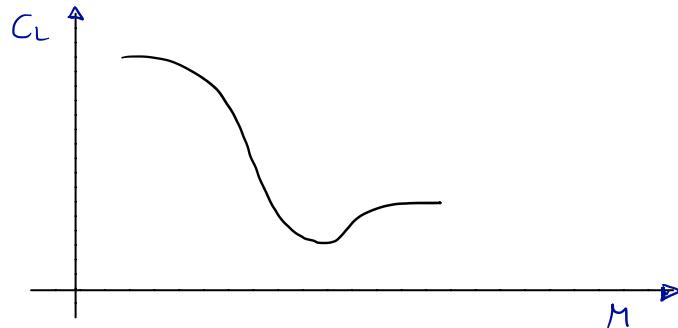


LECTURE 1

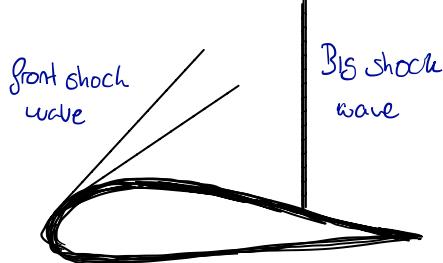
airbus

Elements of gasdynamics	High speed flow	} Extra books
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Practical wk 2.7 - 2.9 High speed



lift coefficient drops due to the presence of shock waves : (separation)



- Big shock wave establish transition between supersonic - subsonic.
- Front shock waves make sure boundary layer is turbulent.
- Big shock wave frequency can be dangerous for the wings

- For a turbine or an engine. To increase the efficiency the shock waves must be minimized.

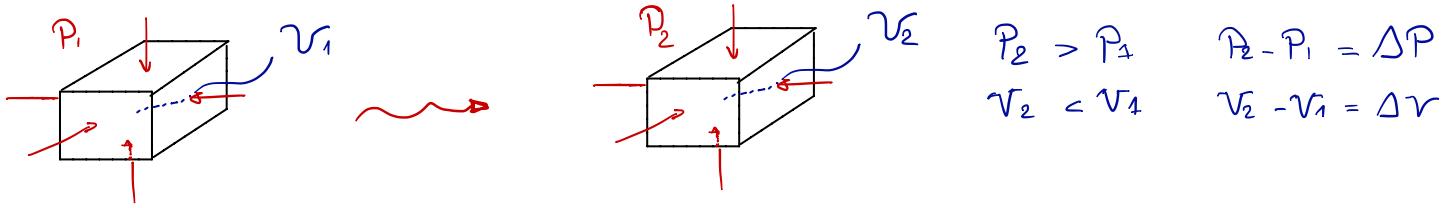
$$C_p \propto \frac{1}{\sqrt{1-M_\infty^2}}$$

Pressure is proportional to $\frac{1}{\sqrt{1-M_\infty^2}}$ Prandt - glauert singularity

FLows

- SUBSONIC $M_\infty < 0.8$ →
- TRANSONIC $0.8 < M_\infty < 1$ →
- TRANSONIC $1 < M_\infty < 1.2$ →
- SUPERSONIC $M_\infty > 1.2$ →
- HYPERSONIC $M_\infty > 5$ →

COMPRESSIBLE



compressibility:

$$\tau = -\frac{1}{V_1} \cdot \frac{\Delta V}{\Delta P}$$

Relationship between specific volume and density

$$v = 1/\rho$$

$$\tau = \frac{1}{P} \cdot \frac{\partial P}{\partial v}$$

$$dv = \frac{1}{P} dP = -\frac{1}{P^2} \partial P$$

compressibility differs in the way you compress.

- constant temperature $\tau_T = -\frac{1}{v} \left(\frac{\partial v}{\partial P} \right)_T$
- constant entropy $\tau_s = -\frac{1}{v} \left(\frac{\partial v}{\partial P} \right)_s$

- $\tau_{\text{solids}} \approx 10^{-12}$

- $\tau_{\text{liquid}} \approx 10^{-10}$

$$\frac{m^2}{N}$$

- $\tau_{\text{gas}} \approx 10^{-5}$

EQUATIONS FOR COMPRESSIBLE FLOW

- P is an additional variable
- introduce energy balance.

CONTINUITY, ENERGY,

3

variables
 P v P T e
 added by
 the heat
 equation.

Two extra equations.

$$P = \rho RT$$

$$e = C_v \cdot T$$

GAS MODEL
 2

ASSUMPTIONS

- 1-D flow
- Steady flow
- Inviscid flow
- No heat transfer
- No body forces.

CONTINUITY

$$\frac{\partial}{\partial t} \int_V \rho dv + \int_S \rho \vec{v} \cdot d\vec{s} = 0 \quad \int_S \rho \vec{v} \cdot d\vec{s} = \int_{A_1} \rho \vec{v} \cdot d\vec{s} - \int_{A_2} \rho \vec{v} \cdot d\vec{s} = 0$$

$$\rho V A = \text{constant}$$

$$\dot{m} = \text{constant}$$

Momentum Equation

$$\frac{\partial}{\partial t} \int_V d\vec{V} \cdot dV + \int_S \rho \vec{V} (\vec{V} \cdot d\vec{s}) = - \int_S p d\vec{s} + \int_V \rho \vec{f} dV = \int_{A_1} \rho \vec{V} (\vec{V} \cdot d\vec{s}) + \int_{A_2} \rho \vec{V} (\vec{V} \cdot d\vec{s}) =$$

$$- \int_{A_1 \cup A_2} P \cdot d\vec{s} - \int_{\text{side surface}} P \cdot d\vec{s} \longrightarrow -P_1 V_1^2 \cdot A_1 + P_2 V_2^2 \cdot A_2 = P_1 A_1 - P_2 A_2 - \int_{A_1}^2 P \cdot dA$$

$P + \rho V^2 = \text{constant}$ → for A(x) constant, constant area.

ENERGY:

$$\frac{\partial}{\partial t} \int_V \rho (e + \frac{1}{2} V^2) dV + \int_S \rho \vec{V} (e + \frac{1}{2} V^2) d\vec{s} = \int_V \dot{q} \rho dV - \underbrace{\int_S P \vec{V} \cdot d\vec{s}}_{\text{work done by pressure forces.}} + \underbrace{\int_V \rho (\vec{f} \cdot \vec{V}) dV}_{\text{body forces.}}$$

$$\int_S \rho \left(e + \frac{V^2}{2} + \frac{P}{\rho} \right) \vec{V} \cdot d\vec{s} = 0$$

$e + \frac{P}{\rho} + \frac{V^2}{2} = \text{constant}$

$$\left. \begin{array}{l} h = e + \frac{P}{\rho} \\ h = \text{constant} \\ h = C_p \cdot T \end{array} \right\}$$

$$H = h + \frac{V^2}{2}$$

$$\dot{m}, H_1 = \dot{m}_2 H_2$$

$$\rho \cdot H \cdot V \cdot A = \text{constant}$$

$E = e + \frac{V^2}{2}$ } total energy
 $H = e + \frac{V^2}{2} + \frac{P}{\rho}$ } total enthalpy

Enthalpy is conserved. Energy is not conserved for the flow cause it can give away energy.

FOR A FLOW

STAGNATION CONDITIONS: conditions of the flow for velocity equals to 0

$H = C_p \cdot T + \frac{V^2}{2}$ → Temperature increases as the velocity decreases.

STATIC STATE: nonzero velocity, the flow goes from stagnation condition to static state.

STAGNATION TEMPERATURE IS CONSTANT DURING AN ADIABATIC PROCESS.

e_0 } h_0 } are also constant. // Pressure is not known.

LECTURE 2

KINETIC GAS THEORY

- T and P are representations of molecular motion.
- T measure of average translational kinetic energy.
- P caused by impact of molecules on the wall.

EQUATION OF STATE

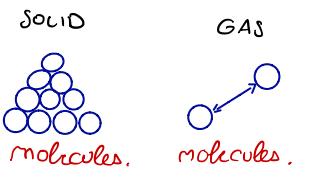
$$\frac{P}{n} = R \cdot T$$

$$R = \frac{R}{m} \rightarrow \text{universal gas constant}$$

$$\rightarrow \text{molar mass}$$

general case $C_V = C_V(P, T) \rightarrow$ constant for perfect gas

$$C_V = \left. \frac{\partial e}{\partial T} \right|_V \quad \begin{matrix} \text{constant} \\ \text{volume} \end{matrix}$$



PERFECT GAS MODEL EQUATIONS

$$m \cdot \frac{d^2 \vec{r}}{dt^2} = \vec{F}$$

m : mass of molecule

\vec{r} : position vector

\vec{F} : force acting on molecule

$$P = \frac{n \cdot m}{V}$$

SCALAR PRODUCT

$$m \vec{r} \cdot \frac{d^2 \vec{r}}{dt^2} = \vec{F} \cdot \vec{r}$$

VELOCITY OF MOLECULE

$$m \cdot \left[\frac{\partial}{\partial t} \cdot \vec{r} \cdot -\frac{\partial \vec{r}}{\partial t} - \left(\frac{d \vec{r}}{dt} \right)^2 \right] = \vec{r} \cdot \vec{F} \quad c = \frac{d \vec{r}}{dt} \quad \begin{matrix} \text{speed} \end{matrix}$$

$$m \cdot \left[\frac{\partial}{\partial t} \vec{r} \cdot \vec{c} - \vec{c}^2 \right] = \vec{r} \cdot \vec{F} \quad \begin{matrix} \text{single molecule.} \end{matrix}$$

ENSEMBLE AVERAGE $\overline{\vec{c}^2} = \frac{1}{N} \sum_{n=1}^N \vec{c}_n^2$ \rightarrow STATIONARY SYSTEM Time average

$$\overline{\vec{c}^2} = \frac{1}{T} \int_0^T \vec{c}_A^2 dt, \quad T \rightarrow \infty$$

$$m \cdot \underbrace{\left[\frac{d}{dt} \vec{r} \cdot \vec{c} - \vec{c}^2 \right]}_0 = \vec{r} \cdot \vec{F} \quad \begin{matrix} \text{f(p) at the wall} \end{matrix}$$

inside because interaction between molecules are random.

