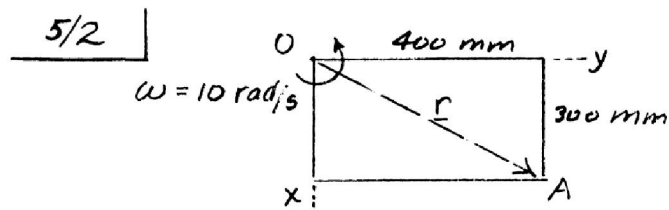


$$\frac{5/1}{\quad} \quad \alpha = \frac{\Delta\omega}{t} = \frac{800-200}{4/60} = 9000 \text{ rev/min}^2$$

$$\omega_2^2 = \omega_1^2 + 2\alpha\theta, \quad 800^2 = 200^2 + 2(9000)\theta \quad (\text{rev/min})^2$$

$$\theta = \frac{800^2 - 200^2}{2(9000)} = \underline{33.3 \text{ rev}} = \text{N}$$



$$r = 500 \text{ mm or } 0.5 \text{ m}$$

$$(a) \text{ Scalar: } v = r\omega = 0.5(10) = \underline{5 \text{ m/s}}$$

$$a = a_n = r\omega^2 = 0.5(10^2) = \underline{50 \text{ m/s}^2}$$

$$(b) \underline{r} = 0.3\underline{i} + 0.4\underline{j} \text{ m}, \underline{\omega} = 10\underline{k} \text{ rad/s}$$

$$\underline{v} = \underline{\omega} \times \underline{r} = 10\underline{k} \times (0.3\underline{i} + 0.4\underline{j}) = 3\underline{j} + 4(-\underline{i})$$

$$v = \sqrt{3^2 + (-4)^2} = \underline{5 \text{ m/s}}$$

$$\underline{a} = \dot{\underline{\omega}} \times \underline{r} + \underline{\omega} \times \underline{v} = 0 + \underline{\omega} \times \underline{v}$$

$$= 0 + 10\underline{k} \times (3\underline{j} - 4\underline{i}) = -30\underline{i} - 40\underline{j} \text{ m/s}^2$$

$$|\underline{a}| = \sqrt{30^2 + 40^2} = \underline{50 \text{ m/s}^2}$$

5/3 | Let  $\underline{k}$  be a unit vector out of paper.

$$(a) \underline{v}_A = \underline{\omega} \times \underline{r}_{A/o} = 3\underline{k} \times (-0.4\underline{e}_n) = \underline{1.2\underline{e}_t} \text{ m/s}$$

$$\underline{a}_A = \underline{\alpha} \times \underline{r}_{A/o} - \omega^2 \underline{r}_{A/o} = -14\underline{k} \times (-0.4\underline{e}_n) - 3^2(-0.4\underline{e}_n) \\ = \underline{-5.6\underline{e}_t + 3.6\underline{e}_n} \text{ m/s}^2$$

$$(b) \underline{v}_B = \underline{\omega} \times \underline{r}_{B/o} = 3\underline{k} \times (-0.4\underline{e}_n + 0.1\underline{e}_t)$$

$$= \underline{1.2\underline{e}_t + 0.3\underline{e}_n} \text{ m/s}$$

$$\underline{a}_B = \underline{\alpha} \times \underline{r}_{B/o} - \omega^2 \underline{r}_{B/o} \\ = -14\underline{k} \times (-0.4\underline{e}_n + 0.1\underline{e}_t) - 3^2(-0.4\underline{e}_n + 0.1\underline{e}_t) \\ = \underline{-6.5\underline{e}_t + 2.2\underline{e}_n} \text{ m/s}^2$$

