c}
4/93 \\
\overline{A} = \overline{A} = 53.7 \text{ ft/sec}^2
\end{array}$ $F = 20 \text{ lb} \\
\overline{A} = \overline{A} = 53.7 \text{ ft/sec}^2$ W = 12 lb

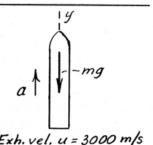
4/94 For the system, $\sum M_0 = \dot{H}_0 = 0$, so Ho is conserved: $\frac{2}{16} \left(1000\right) \frac{10}{12} = \frac{2}{16} \left(\frac{10}{12}\right)^2 \omega + 3 \left(\frac{20}{12}\right)^2 \omega$ $\omega = 12.37 \text{ rad/sec}$

A large horizontal force is exerted on the rod by the bearing so that $\Sigma F \neq 0$ in the horizontal direction. Thus $G_{\chi} \neq 0$ and the linear momentum of the bullet-pendulum system is not conserved.

 $F = m'\Delta v_{x}: \Delta v_{x} = v \cos 20^{\circ}$ $Q = Av: \frac{1400 \times 231}{1728} \frac{1}{60} \frac{ft^{3}}{sec}$ $= \frac{\pi \times 2^{2}/4}{144} v_{x}, \quad v = 143.0 \text{ ft/sec}$ $\Delta v_{x} = 143.0 \cos 20^{\circ} - 0 = 134.4 \text{ ft/sec}$ $m' = \rho Q = \frac{62.4}{32.2} \frac{1400 \times 231}{1728 \times 60} = 6.04 \text{ lb-sec/ft}$ F = 6.04 (134.4) = 812 lb

 $\frac{4/96}{\sum F = ma: m'u - (m_o - m't)g = (m_o - m't)a} = \frac{1}{mo - m't} - g$ $\alpha = \frac{dv}{dt} = \frac{m'u}{m_o - m't} - g$ $\int_0^1 dv = \int_0^1 \frac{m'u}{m_o - m't} dt - \int_0^1 g dt$ $v = -u \ln(m_o - m't)|_0^1 - gt|_0^1$ $v = u \ln(\frac{m_o}{m_o - m't}) - gt$

 $\frac{4/98}{T = m'u} = 120(640) = 76.8 (10^{3}) \text{ N}$ $\Sigma F_{t} = ma_{t} : 76.8 (10^{3}) - 26.2 (10^{3}) \cos 30^{\circ}$ $= 2.80 (10^{3}) a_{t}$ $a_{t} = 19.34 \text{ m/s}^{2}$ $\Sigma F_{n} = ma_{n} : 26.2 (10^{3}) \sin 30^{\circ}$ $= 2.80 (10^{3}) a_{n}$ $a_{n} = 4.67 \text{ m/s}^{2}$



$$ZF = m\dot{s} + m\dot{u} : -mg = ma - 5.2(3000)$$

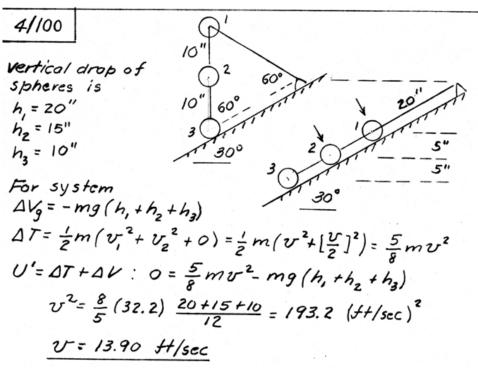
$$(1400 - 5.2t)(a + 8.70) = 15600$$

$$a = \frac{15600}{1400 - 5.2t} - 8.70 \text{ m/s}^2$$

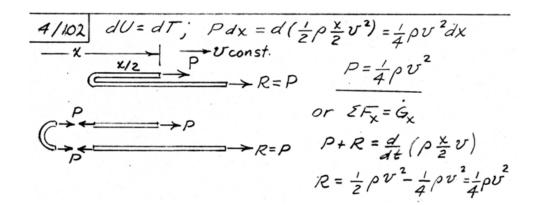
When
$$t = 60 s$$
, $a = \frac{15600}{1400 - 5.2(60)} - 8.70 = 14.34 - 8.70$
= 5.64 m/s²