SPHERICAL VESSEL

$$\text{Radius } r_0 \quad \# \text{molecules } N \quad \left. \begin{aligned} -N \cdot m \cdot \vec{C}^2 &= \vec{F} \cdot \vec{r} \\ \# \text{mol} &\quad \text{average} \end{aligned} \right\} \quad \begin{aligned} \vec{F} &= p \cdot A \cdot \vec{n} = p \cdot 4\pi r_0^2 \cdot \vec{n} \\ \vec{r} &= -r_0 \vec{n} \\ |\vec{n}|^2 &= 1 = \vec{n} \cdot \vec{n} \end{aligned}$$

$$V = \frac{4}{3} \pi r_0^3$$

$$N \cdot m \cdot \vec{C}^2 = p \cdot 4\pi r_0^2 \quad \xrightarrow{3 \text{ comes from } 2+1} \quad \boxed{\frac{Nm}{V} \cdot \vec{C}^2 = 3p} \quad \boxed{\frac{p}{p} = \frac{1}{3} \vec{C}_2}$$

ONLY VALID
FOR MONOATOMIC
GASES

TRANSLATIONAL KINETIC ENERGY

$$C_T = \frac{1}{2} \vec{C}^2 \quad e = e_T = \frac{3}{2} RT \quad \xrightarrow{\frac{1}{3} \vec{C}_2 \text{ must be equal to } RT}$$

$$C_T = \frac{1}{2} (\vec{C_x}^2 + \vec{C_y}^2 + \vec{C_z}^2)$$

$$\left[C_P = \frac{\partial h}{\partial T} \Big|_p = \frac{\partial (e + \frac{p}{s})}{\partial T} = \frac{\partial (e + RT)}{\partial T} = C_V + R \right]$$

$$C_V = \frac{3}{2} R$$

$$C_P = \frac{5}{2} R$$

$$\gamma = \frac{C_P}{C_V} = \frac{5}{3} = 1.66$$

$$C_P = C_V + R$$

DIATOMIC GAS $\rightarrow n_{\text{dof}} = 5$

HYPOTHESIS - EQUIPARTITION OF ENERGY

$$C = e_T + e_R \longrightarrow 2 \text{dof} \cdot \frac{1}{2} RT$$

$\hookrightarrow 3 \text{ dof} \cdot \frac{1}{2} RT$

$$e = n_{\text{dof}} \cdot \frac{1}{2} RT$$

$$C_P = \frac{n}{2} R$$

$$C_P = \frac{n+2}{2} R$$

$$\gamma = \frac{n+2}{n}$$

TRIATOMIC GAS

$n_{\text{dof}} = 6$, use above relationship.

LIMITS FOR DOF

High Temperature adds more degrees of freedom

$$C = e_T + e_R + e_V + e_E + \dots$$

become important after 600 K

High Pressures (low temperatures)

$$V = \frac{RT}{P} \quad \left. \begin{aligned} P \uparrow V &= 0 \\ T \downarrow V &= 0 \end{aligned} \right\} \text{ NOT POSSIBLE } \quad \text{this goes to critical point.}$$

VAN DER WAALS EOS

$$(P + \frac{C}{V^2})(V + b) = RT$$

↓ interactions between molecules. ↓ volume of the molecules

accounts for volume of molecules and its interactions.

AIR at

$$1\text{K} \rightarrow \frac{C_v}{R} = -\frac{3}{2}$$

$$3-600\text{ K} \rightarrow \frac{C_v}{R} = -1.4 \rightarrow \boxed{Y = 1.4}$$

$$2000\text{ K} \rightarrow \frac{C_v}{R} = -\frac{7}{2}$$

$\left. \begin{array}{c} C_v \\ R \end{array} \right\}$ increases with temperature.

translational
trans + rotational
trans + rot + vibration

AIR PROPERTIES

$$\left. \begin{array}{l} 21\% \text{ O}_2 \rightarrow \mu_o = 16 \text{ g/mol} \\ 78\% \text{ N}_2 \rightarrow \mu_n = 28 \text{ g/mol} \\ 1\% \text{ Ar} \rightarrow \mu_A = 39.9 \text{ g/mol} \end{array} \right\} M_{\text{air}} = 28.96 \text{ g/mol} \quad R_{\text{air}} = \frac{R}{M_{\text{air}}} = 287 \text{ J/kg K}$$

DIATOMIC MOLECULES SO $\rightarrow n = 5$

$$C_v = \frac{5}{2}R = 717.7 \text{ J/kg K}$$

$$C_p = \frac{7}{2}R = 1004.8 \text{ J/kg K}$$

SPEED OF SOUND

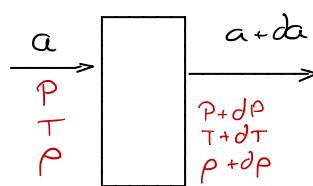
kinetic energy \vec{C}^2

$$\text{velocity} = \sqrt{\vec{C}^2} > |\vec{C}| > a \rightarrow \sqrt{\frac{8RT}{n}}$$

its not only moving but also colliding

SOUND WAVE:

Follow soundwave as it moves. Flow is moving towards us in the front of the sound wave and moving away behind the sound wave.



CONTINUITY ①

$$\rho a = (\rho + dp)(a + da)$$

$$a = -\rho \frac{da}{dp}$$

MOMENTUM ②

$$\rho + \rho a^2 = (\rho + dp) + (\rho + dp)(a + da)^2$$

$$dp = -2\rho a da - a^2 dp$$

$$\frac{da}{dp} = -\frac{a^2}{2\rho a} - \frac{1}{2\rho a} \cdot \frac{dp}{da}$$

COMBINING ① ②

$$a = \sqrt{\left(\frac{dp}{dp}\right)_s} \rightarrow \text{ISOTROPIC CHANGE OF STATE} \rightarrow \frac{P_1}{P_2} = \left(\frac{\rho_1}{\rho_2}\right)^\gamma \rightarrow \frac{P}{\rho} = \text{constant}$$

$$\frac{dp}{dp} = \frac{d}{dp}(C_P^\gamma) = \gamma C_P^{\gamma-1}$$

$$\frac{dp}{dp} = \frac{\gamma P}{\rho} = \gamma RT$$

$$a = \sqrt{\gamma RT}$$

COMPRESSIBILITY

$$\tau = -\frac{1}{v} \cdot \frac{\partial v}{\partial p} \Big|_s = -\rho \cdot \frac{\partial \frac{1}{p}}{\partial p} = -\rho \left[\frac{0 - \frac{\partial p}{\partial p} \Big|_s}{p^2} \right]$$

$$\tau = \frac{1}{\rho a^2}$$

The lower the compressibility the higher the speed of sound.

MACH NUMBER

$$M = \frac{V}{a} = \frac{\text{convective speed}}{\text{sound prop. speed}}$$

$$M \rightarrow \frac{\text{ordered motion}}{\text{internal energy.}} = \frac{\frac{V^2}{2}}{e} = \frac{\frac{V^2}{2}}{C_v T} = \frac{Y(Y-1)}{2} M^2$$

kinetic energy
molecular random motion

ENERGY EQUATION

Adiabatic flows: no heat added or taken.

$$H = h_0 = h + \frac{1}{2} V^2 \rightarrow \text{constant through the flow.}$$

$$C_p \cdot T_0 = C_p \cdot T + \frac{1}{2} V^2 \rightarrow \text{write in terms of velocity.}$$

$$a = \sqrt{Y \cdot R \cdot T}$$

$$\frac{C_p}{YR} \cdot a_0^2 = \frac{C_p}{YR} a^2 + \frac{V^2}{2}$$

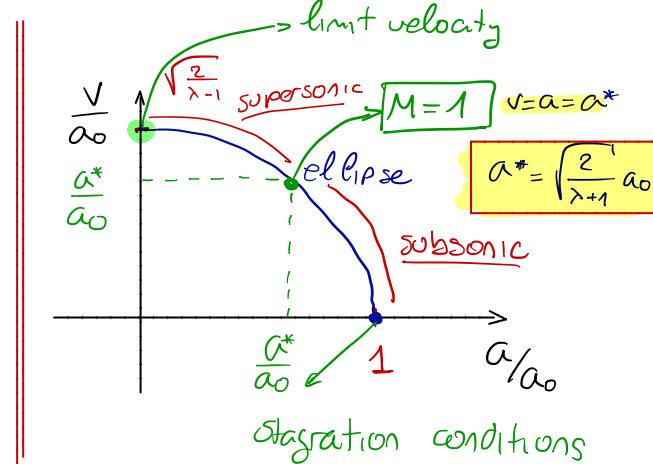
$$C_p = \frac{YR}{Y-1} \rightarrow \frac{a_0^2}{Y-1} = \frac{a^2}{Y-1} + \frac{V^2}{2}$$

internal work energy kinetic energy

LIMIT VELOCITY:

$$V_{\text{limit}} = a_0 \sqrt{\frac{2}{Y-1}}$$

$$V_{\text{limit}} = \sqrt{2 C_p T_0}$$



LIMIT MACH:

$$M \Big|_{V \rightarrow V_{\text{limit}}} = \frac{V_{\text{limit}}}{a_{\text{limit}}} \rightarrow \infty$$

a^* , a_0 and V_{lim} are constant through the flow

ISENTROPIC RELATIONS

Using T_0, P_0, ρ_0

$$\frac{T_0}{T} = 1 + \frac{Y-1}{2} M^2$$

$$\frac{P_0}{P} = \left(1 + \frac{Y-1}{2} M^2 \right)^{\frac{Y}{Y-1}}$$

$$\frac{\rho_0}{\rho} = \left(1 + \frac{Y-1}{2} M^2 \right)^{\frac{1}{Y-1}}$$

CONCORDE SKIN TEMPERATURES

What is the temperature of the nose?