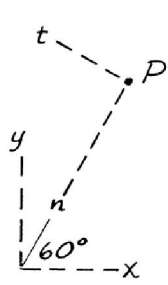
$$\frac{5/4}{\quad} \quad \omega_{AB} = \omega_{Cart} = \omega_{OG} = \frac{v_G}{OG}, \quad \omega = \frac{14.20}{(56-8)/12} = \underline{3.55 \frac{\text{rad}}{\text{sec}}}$$

$$\omega_{av} = \frac{\Delta\theta}{\Delta t} = \frac{\pi/4}{0.638} = \underline{1.231 \text{ rad/sec}}$$

5/5 | For  $\theta = 90^\circ$ ,  $\underline{a} = -a_t \underline{i} - a_n \underline{j}$  so  $a_t = r\alpha = 1.8 \text{ m/s}^2$ ,  
 $\alpha = \frac{1.8}{0.3} = \underline{6 \text{ rad/s}^2}$

$\& a_n = r\omega^2 = 4.8 \text{ m/s}^2$ ,  $\omega = \sqrt{4.8/0.3} = \underline{4 \text{ rad/s}}$

5/6



$$a_x = -3.02 \text{ m/s}^2$$

$$a_y = -1.624 \text{ m/s}^2$$

$$a_t = 3.02 \sin 60^\circ - 1.624 \cos 60^\circ = 1.803 \frac{\text{m}}{\text{s}^2}$$

$$a_n = 3.02 \cos 60^\circ + 1.624 \sin 60^\circ = 2.92 \frac{\text{m}}{\text{s}^2}$$

$$a_t = r\alpha: \alpha = 1.803/0.3 = \underline{6.01 \text{ rad/s}^2}$$

$$a_n = r\omega^2: \omega^2 = 2.92/0.3 = 9.72 \text{ (rad/s)}^2, \omega = \underline{3.12 \text{ rad/s}}$$

$$\underline{5/7} \quad \theta = 2t^3 - 3t^2 + 4 \text{ rad.}$$

$$\dot{\theta} = 6t^2 - 6t \text{ rad/s}$$

$$\ddot{\theta} = 12t - 6 \text{ rad/s}^2$$

$$\text{When } \ddot{\theta} = 42 \text{ rad/s}^2, 42 = 12t - 6, t = 4 \text{ s}$$

$$\text{When } \ddot{\theta} = 66 \text{ rad/s}^2, 66 = 12t - 6, t = 6 \text{ s}$$

$$\theta_{t=4\text{s}} = 2(4^3) - 3(4^2) + 4 = 84 \text{ rad}$$

$$\theta_{t=6\text{s}} = 2(6^3) - 3(6^2) + 4 = 328 \text{ rad}$$

$$\Delta\theta = 328 - 84 = \underline{244 \text{ rad}}$$

5/8

For point P,

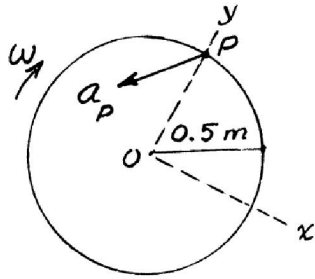
$$\underline{a}_P = -3\underline{i} - 4\underline{j} \text{ m/s}^2$$

$$a_n = r\omega^2, 4 = 0.5\omega^2, \omega = \sqrt{8} \frac{\text{rad}}{\text{s}}$$

$$\underline{\omega} = -\sqrt{8} \underline{k} \text{ rad/s}$$

$$a_t = r\alpha, 3 = 0.5\alpha, \alpha = 6 \text{ rad/s}^2$$

$$\underline{\alpha} = 6 \underline{k} \text{ rad/s}^2$$





$$\frac{5}{9} \quad a_{\theta} = a_t = r\alpha$$

$$\omega = \omega_0 + \alpha t: 300(2\pi)/60 = 0 + \alpha(2), \alpha = 5\pi \text{ rad/s}^2$$

$$\text{Thus } 5.5 = r(5\pi), r = 0.350 \text{ m}$$

$$b = \sqrt{0.350^2 - 0.3^2} = 0.1806 \text{ m or } \underline{b = 180.6 \text{ mm}}$$

$$\underline{5/10} \quad \underline{v_p = \underline{\omega} \times \underline{r} = 2\underline{k} \times [0.5\underline{i} + 0.2\underline{j} + 0.050\underline{k}]} \\ = \underline{-0.4\underline{i} + \underline{j} \text{ m/s}}$$