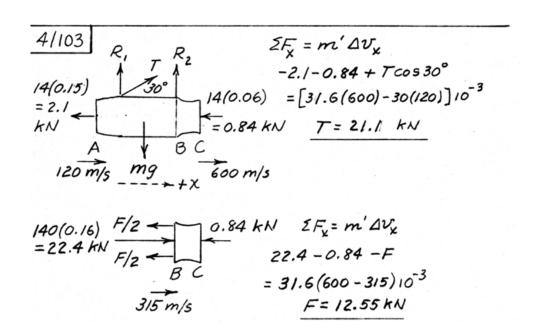
Max. accel. occurs when 5.2 t = 1200, t = 231 s

$$a_{\text{max}} = \frac{15600}{1400 - 5.2(231)} - 8.70 = 78.0 - 8.70 = 69.3 \text{ m/s}^2$$



Potential energy loss goes into impact energy loss





4/104
$$G_{x} = \rho(L-x)\sqrt{zgx} = \rho\sqrt{zg}\left(Lx^{1/2}-x^{3/2}\right)$$

$$\downarrow x \qquad \rho gL \qquad \mathcal{E}F_{x} = \dot{G}_{x} \quad \text{for entire system}$$

$$\downarrow \dot{x} = U \qquad \rho gL - F = \rho\sqrt{zg}\left(\frac{1}{2}Lx^{-1/2} - \frac{3}{2}x^{1/2}\right)\dot{x}$$

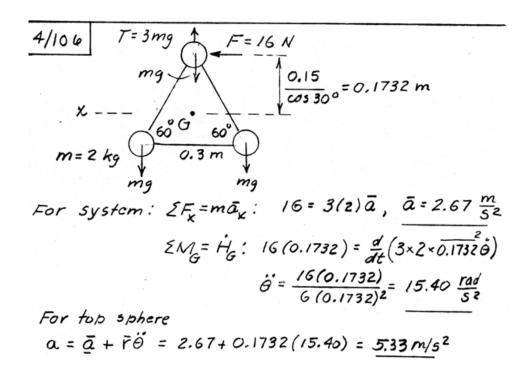
$$= \rho\sqrt{2g}\left(\frac{1}{2}L\sqrt{zg} - \frac{3}{2}\sqrt{zg}x\right)$$

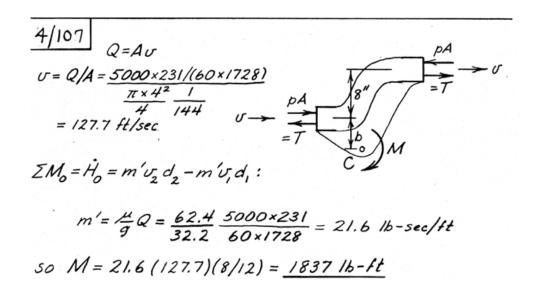
$$= \rho gL - 3\rho gx$$

$$= \rho gL - 3\rho gx$$

$$= \rho gL - 3\rho gx$$
Alternatively
$$\rho gx \qquad P \qquad P = m'\Delta u = \rho\dot{x}(\dot{x}) = \rho\dot{x}^{2} = \rho(2gx) = 2\rho gx$$

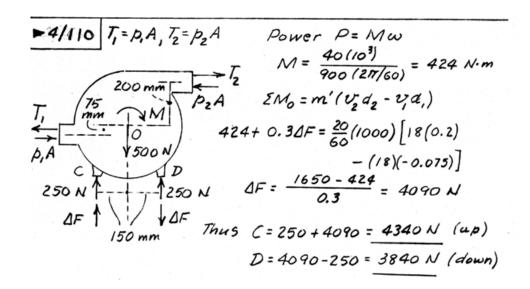
$$\mathcal{E}F = 0; \quad 2\rho gx + \rho gx - F = 0, \quad F = 3\rho gx$$





4/108 System is conservative, so $\Delta V_g + \Delta T = 0$. $-\rho g \times \frac{x}{2} + \frac{1}{2}\rho L \dot{x}^2 = 0, \quad \frac{g}{L} \times^2 = \dot{x}^2, \quad \dot{x} = \sqrt{\frac{g}{L}} \times$ (a) $accel\ a = \ddot{x} = \sqrt{\frac{g}{L}} \dot{x} = \sqrt{\frac{g}{L}} \sqrt{\frac{g}{L}} x$, so $a = \frac{g}{L} x$ (b) $\Sigma F = ma$: $T = \rho(L - x) \frac{g}{L} x$ $T = \rho g \times (1 - \frac{x}{L})$ Check from vertical part $\rho g x - T = \rho x \frac{g}{L} x, \quad T = \rho g \times (1 - \frac{x}{L}), o x.$ (c) $v dv = a_x dx$: $\int_0^v dv = \frac{g}{L} \int_0^L x dx, \quad \frac{v^2}{2} = \frac{g}{L} \frac{L^2}{2}, \quad v = \sqrt{gL}$