$$M = 2.06 \quad h = 16 \text{ km} \quad T = -56.5^\circ\text{C}$$

$$\frac{T_0}{T} = 1 + \frac{\gamma-1}{2} M^2 = 1 + 0.2 \cdot (2.06)^2 = 1.85 \quad T_0 = 1.85 \cdot 216.7 = 400 \text{ K} = 128^\circ\text{C}$$

SONIC CONDITIONS

$$\frac{T^*}{T_0} = \frac{2}{\gamma+1} \quad \left| \quad \frac{P^*}{P_0} = \left(\frac{2}{\gamma+1} \right)^{\frac{1}{\gamma-1}} \quad \left| \quad \frac{P^*}{P_0} = \left(\frac{2}{\gamma+1} \right)^{\frac{\gamma}{\gamma-1}}$$

$$(M^*)^2 = \frac{(\gamma+1) M^2}{2 + (\gamma-1) M^2}$$

$$M^* = \frac{V}{a^*}$$

Relation between M and M^*

$$\frac{a^2}{\gamma-1} + \frac{u^2}{2} = \frac{a^{*2}}{\gamma-1} + \frac{a^{*2}}{2}$$

$$M^2 = \frac{2}{\frac{(\gamma+1)}{(M^*)^2} - (\gamma-1)}$$

$$\text{If } M = 0 \longrightarrow M^* = 0$$

$$\text{If } M < 1 \longrightarrow M^* < 1$$

$$\text{If } M = 1 \longrightarrow M^* = 1$$

$$\text{If } M > 1 \longrightarrow M^* > 1$$

$$\text{If } M \rightarrow \infty \longrightarrow M^* \rightarrow \sqrt{\frac{\gamma+1}{\gamma-1}}$$

Behaves the same way.

Relation between $\frac{P_0}{P} = \left(1 + \frac{\gamma-1}{2} M^2 \right)^{\frac{\gamma}{\gamma-1}}$ and $P_0 - P = \frac{1}{2} \rho V^2$

$$P_0 - P = P \left\{ \left(1 + \frac{\gamma-1}{2} M^2 \right)^{\frac{\gamma}{\gamma-1}} - 1 \right\}$$

$$\left[\frac{1}{2} \rho V^2 = \frac{1}{2} \rho a^2 M^2 = \frac{1}{2} \gamma P M^2 \right]$$

$$f(M) = \frac{\left(1 + \frac{\gamma-1}{2} M^2 \right)^{\frac{\gamma}{\gamma-1}} - 1}{\frac{1}{2} \gamma M^2}$$

$$\left. \begin{aligned} P_0 - P &= \frac{1}{2} \rho V^2 \cdot f(M) \\ &\text{compressibility factor} \end{aligned} \right\}$$

$$P_0 - P = \frac{1}{2} \rho V^2 \left(1 + \frac{1}{4} M^2 + \frac{1}{40} M^4 + \dots \right)$$

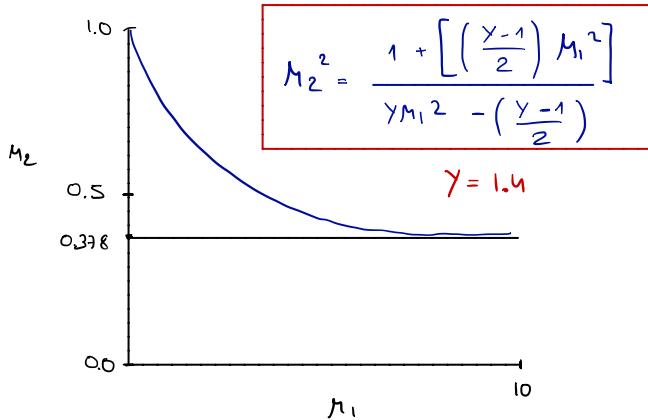
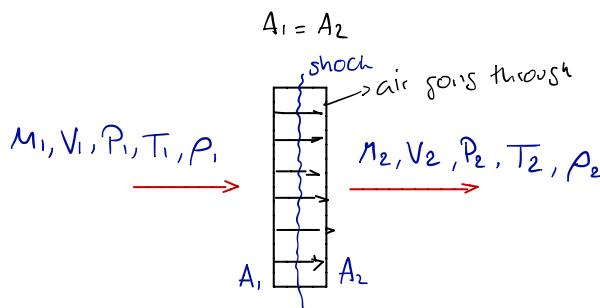
$$f(M) = 1 + \frac{1}{4} M^2 + \frac{1}{40} M^4 + \frac{1}{1660} M^6 + \dots$$

with this you can find the α_3 Mach correction.

CHAPTER 8

CALCULATION OF NSW PROPERTIES NORMAL SHOCK WAVE

Obtain ratios of the thermodynamic properties A_2/A_1 , P_2/P_1 , T_2/T_1 across a NSW.



mass conservation

$$\rho_1 u_1 = \rho_2 u_2$$

momentum

$$P_1 + \rho_1 u_1^2 = P_2 + \rho_2 u_2^2$$

energy balance

$$h_1 + \frac{u_1^2}{2} = h_2 + \frac{u_2^2}{2} : \quad \frac{Y P_1}{P_1} + \frac{Y-1}{2} u_1^2 = \frac{Y P_2}{P_2} + \frac{Y-1}{2} u_2^2$$

calorically perfect gas

- $h = C_p \cdot T$
- $P = \rho R T$ ideal gas law
- $C_p = \text{constant}$

Using continuity: amount of mass constant
 $A_1 = A_2$

$$\frac{P_2}{P_1} = \frac{u_1}{u_2} = \frac{u_1^2}{u_1 \cdot u_2} = \frac{u_1^2}{M_1^2} = M_1^{-2}$$

$$\frac{P_2}{P_1} = \frac{(Y+1) M_1^2}{2 + (Y-1) M_1^2}$$

Momentum equation: amount of momentum entering and leaving must be equal to momentum leaving and staying.

$$P_2 - P_1 = \rho_1 u_1 - \rho_2 u_2 = \rho_1 u_1 (u_1 - u_2) = \rho_1 u_1^2 \left(1 - \frac{u_2}{u_1}\right) = \rho_1 u_1^2 \left(1 - \frac{P_1}{P_2}\right)$$

$$\frac{P_2}{P_1} - \frac{P_1}{P_2} = \frac{P_1}{P_2} u_1^2 \left(1 - \frac{P_1}{P_2}\right)$$

$$\frac{P_2}{P_1} = 1 + \frac{\gamma u_1^2}{\gamma R T_1} \left(1 - \frac{P_1}{P_2}\right) = 1 + \gamma M_1^2 \left(1 - \frac{P_1}{P_2}\right)$$

$$\frac{P_2}{P_1} = 1 + \frac{2\gamma}{Y+1} (M_1^2 - 1)$$

IDEAL GAS LAW $\frac{T_2}{T_1} = \frac{P_2}{P_1} \cdot \frac{\rho_1}{\rho_2}$

$$\frac{T_2}{T_1} = \frac{h_2}{h_1} = \left[1 + \frac{2\gamma}{Y+1} (M_1^2 - 1)\right] \cdot \frac{2 + (Y-1) M_1^2}{(Y+1) M_1^2}$$

WHAT CAUSES THE SHOCK

$$\frac{u_2}{u_1} = \frac{2 + (Y-1) M_1^2}{(Y+1) M_1^2} = \frac{P_1}{P_2} \quad \begin{array}{l} \text{strength is given by} \\ M_1 \end{array}$$

$$\frac{P_2}{P_1} = 1 + \frac{2\gamma}{Y+1} (M_1^2 - 1)$$

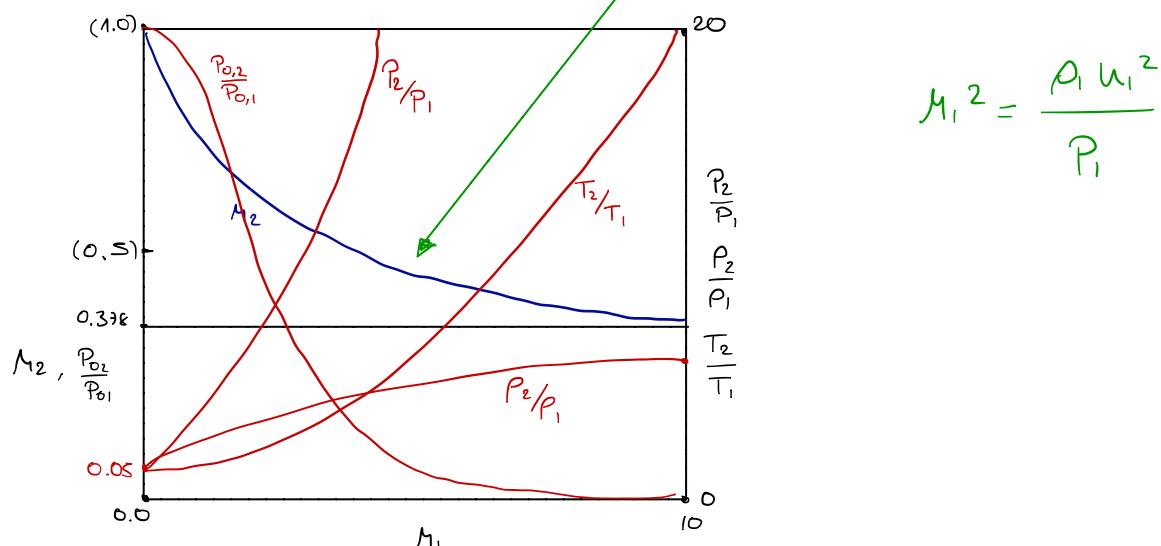
2 solutions
 boundary conditions gives the needed sol
 so sometimes we have a shock and sometimes we don't.