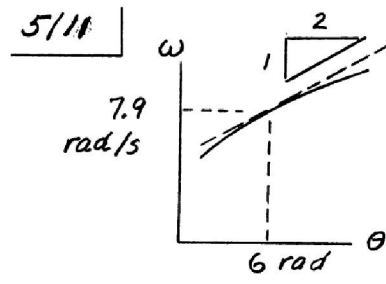
$$\underline{a_p = \underline{\alpha} \times \underline{r} + \underline{\omega} \times (\underline{\omega} \times \underline{r})} \\ = -3\underline{k} \times [0.5\underline{i} + 0.2\underline{j} + 0.050\underline{k}] \\ + 2\underline{k} \times [2\underline{k} \times (0.5\underline{i} + 0.2\underline{j} + 0.050\underline{k})] \\ = \underline{-1.4\underline{i} - 2.3\underline{j} \text{ m/s}^2}$$

Note that  $\underline{r}$  could have been taken as  $0.5\underline{i} + 0.2\underline{j}$  m  
The magnitudes of the above results are

$$v_p = 1.077 \text{ m/s} \quad \text{and} \quad a_p = 2.69 \text{ m/s}^2.$$

These magnitudes check with

$$v_p = r_{xy} \omega = \sqrt{0.5^2 + 0.2^2} (2) = 1.077 \text{ m/s}^2 \quad \checkmark \\ \text{and} \quad a_p = \sqrt{a_t^2 + a_n^2} = \sqrt{(r_{xy} \alpha)^2 + (r_{xy} \omega^2)^2} \\ = \sqrt{0.5^2 + 0.2^2} \sqrt{3^2 + 2^4} = 2.69 \text{ m/s}^2 \quad \checkmark$$