For entire rope of constant mass $ZF_{x} = G_{x}, pgL - R = \frac{d}{dt} \left(p[L-x]\dot{x} + 0 \right) - - - - (1)$ $AT + \Delta V_{g} = 0; \frac{1}{2}p(L-x)\dot{x}^{2} = pgx\left(L - \frac{x}{2} \right)$ $\dot{x}^{2} = \frac{x(2L-x)}{L-x}g \quad \text{or} \quad \dot{x}(L-x) = \frac{x}{x}(2L-x)g$ Substitute into (1) & get $pgL - R = \frac{d}{dt} \left(\frac{x(2L-x)}{\dot{x}}pg \right) = pg\frac{\dot{x}[2L-2x]\dot{x} - x[2L-x]\dot{x}}{\dot{x}^{2}}$ $= 2pg(L-x) - pgx\left(2L-x \right)\frac{\ddot{x}}{\dot{x}^{2}}$ Differentiate \dot{x}^{2} & get $\ddot{x} = \left[1 + \frac{x(L-\frac{x}{2})}{(L-x)^{2}} \right]g$. Substitute $4 \text{ set } pgL - R = 2pg\left(L-x \right) - pgx\left(2L-x \right) \left[1 + \frac{x(L-\frac{x}{2})}{(L-x)^{2}} \right]g/\dot{x}^{2}$ Substitute \dot{x}^{2} , simplify, & solve for R 4 get $R = pgx \frac{4L-3x}{2(L-x)}, \quad \text{(Less than } R_{a=0} \text{ of Prob. } 4 \text{ pos}$ with $x < \frac{2L}{3}$)



Entire system is conservative so $\Delta V_g + \Delta T = 0$ $-\rho g \times \frac{\chi}{2} + \frac{i}{Z} \rho \times V^2 = 0, \quad V = Vg \times, \quad \alpha = \dot{v} = \frac{i}{Z} \frac{\sqrt{g}}{\sqrt{g}} \sqrt{g} \times = \frac{g}{2} \sqrt{g}$ For entire system $\Sigma F_{\chi} = \dot{G}_{\chi}$ $\rho g L - R = \frac{d}{dt} (\rho \times V) = \frac{d}{dt} (\rho \sqrt{g} \times^{3/2}) = \frac{3}{2} \rho g \times \chi$ $\chi = \rho g L - \frac{d}{dt} (\rho \times V) = \frac{d}{dt} (\rho \sqrt{g} \times^{3/2}) = \frac{3}{2} \rho g \times \chi$ $\chi = \rho g L - \frac{d}{dt} (\rho \times V) = \frac{d}{dt} (\rho \sqrt{g} \times^{3/2}) = \frac{3}{2} \rho g \times \chi$ $\chi = \rho g L - R = \rho g L - \frac{3}{2} \rho g \times \chi$ $\chi = \rho g (L - \frac{3}{2} \times \chi)$ $\chi = \rho g (L - \frac{3}{2} \times \chi)$ $\chi = \rho g (L - \frac{3}{2} \times \chi)$ $\chi = \rho g (L - \chi) = \rho g (L - \frac{3}{2} \times \chi)$ $\chi = \rho g (L - \chi) = \rho g (L - \chi)$ $\chi = \rho g (L - \chi) - \rho g (L - \chi)$ $\chi = \rho g (L - \chi)$ $\chi = \rho g (L - \chi) - \rho g (L - \chi)$ $\chi = \rho g (L - \chi)$ $\chi = \rho g (L - \chi)$ $\chi = \rho g (L - \chi)$

With neglect of mass of pulley 4 weight of small portion of chain in contact with pulley $EM_0 \approx 0$ so $T_1 = T_2 = T$ EF = ma for chains FF =

So
$$T = \rho(H - h)\frac{h}{H}g + \rho g(H - h)$$
, $T = \rho g(H - \frac{h^2}{H})$ (4)
Pulley 4 chain on it: steady flow gives

$$\Sigma F_y = m'\Delta v_y: 2T - R = \rho v (v - [-v]), R = 2T - 2\rho v^2$$
 (5)
But $\int_0^v v dv = \int_0^h \frac{g}{H} h dh$, $v^2 = \frac{g}{H} h^2$, $v = \sqrt{\frac{g}{H}} h$ (6)

Substitute (4) \$\frac{1}{4}\$ (6) into (3) \$\frac{4}{9}et\$ $R = 2pg(H - \frac{h^2}{H}) - 2p\frac{g}{H}h^2, R = 2pg(H - \frac{2h^2}{H})$