MACH DOWNSTREAM

$$M_2^2 = \left(\frac{u_2}{a_2} \right)^2 = \underbrace{\left(\frac{u_2}{u_1} \right)^2}_{f(M_1, \gamma)} \cdot \underbrace{\left(\frac{u_1}{a_1} \right)^2}_{M_1^2} \cdot \underbrace{\left(\frac{a_1}{a_2} \right)^2}_{\frac{T_1}{T_2}} \rightarrow f_e(M_1, \gamma) = \boxed{M_2^2 = \frac{1 + \left[\left(\frac{\gamma - 1}{2} \right) M_1^2 \right]}{\gamma M_1^2 - \left(\frac{\gamma - 1}{2} \right)}}$$

IF $M_1 \rightarrow \infty$ we find:

$$\lim_{M_1 \rightarrow \infty} M_2 = \sqrt{\frac{\gamma - 1}{2\gamma}} = 0.378 \quad \parallel \quad \lim_{M_1 \rightarrow \infty} \frac{P_2}{P_1} = \infty \quad \parallel \quad \lim_{M_1 \rightarrow \infty} \frac{P_2}{P_1} = \frac{\gamma + 1}{\gamma - 1} = 6 \quad \parallel \quad \lim_{M_1 \rightarrow \infty} \frac{T_2}{T_1} = \infty$$



PRAUDT GARDNER

$$\frac{\gamma + 1}{2(\gamma - 1)} a^{*2} = \frac{a^2}{\gamma - 1} + \frac{u^2}{2}$$

$$a^* \propto a_0 = \sqrt{\gamma R T_0}$$

$$a^* \text{ constant over NSW}$$

$$\frac{u_2}{u_1} = \frac{2 + (\gamma - 1) M_1^2}{(\gamma + 1) M_1^2} = \frac{1}{M_1^{*2}}$$

$$u_2 \cdot u_1 = \frac{u_1^2}{M_1^{*2}} = a_1^{*2} = a^{*2}$$

$$M_2^* = \frac{1}{M_1^*}$$

ENTROPY CHANGE ACROSS NSW

shocks don't occur in subsonic flows. Entropy will be higher for a shock wave, because a shock wave will increase the randomness of the particles.

$$TdS = de + pdv \longrightarrow$$

$$TdS = dh - vdp$$

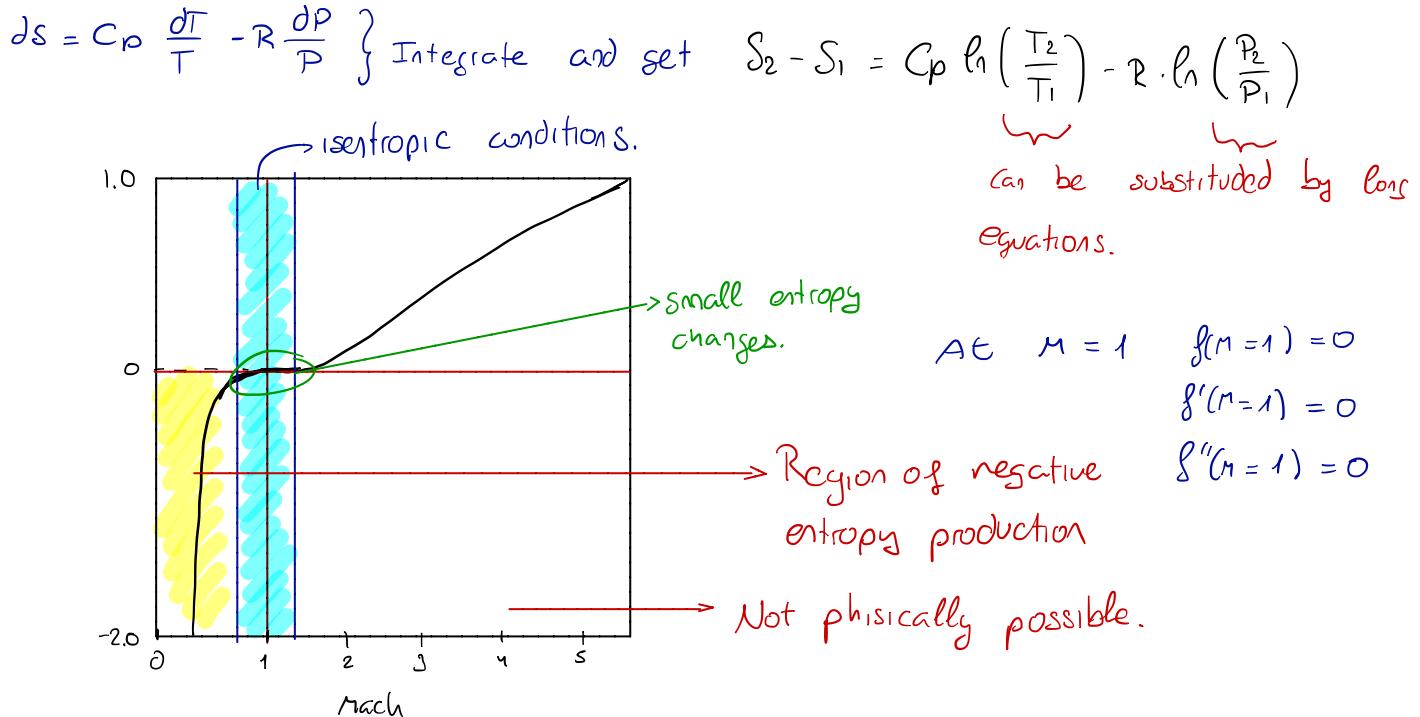
$$dh = de + d(pv) = de + pdv + vdp$$

$$v = \frac{1}{\rho} = \frac{RT}{P}$$

$$de = dh - pdv - vdp$$

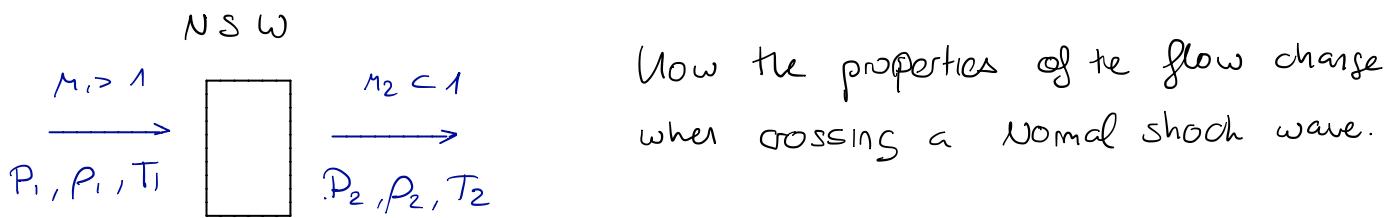
$$h = c_p T$$

ENTROPY CONTINUED



SHOCK WAVE DEFINITION: Non-equilibrium thermodynamic process

- Large velocity gradient causes viscous dissipation.
- Large temperature gradient causes heat diffusion.



TEMPERATURE

The total temperature is constant through a NSW

$$\left. \begin{aligned} Cp T_1 + \frac{u_1^2}{2} &= Cp T_{0,1} \\ Cp T_2 + \frac{u_2^2}{2} &= Cp T_{0,2} \end{aligned} \right\} T_{0,2} = T_{0,1} \quad \text{because } Cp T_1 + \frac{u_1^2}{2} = Cp T_2 + \frac{u_2^2}{2}$$

PRESSURE:

The total pressure decreases across NSW in measure that the process becomes dissipative.

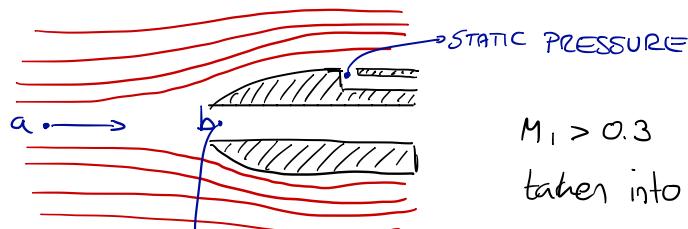
$$S_2 - S_1 = Cp \ln \frac{T_2}{T_1} - R \ln \frac{P_2}{P_1} \quad \left| \quad S_{0,2} - S_{0,1} = Cp \cdot \ln \frac{T_{0,2}}{T_{0,1}} - R \cdot \ln \frac{P_{0,2}}{P_{0,1}} \quad \Delta S = f(Y, M_1) \right.$$

$S_2 = S_{0,2} \quad S_1 = S_{0,1}$

$$S_2 - S_1 = -R \ln \left(\frac{P_{0,2}}{P_{0,1}} \right) \quad \boxed{\frac{P_{0,2}}{P_{0,1}} = f(Y, M_1)}$$

MEASUREMENT OF VELOCITY IN A COMPRESSIBLE FLOW:

The velocity can be determined through a pressure measurement.



stagnation pressure orifice.

$M_1 > 0.3$ compressibility taken into account.