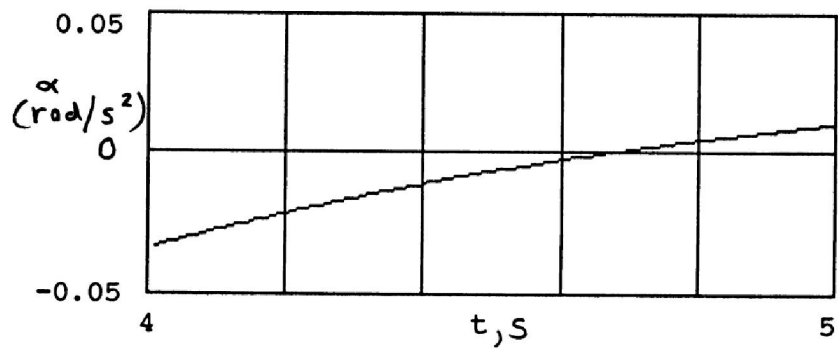
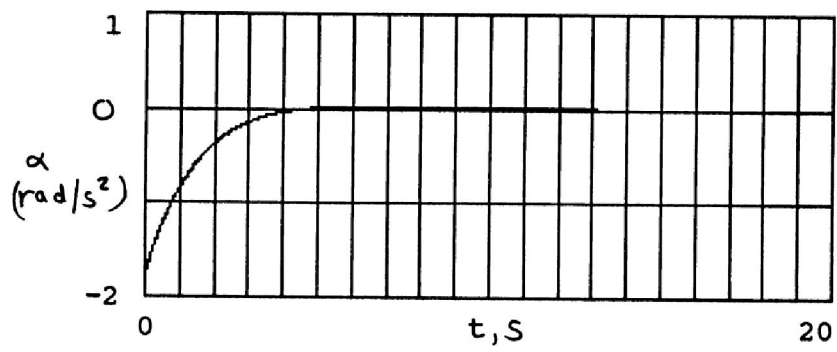
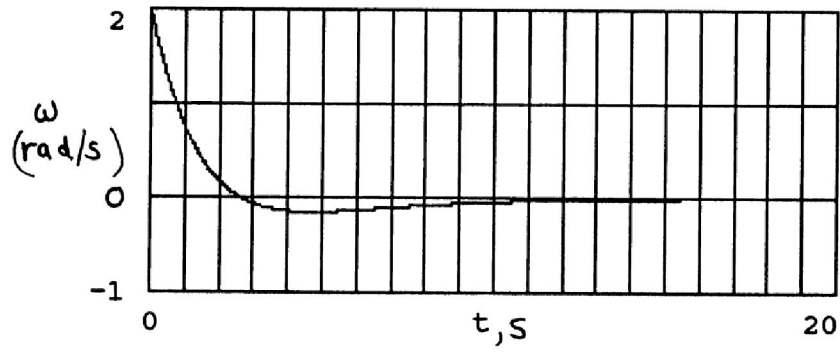
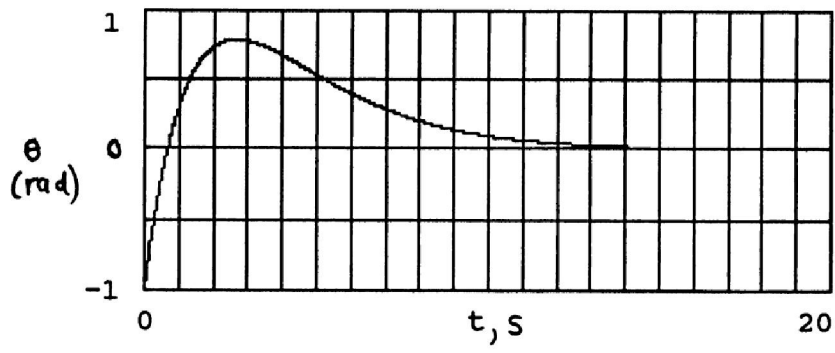


$$\alpha = \omega \frac{d\omega}{d\theta}$$
$$= 7.9 \left(\frac{1}{2}\right) = \underline{3.95 \text{ rad/s}^2}$$

$$\begin{aligned} \frac{5}{12} \quad \theta &= (-1 + 1.5t)e^{-0.5t} \\ \omega &= \frac{d\theta}{dt} = -0.5(-1 + 1.5t)e^{-0.5t} + 1.5e^{-0.5t} \\ &= \underline{(2 - 0.75t)e^{-0.5t}} \end{aligned}$$

$$\begin{aligned} \alpha &= \frac{d\omega}{dt} = -0.5(2 - 0.75t)e^{-0.5t} - 0.75e^{-0.5t} \\ &= \underline{(-1.75 + 0.375t)e^{-0.5t}} \end{aligned}$$

$$\alpha = 0 \text{ when } -1.75 + 0.375t = 0, \quad \underline{t = 4.67 \text{ s}}$$



$$\frac{5/13}{\quad} \quad \underline{\omega}_{OA} = \underline{\omega}_{BC} = -6\mathbf{k} \text{ rad/s}$$

$$\underline{r}_A = 0.3\mathbf{i} + 0.28\mathbf{j} \text{ m}$$

$$\underline{v}_A = \underline{\omega} \times \underline{r}_A = -6\mathbf{k} \times (0.3\mathbf{i} + 0.28\mathbf{j}) = -1.8\mathbf{j} + 1.68\mathbf{i} \text{ m/s}$$

$$\underline{v}_A = 1.68\mathbf{i} - 1.8\mathbf{j} \text{ m/s}$$

$$\underline{a}_A = \dot{\underline{\omega}} \times \underline{r}_A + \underline{\omega} \times \underline{v}_A = 0 + (-6\mathbf{k}) \times (1.68\mathbf{i} - 1.8\mathbf{j})$$

$$= -10.08\mathbf{j} - 10.08\mathbf{i}$$

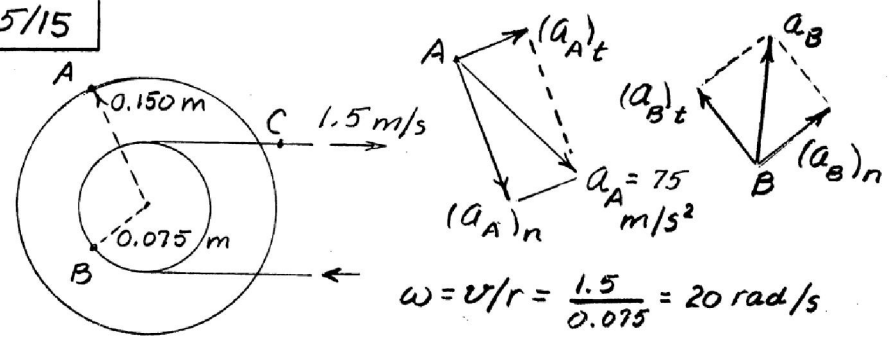
$$\underline{a}_A = -10.8\mathbf{i} - 10.08\mathbf{j} \text{ m/s}^2$$

5/14 | At B,  $v = \frac{50}{30} 44 = 73.3 \text{ ft/sec}$ ,  $r = 180 - \frac{18}{12} = 178.5 \text{ ft}$

$$\omega = v/r = 73.3/178.5 = \underline{0.411 \text{ rad/sec}}$$

Between A & B  $\omega_{av} = \frac{\Delta\theta}{\Delta t} = \frac{30}{180} \pi / 1.52 = \underline{0.344 \text{ rad/sec}}$

5/15



$$\omega = v/r = \frac{1.5}{0.075} = 20 \text{ rad/s}$$

$$(a_A)_n = r\omega^2 = 0.15(20)^2 = 60 \text{ m/s}^2$$

$$(a_A)_t = \sqrt{(75)^2 - (60)^2} = 45 \text{ m/s}^2$$

$$\alpha = a_t/r = 45/0.15 = \underline{300 \text{ rad/s}^2}$$

$$(a_B)_n = 0.075(20)^2 = 30 \text{ m/s}^2$$

$$(a_B)_t = r\alpha = 0.075(300) = 22.5 \text{ m/s}^2$$

$$a_B = \sqrt{(30)^2 + (22.5)^2} = \underline{37.5 \text{ m/s}^2}$$

$$a_C = a_{B_t} = \underline{22.5 \text{ m/s}^2}$$



$$\frac{5}{16} \quad a = a_n = \frac{v^2}{r}, \quad \left(\frac{v^2}{r}\right)_A = \frac{4}{3} \left(\frac{v^2}{4}\right)_B$$

$$r = \frac{4}{4/3} = \underline{3 \text{ in.}}$$

$$\underline{5/17} \quad \underline{v}_A = \underline{\omega} \times \underline{r}_A ; 8\underline{j} = \underline{\omega} \underline{k} \times 4\underline{i} , \underline{\omega} = 2 \text{ rad/sec}$$

$$\underline{\omega} = 2\underline{k} \text{ rad/sec}$$

$$(\underline{a}_B)_t = \underline{\alpha} \times \underline{r}_B ; 6\underline{i} = \underline{\alpha} \underline{k} \times 4\underline{j} , \underline{\alpha} = -3/2 \text{ rad/sec}^2$$

$$\underline{\alpha} = -\frac{3}{2} \underline{k} \text{ rad/sec}^2$$

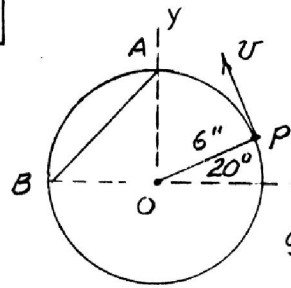
$$\underline{r}_C = \frac{4}{\sqrt{2}} (\underline{i} - \underline{j}) \text{ in.}$$