} For incompressible flows

$$M < 0.3$$

$$V = \sqrt{\frac{2(P_0 - P)}{\rho}}$$

IF $\xrightarrow{\text{isentropic flow}}$

$$\frac{P_{0,1}}{P_1} = \left(1 + \frac{\gamma - 1}{2} M_{1,2} \right)^{\frac{\gamma}{\gamma-1}}$$

————— solving for M_1 ,

$$M_1 = \sqrt{\frac{2}{\gamma-1} \left[\left(\frac{P_{0,1}}{P_1} \right)^{\frac{\gamma-1}{\gamma}} - 1 \right]}$$

velocity can be obtained as

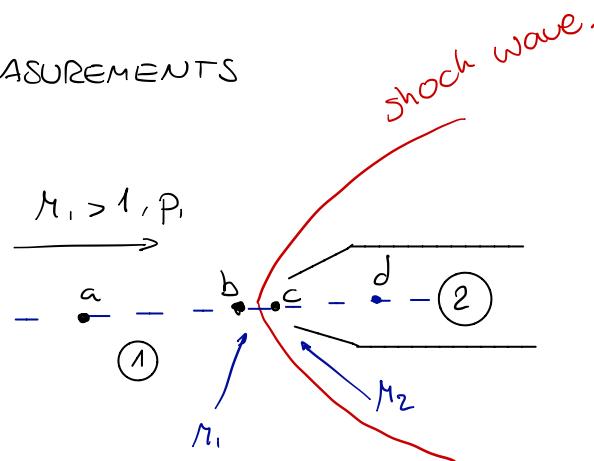
$$u_1 = M_1 \cdot a_1$$

$$u_1 = \sqrt{\frac{2a_1^2}{\gamma-1} \left[\left(\frac{P_{0,1}}{P_1} \right)^{\frac{\gamma-1}{\gamma}} - 1 \right]}$$

We need to know a_1 and T_1 .

SUPPERSONIC FLOW MEASUREMENTS

a shock wave stands before the pitot tube.



$a \rightarrow b$ the flow does not feel the probe

$b \rightarrow c$ NSW deceleration $P_{0,2} \neq P_{0,1}$ and $\frac{P_2}{P_1}^{NSW} = f(\gamma, M_1)$

$c \rightarrow d$ subsonic (isentropic deceleration)

$$\frac{P_{0,2}}{P_1} = \left(1 + \frac{\gamma-1}{2} M_2^2 \right)^{\frac{\gamma}{\gamma-1}}$$

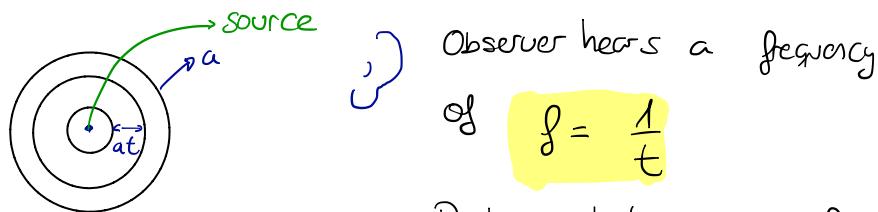
$$\boxed{\frac{P_{0,2}}{P_1} = \frac{P_{0,2}}{P_2} \cdot \frac{P_2}{P_1}}$$

RAYLEIGH PITOT FORMULA

$$\frac{P_{0,2}}{P_1} = \left[\frac{(\gamma+1)^2 M_1^2}{4\gamma M_1^2 - 2(\gamma-1)} \right]^{\frac{\gamma}{\gamma-1}} \cdot \frac{1 - \gamma + 2\gamma M_1^2}{\gamma + 1}$$

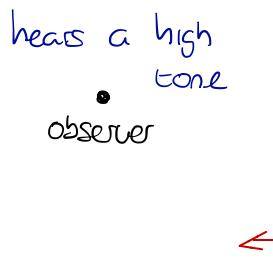
Wave angle.

Consider a source of small disturbances in a quiescent medium.



Distance between wavefront: $a \cdot t$

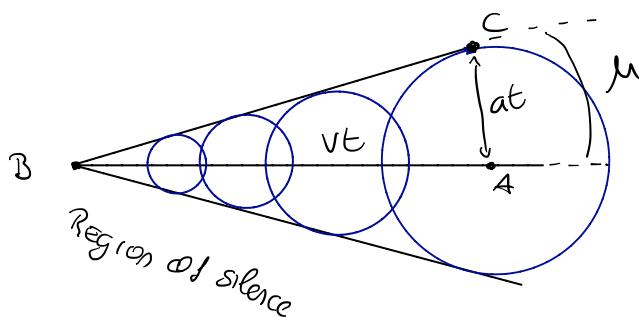
Consider the source in motion. \rightarrow Waves are not concentric anymore.



Doppler effect: difference in perceived frequency.

If $v < a$ the source is always inside the circles

Consider source moving faster than speed of sound.



$$\sin \mu = \frac{at}{vt} = \frac{a}{v} = \frac{1}{M}$$

When the source moves from

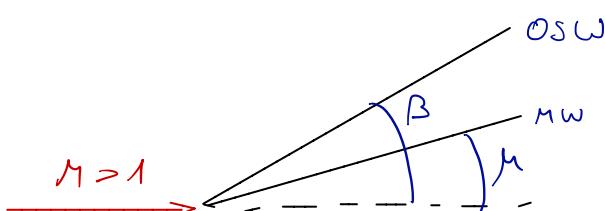
$A \rightarrow B$

the sound wave traveled from

$A \rightarrow C$

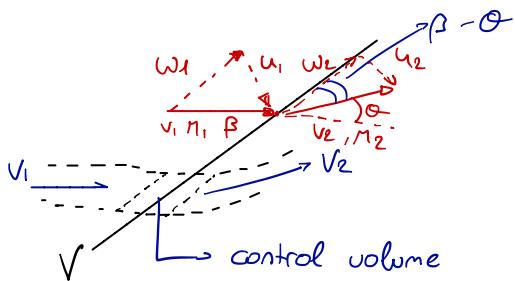
$$\mu = \arcsin \left(\frac{1}{M} \right)$$

DISTURBANCES STRONGER THAN SOUND



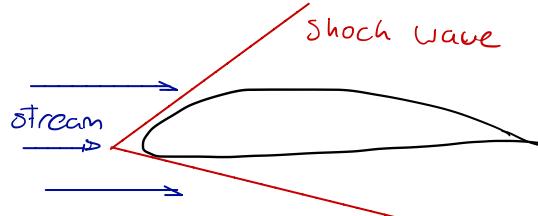
Shock wave angle: β } $\beta \geq \mu$
Mach wave angle: μ

OBLIQUE SHOCK RELATIONS



For a NSW the shock wave is perpendicular to the flow stream

This is an oblique shock and happens for example when.



INTRODUCING THE MACH RELATIVE TO VELOCITY COMPONENTS

$$M_1 = \frac{w_1}{a_1} \quad ; \quad M_{t2} = \frac{w_2}{a_2} \quad || \quad w_1 = V_1 \sin \beta \quad u_2 = V_2 \sin (\beta - \theta)$$

$$M_{n1} = \frac{u_1}{a_1} = \frac{V_1}{a_1} \sin \beta = M_1 \sin \beta$$

$$M_{n2} = M_2 \sin (\beta - \theta)$$

EQUATIONS FOR OSW

MOMENTUM:

tangential component

$$\int_s (\rho \vec{v} \cdot d\vec{s}) \omega = - \int_s (\rho \cdot ds)_{\text{tangential}}$$

But $d\vec{s}$ is perpendicular to the control surface

$(\rho ds)_{\text{tan}}$ over the inlet and outlet surfaces is 0

$$-(\rho_1 A_1 u_1) \omega_1 + (\rho_2 A_2 u_2) \omega_2 = 0$$

$$A_1 = A_2 \quad \rho_1 u_1 = \rho_2 u_2$$

$$\boxed{\omega_1 = \omega_2}$$

CONTINUITY:

$$\rho_1 V_1 \sin \beta = \rho_2 V_2 \sin (\beta - \theta)$$

$$\rho_1 u_1 = \rho_2 u_2$$

normal component

$$\int_s (\rho \vec{v} \cdot d\vec{s}) n = - \int_s \rho ds$$

$$-\rho_1 u_1 A_1 u_1 + \rho_2 u_2 A_2 u_2 = -(-P_1 A_1 + P_2 A_2)$$

$$\rho_1 + \rho_1 u_1^2 = \rho_2 + \rho_2 u_2^2$$

$$\boxed{P + \rho u^2 = \text{constant}}$$

ENERGY EQUATION:

$$\int_s \rho \left(e + \frac{v^2}{2} \right) \vec{v} \cdot d\vec{s} = - \int_s p \vec{v} \cdot d\vec{s}$$

$$A_1 = A_2$$

$$-\rho_1 \left(e_1 + \frac{v_1^2}{2} \right) u_1 A_1 + \rho_2 \left(e_2 + \frac{v_2^2}{2} \right) u_2 A_2 = -(-\rho_1 u_1 A_1 + \rho_2 u_2 A_2)$$

$$\cancel{\rho_1 u_1 \left(e + \frac{\rho_1}{\rho_1} + \frac{v_1^2}{2} \right)} = \cancel{\rho_2 u_2 \left(e_2 + \frac{\rho_2}{\rho_2} + \frac{v_2^2}{2} \right)} \rightarrow h_1 + \frac{v_1^2}{2} = h_2 + \frac{v_2^2}{2}$$

$\boxed{V^2 = U^2 + W^2}$

$$h_1 + \frac{u_1^2 + w_1^2}{2} = h_2 + \frac{u_2^2 + w_2^2}{2}$$

$$\boxed{h + \frac{U^2}{2} = \text{constant}}$$

SAME RELATIONS AS IN NSW

$$M_{n,2} = \frac{1 + \frac{\gamma-1}{2} M_{n,1}^2}{\gamma M_{n,1}^2 - \frac{\gamma-1}{2}} \quad M_{n,2} = f(\gamma, M_{n,1}) \quad M_{n,2} = f(\gamma, M_1, \beta)$$

$$\frac{P_2}{P_1} = \frac{(\gamma+1) M_{n,1}^2}{2 + (\gamma-1) M_{n,1}^2} \rightarrow f(\gamma, M_1, \beta) \quad \left. \begin{array}{l} M_2 = \frac{M_{n,2}}{\sin(\beta - \Theta)} \\ M_2 = f(\gamma, M_1, \beta, \Theta) \end{array} \right\}$$

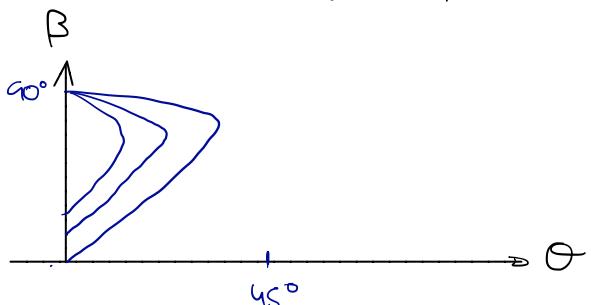
$$\tan \beta = \frac{u_1}{w_1} \quad \tan(\beta - \Theta) = \frac{u_2}{w_2}$$

Θ is not a variable, from geometry.