$$\underline{a}_C = \underline{\alpha} \times \underline{r}_C + \underline{\omega} \times (\underline{\omega} \times \underline{r}_C)$$

$$= -\frac{3}{2} \underline{k} \times \frac{4}{\sqrt{2}} (\underline{i} - \underline{j}) + 2\underline{k} \times (2\underline{k} \times \frac{4}{\sqrt{2}} [\underline{i} - \underline{j}])$$

$$= \frac{6}{\sqrt{2}} (-\underline{i} - \underline{j}) + \frac{16}{\sqrt{2}} (-\underline{i} + \underline{j}) = \underline{\sqrt{2}(-11\underline{i} + 5\underline{j})} \text{ in./sec}^2$$

5/18



$$v_x = -4.2 \text{ ft/sec}$$

$$v = 4.2 / \sin 20^\circ = 12.28 \text{ ft/sec}$$

$$\omega = \frac{v}{r} = \frac{12.28}{6/12} = 24.6 \frac{\text{rad}}{\text{sec}}$$

CCW

$$\underline{\omega} = \underline{\omega}_{OP} = \underline{+24.6k} \text{ rad/sec}$$

Element BC remains parallel to z-axis so has no angular velocity

$$\underline{5/19} \quad \alpha = \frac{d\omega}{dt} = 2 - kt = 2 - 0.2t$$

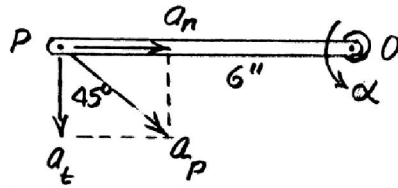
$$\int_{\omega_0}^{\omega} d\omega = \int_0^t (2 - 0.2t) dt, \quad \omega = \omega_0 + 2t - 0.1t^2$$

$$\omega_0 = 200 \times 2\pi / 60 = 20.9 \text{ rad/s}$$

$$\text{For } t = 5 \text{ s, } \omega = 20.9 + 2(5) - 0.1(5^2) = 28.4 \text{ rad/s}$$

$$N = 28.4 \times 60 / 2\pi = \underline{272 \text{ rev/min}}$$

5/20



$$\alpha = \frac{600(2\pi)}{60} \frac{1}{2} = 10\pi \text{ rad/sec}^2$$

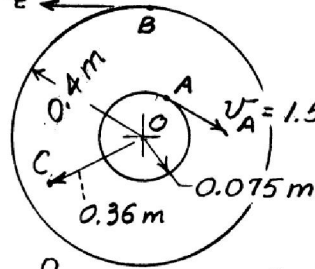
$$a_t = r\alpha = 6(10\pi) = 60\pi \text{ in./sec}^2$$

$$a_n = r\omega^2 = 60\pi \text{ in./sec}^2 \text{ for } 45^\circ$$

$$\text{So } \omega^2 = 60\pi/6 = 10\pi, \omega = 5.60 \text{ rad/s}$$

$$\omega = \omega_0 + \alpha t : 5.60 = 0 + 10\pi t, \underline{t = 0.1784 \text{ sec}}$$

$$\frac{5/21}{a_{Bt}} = a_B = 45 \text{ m/s}^2$$



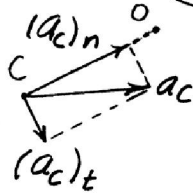
$$\omega = v/r = \frac{1.5}{0.075} = 20 \text{ rad/s}$$

$$\alpha = a_t/r = \frac{45}{0.4} = 112.5 \text{ rad/s}^2$$

$$(a_c)_n = r\omega^2 = 0.36(20)^2 = 144 \text{ m/s}^2$$

$$(a_c)_t = r\alpha = 0.36(112.5) = 40.5 \text{ m/s}^2$$

$$a_c = \sqrt{(144)^2 + (40.5)^2} = \underline{149.6 \text{ m/s}^2}$$



$$\underline{5/22} \quad \alpha = 1.8 - k\theta \text{ rev/s}^2, \theta \text{ in revolutions}$$