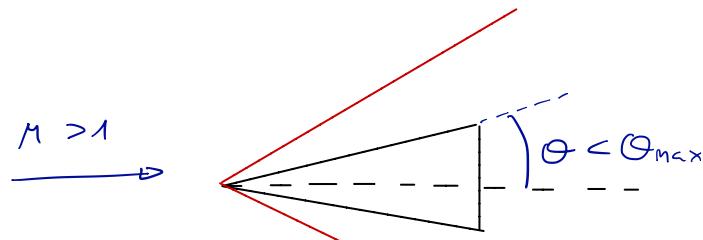
$$\frac{\tan(\beta - \Theta)}{\tan(\beta)} = \frac{u_2}{u_1} = \frac{\rho_1}{\rho_2} = f(\gamma, M_1, \beta) \quad M - \beta - \Theta \text{ relation}$$

$$\tan \Theta = 2 \cot(\beta) \frac{M_1^2 \sin^2 \beta - 1}{M_1^2 (\gamma \cos(\beta)) + 2}$$

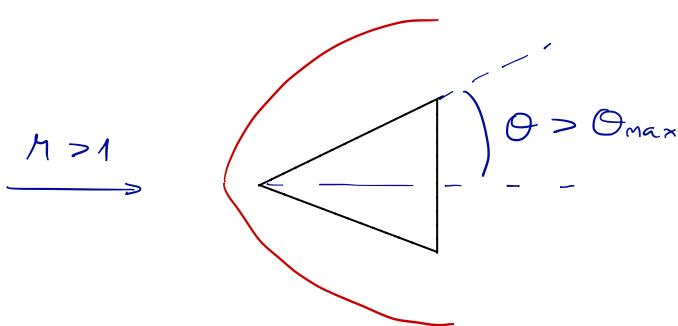
$$\left. \begin{array}{l} \Theta = f(\gamma, M_1, \beta) \\ M_2 = f(\gamma, M_1, \beta) \end{array} \right\} \text{GRAPH } \Theta - \beta$$



CONSIDERATIONS M- β - Θ RELATION



If $\theta > \theta_{\max} \rightarrow$ detached shock
locally the shock becomes normal.

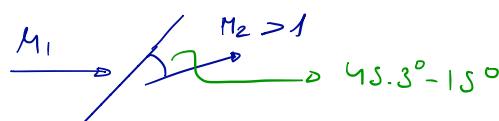


θ_{\max} increases with the mach number

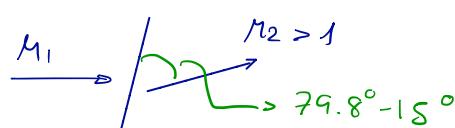
For any given couple M_1, θ with $\theta < \theta_{\max}$ there are two possible solutions

EXAMPLE: $M_1 = 2.0 \quad \theta = 15^\circ \rightarrow \begin{cases} \beta_1 = 45.3^\circ \\ \beta_2 = 79.8^\circ \end{cases}$

β_1 is a weak shock:



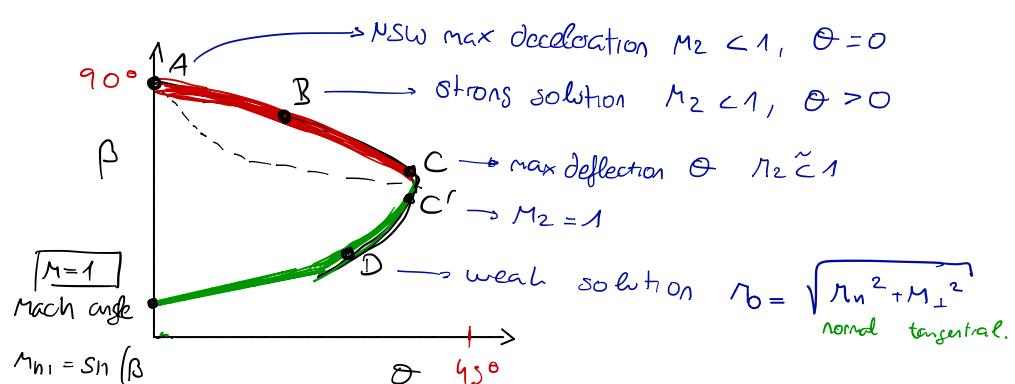
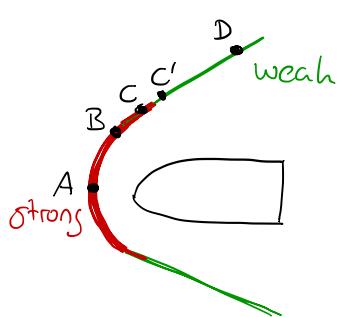
β_2 is a strong shock:



If $\theta = 0^\circ \rightarrow$:

- stronger possible SW $\beta = 90^\circ$
- weakest: (mach wave) $\beta = 0^\circ$

DETACHED SW IN FRONT OF BLUNT BODY

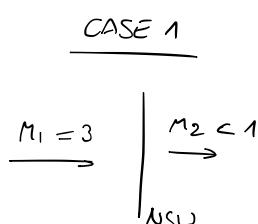


EXAMPLE SUPERSONIC INLET

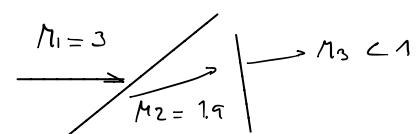
- A Mach 3 flow is to be decelerated to subsonic regime (prior to combustion)
- 2 ways of deceleration

→ NSW

→ OSW + NSW



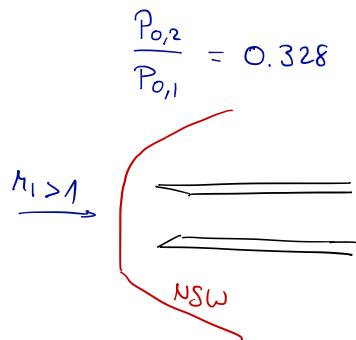
CASE 2



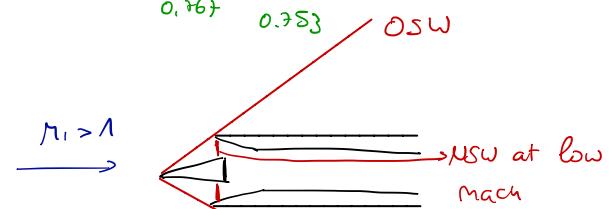
COMPARISON

$$\left(\frac{P_{0,3}}{P_{0,1}} \right)_2 = 1.76$$

$$\left(\frac{P_{0,3}}{P_{0,1}} \right)_1 = 0.328$$

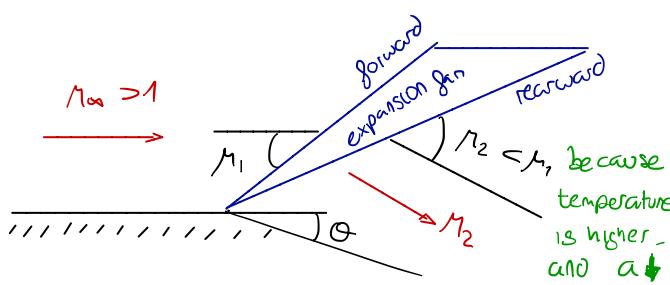


$$\left(\frac{P_{0,3}}{P_{0,1}} \right)_1 = \underbrace{\frac{P_{0,3}}{P_{0,2}}}_{0.767} \cdot \underbrace{\frac{P_{0,2}}{P_{0,1}}}_{0.753} = 0.678$$



HIGHER DECELERATION EFFICIENCY → HIGHER ENGINE THRUST

PRANDTL-MEYER EXPANSION



supersonic stream

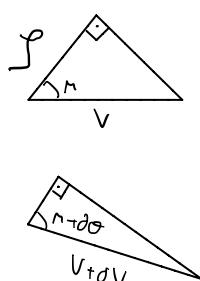
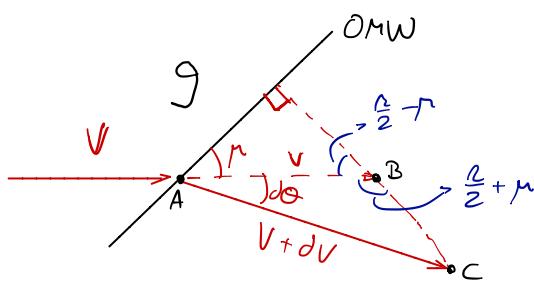
expansion fan: an infinite number of Mach waves making continuous region

Since the expansion is made out of Mach waves $dS = 0$ (isentropic)

PROBLEM STATEMENT

DETACHED NORMAL SHOCK WAVE HAPPENS WHEN θ IS greater than θ_{max}

Determine conditions (2) from conditions (1) and deflection θ



$$\frac{V + dV}{V} = \frac{\sin(\frac{\pi}{2} + \mu)}{\sin(\frac{\pi}{2} - \mu - d\alpha)}$$

$$J = (U + dV) \cos(\mu + d\alpha)$$

Derive:

$$\sin\left(\frac{\pi}{2} + \mu\right) = \cos\left(\frac{\pi}{2} - \mu\right) = \cos\mu$$

$$\sin\left(\frac{\pi}{2} - \mu - d\alpha\right) = \cos(\mu + d\alpha) = \cos\mu \cos d\alpha - \sin\mu \sin d\alpha$$

$$1 + \frac{dV}{V} = \frac{\cos\mu}{\cos\mu \cos d\alpha - \sin\mu \sin d\alpha}$$

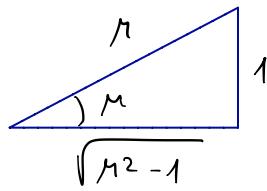
HYPOTHESIS:

$$d\alpha \ll 1$$

$$\begin{cases} \sin d\alpha = d\alpha \\ \cos d\alpha = 1 \end{cases}$$

$$1 + \frac{dV}{V} = \frac{\cos \mu}{\cos \mu - d\theta \sin \mu} = \frac{1}{1 - d\theta \tan \mu} \quad \text{Expand around } d\theta = 0 \text{ so we get}$$

$$1 + \frac{dV}{V} = 1 + d\theta \tan \mu \quad \text{or} \quad d\theta = \frac{dV/V}{\tan \mu}$$



$$\tan \mu = \frac{1}{\sqrt{M^2 - 1}}$$

Therefore

$$d\theta = \sqrt{M^2 - 1} \frac{dV}{V}$$

$$\left. \begin{array}{l} M > 1 \\ d\theta > 0 \\ dV > 0 \end{array} \right\}$$

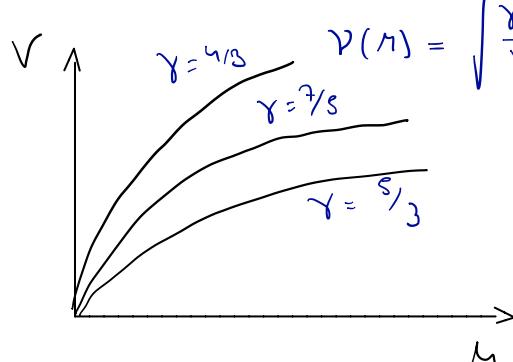
3Y DIFFERENTIATION AND MANIPULATION

$$\frac{da}{a} = -\frac{\gamma-1}{2} M \left(1 + \frac{\gamma-1}{2} M^2\right)^{-1} dM$$

$$\frac{dV}{V} = \frac{1}{1 + \frac{\gamma-1}{2} M^2} \cdot \frac{dM}{M}$$

$$\Theta = V(M) = \int_{M_1}^{M_2} \frac{\sqrt{M^2 - 1}}{1 + \frac{\gamma-1}{2} M^2} \cdot \frac{dM}{M}$$

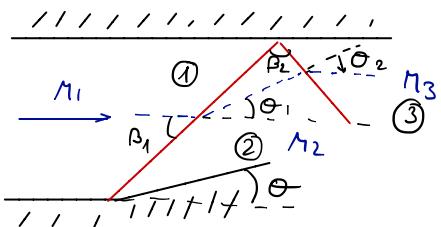
→ INTEGRATING



$$\Theta = VM_2 - VM_1$$

can be found given that
 $V(M=1) = 0$

SHOCK INTERACTIONS / REFLECTIONS

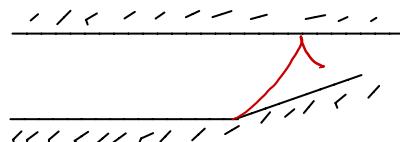


$$\begin{aligned} \theta_1 &= \theta \\ \theta_2 &= -\theta_1 \end{aligned}$$

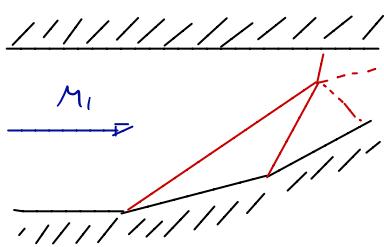
The flow after the reflection must be parallel to the top wall

If M_1 is only slightly above the minimum for a straight OSW at given Θ . The first shock may exist but the second is not possible. This situation creates the

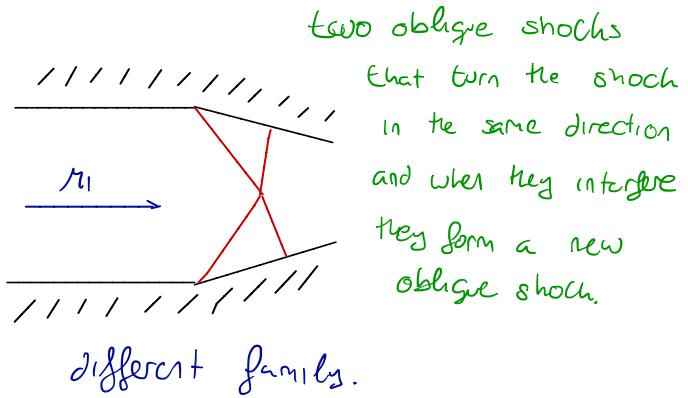
λ shock



SHOCK-SHOCK INTERACTION



Same family

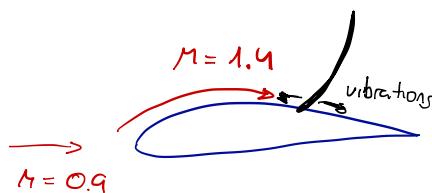


different family.

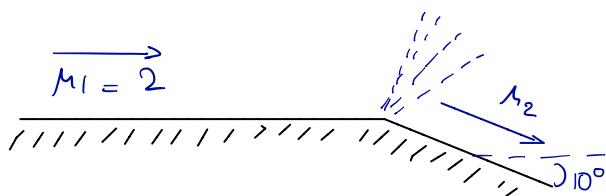
TOTAL PRESSURE LOSSES

APPLICATIONS

- supersonic inlet
- swept wings



EXPANSION FAN EXAMPLE



$$\gamma = 1.4 \quad \Theta = \gamma(M_2) - \gamma(M_1)$$

$$\gamma(M_1) = 26.38^\circ$$

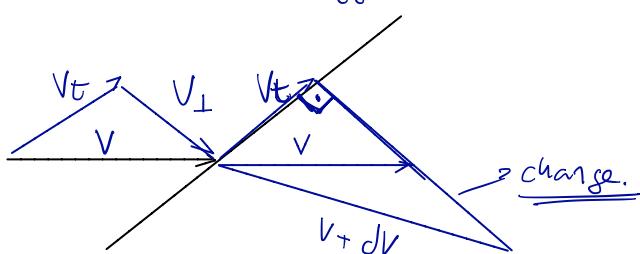
$$\Theta = 10 + 26.38^\circ = 36.38 - \gamma(M_2)$$

iterate $\rightarrow M_2 = 2.4$

$$\text{Pressure: } \frac{P_0}{P} = \left(1 + \frac{\gamma-1}{2} M^2\right)^{\frac{\gamma}{\gamma-1}}$$

$$\frac{P_2}{P_1} = \left(\frac{1 + \frac{\gamma-1}{2} M_1^2}{1 + \frac{\gamma-1}{2} M_2^2} \right)^{\frac{\gamma}{\gamma-1}} = 0.55$$

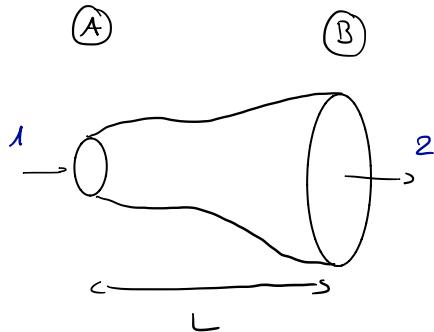
Obligee waves
don't modify tangential velocity



CHAPTER 10 COMPRESSIBLE FLOWS THROUGH NOZZLES

Nozzle: converts potential/internal energy into kinetic energy. $u \uparrow P \downarrow$

Diffuser: converts kinetic energy into potential energy $u \downarrow P \uparrow$



$$A : A(x)$$

$$u(x)$$

$$P(x)$$

$$M(x)$$

Assume

- Steady flow $\frac{\partial}{\partial t} = 0$

- Inviscid

- Adiabatic

- Quasi one dimensional $u = u(x)$ large \rightarrow neglect the others.

$$\hookrightarrow A(x) = A$$

$$\frac{dA}{dx} \ll \frac{L}{A}$$

wire section varies smoothly.

CONTINUITY EQUATION

$$\rho_1 A_1 \cdot u_1 = \rho_2 A_2 u_2$$

$$\rho \cdot A \cdot u = \text{constant}$$

$$\textcircled{1} \quad d(\rho A \cdot u) = 0$$

$$\textcircled{2} \quad u \cdot A \cdot d\rho + u \cdot dA \cdot \rho + du \cdot A \cdot \rho = 0$$

$$\textcircled{3} \quad \frac{d\rho}{\rho} + \frac{dA}{A} + \frac{du}{u} = 0$$

$$\textcircled{4} \quad u^2 A d\rho + u^2 dA \rho + du \cdot u \cdot A \cdot \rho = 0$$

MOMENTUM EQUATION

$$A_1 P_1 + \rho_1 u_1^2 A_1 + \int_{A_1}^{A_2} P dA = A_2 P_2 + \rho_2 u_2^2 A_2$$

forces acting on wall.

$$\begin{aligned} A_1 P_1 + P_1 \cdot u_1^2 \cdot A_1 + P_1 \cdot dA &= (P + dP)(A + dA) \\ &\quad + (P + dP)(u + du)^2 + (A + dA) \\ &\quad u^2 + 2u du + du^2 \end{aligned}$$

$$A dP + 4u^2 d\rho + \rho u^2 dA + \boxed{2\rho u A du = 0}$$

Compare with $\textcircled{4}$ only the 2 is different.