$$0.6 = 1.8 - k(20), \quad k = 0.06 \text{ 1/s}^2$$

$$\text{So } \alpha = 1.8 - 0.06\theta \text{ rev/s}^2; \quad \omega_0 = 300/60 = 5 \text{ rev/s}$$

$$\omega d\omega = \alpha d\theta: \quad \int_5^{\omega} \omega d\omega = \int_0^{20} (1.8 - 0.06\theta) d\theta$$

$$\omega^2 = 5^2 + 2 \left[ 1.8\theta - 0.03\theta^2 \right]_0^{20} = 25 + 48 = 73 \text{ (rev/s)}^2$$

$$\omega = \sqrt{73} = 8.54 \text{ rev/s or } N = 8.54(60) = \underline{513 \text{ rev/min}}$$

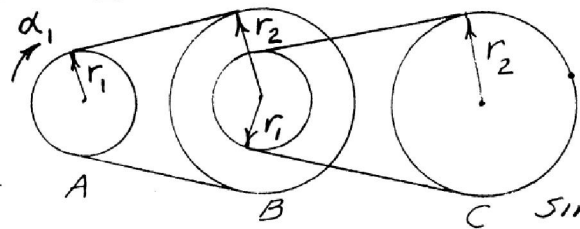
5/23 | For gear A,  $\Delta\omega = \int_2^6 \alpha_A dt$ ,  $N_A = 2N_B$

$$(N_A - 600) \frac{2\pi}{60} = \frac{4+8}{2} (6-2), N_A = 600 + 229 = 829 \text{ rev/min}$$

$$\text{so at } t=6\text{ s, } N_B = \frac{829}{2} = \underline{415 \text{ rev/min}}$$



► 5/24



$$r_2 \omega_C = r_1 \omega_B$$

$$r_2 \omega_B = r_1 \omega_A$$

so that

$$\omega_C = \left(\frac{r_1}{r_2}\right)^2 \omega_A$$

Similarly  $\alpha_C = \left(\frac{r_1}{r_2}\right)^2 \alpha_1$

$\omega_A = \alpha_1 t$  so that  $\omega_C = \left(\frac{r_1}{r_2}\right)^2 \alpha_1 t$

For P,  $a_n = r_2 \omega_C^2 = r_2 \left[ \left(\frac{r_1}{r_2}\right)^2 \alpha_1 t \right]^2$

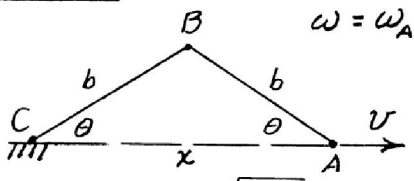
$$a_t = r_2 \alpha_C = r_2 \left(\frac{r_1}{r_2}\right)^2 \alpha_1$$

$$a_p = \sqrt{a_n^2 + a_t^2} = \frac{r_1^2}{r_2} \alpha_1 \sqrt{1 + \left(\frac{r_1}{r_2}\right)^4 \alpha_1^2 t^4}$$

5/25

$$x = 2b \cos \theta, \quad \dot{x} = -2b\dot{\theta} \sin \theta, \quad v = \dot{x}$$

$$\omega = \omega_{AB} = \dot{\theta} \text{ so } \omega = \frac{-v}{2b \sin \theta} \text{ CW}$$



$$\text{For } a = \ddot{x} \text{ const.}, \quad \dot{x}^2 = 2ax$$
$$v = \sqrt{2ax}$$

$$\text{so } \omega = \frac{\sqrt{2ax}}{2b \sqrt{1 - \cos^2 \theta}} = \frac{\sqrt{2ax}}{\sqrt{4b^2 - x^2}}$$

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