ENERGY EQUATION

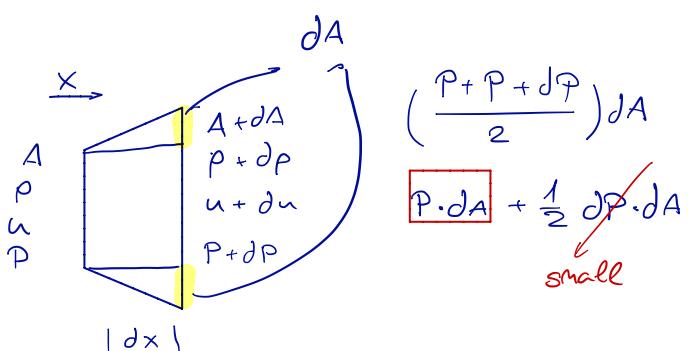
$$\text{total enthalpy} = \text{constant} = h + \frac{u^2}{2}$$

$$h_1 + \frac{u_1^2}{2} = h_2 + \frac{u_2^2}{2}$$

$$A dP + \rho u A du = 0$$

$$\boxed{dP = -\rho u du}$$

EULER'S EQUATION



$$\frac{dP}{\rho} = -u du \quad \left. \begin{array}{l} a^2 = \frac{\partial P}{\partial \rho} \rightarrow a^2 \cdot \frac{d\rho}{\rho} = -u du \\ \frac{dP}{\rho} \cdot \frac{d\rho}{\rho} = -u du \end{array} \right\}$$

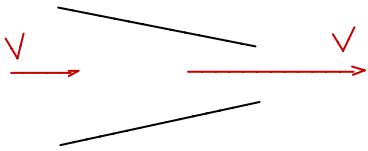
$$\frac{dp}{\rho} = -\frac{u^2}{a^2} \frac{du}{u} = -M^2 \frac{du}{u}$$

From eq(3) $-\frac{du}{u} - \frac{dA}{A} = -M^2 \cdot \frac{du}{u}$ AREA-VELOCITY RELATION

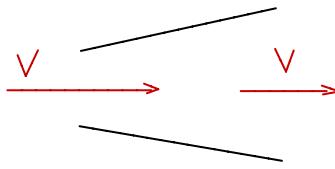
$$\frac{dA}{A} = (M^2 - 1) \frac{du}{u}$$

CONSEQUENCES OF $\frac{dA}{A} = (M^2 - 1) \frac{du}{u}$

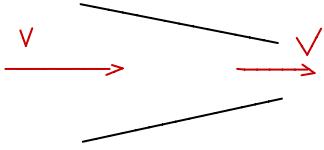
- $M < 1 \quad dA < 0$



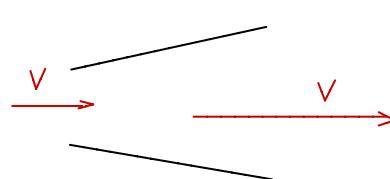
- $M < 1 \quad dA > 0$



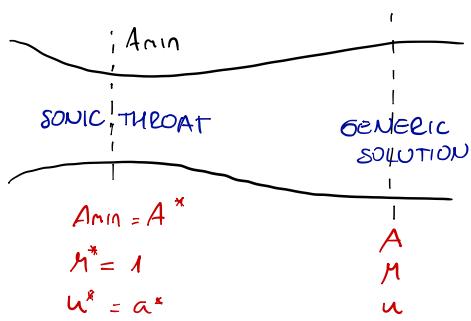
- $M > 1 \quad dA < 0$



- $M > 1 \quad dA > 0$



NOZZLE FLOWS: determine relation starting from the Velocity-Area relation.



FROM CONTINUITY:

$$\rho^* u^* A^* = \rho u A$$

$$\frac{A}{A^*} = \frac{\rho^* u^*}{\rho u} = \frac{\rho^* a^*}{\rho u} = \frac{[\rho^* | p_0 | a^*]}{[\rho_0 | p | u]}$$

$$\frac{\rho^*}{\rho_0} = \left(\frac{2}{\gamma + 1} \right)^{\frac{1}{\gamma-1}}$$

$$\frac{a^*}{u} = \frac{1}{M^*}$$

$$\frac{\rho_0}{\rho} = \left(1 + \frac{\gamma-1}{2} M^2 \right)^{\frac{1}{\gamma-1}}$$

$$(M^*)^2 = \frac{(\gamma+1) M^2}{2 + (\gamma-1) M^2}$$

$$\left(\frac{A}{A^*} \right)^2 = \frac{1}{M^2} \left[\frac{2}{\gamma+1} \left(1 + \frac{\gamma-1}{2} M^2 \right) \right]^{\frac{\gamma+1}{\gamma-1}}$$

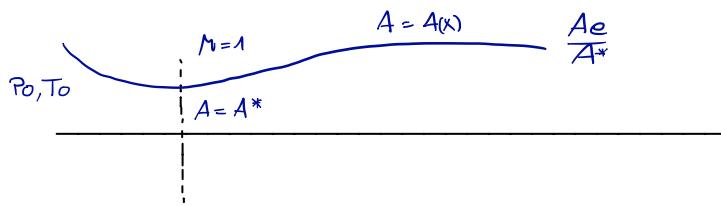
$$M = M \left(\frac{A}{A^*} \right) \quad \frac{A}{A^*} = f(M)$$

$$\left\{ \begin{array}{l} 1.) M < 1 \\ 2.) M > 1 \end{array} \right\}$$

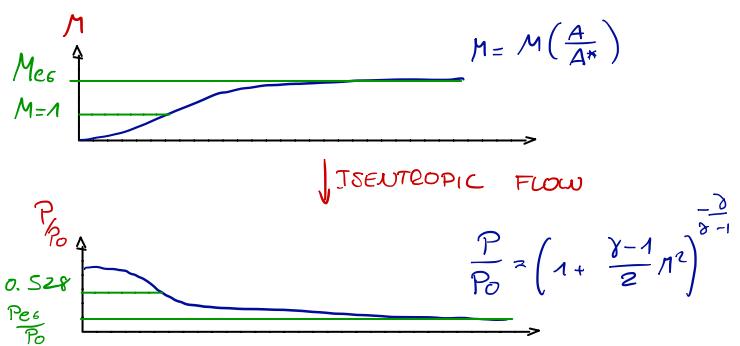
solution depends on boundary condition:
pressure ratio across the nozzle.

look into the table for IF $\rightarrow \frac{A}{A^*} = 2$ M = 0.31 M = 2.2

CONSIDER A LAVAL NOZZLE



ASSUMING SUPERSONIC EXIT



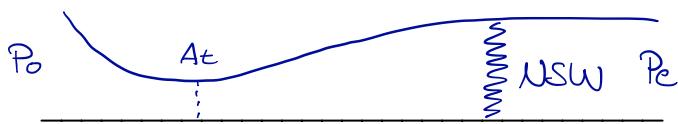
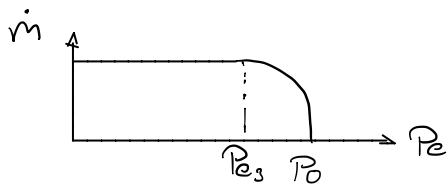
→ In an isentropic flow P_e must be the same P_{e3}

→ If $P_e \neq P_{e3}$

When $P_e = P_{e3} \rightarrow A_t = A^*$

$$\dot{m} = \rho^* u^* A^* = \rho^* u^* A_t$$

If $P_e < P_{e3} \rightarrow$ still the throat conditions are sonic \dot{m} is fixed → choked mass flow regime.

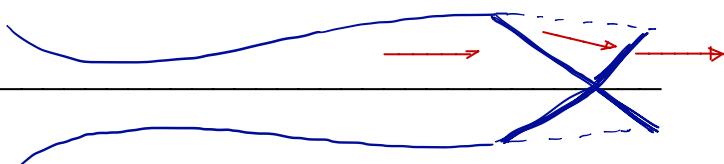


When P_e further decreases:

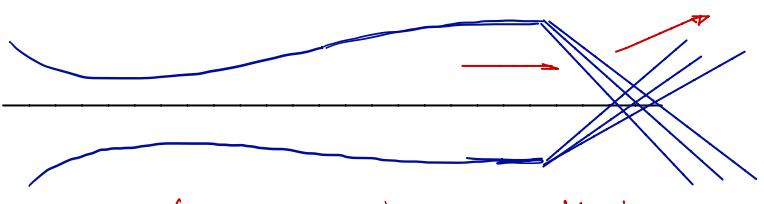
→ NSW travels downstream

We call P_{es} the pressure where a NSW is placed at the nozzle exit.

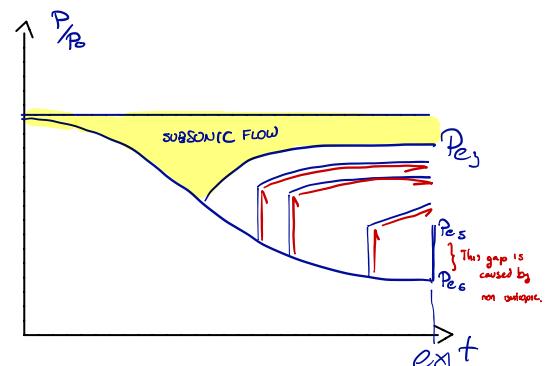
- If $P_e < P_e < P_{es}$ a NSW is too strong and OSW appear. over-expanded flow regime.



- If $P_e < P_{es}$ the flow needs to expand further to adapt the pressure Prandtl-Meyer expansion fans appear. under-expanded flow regime.

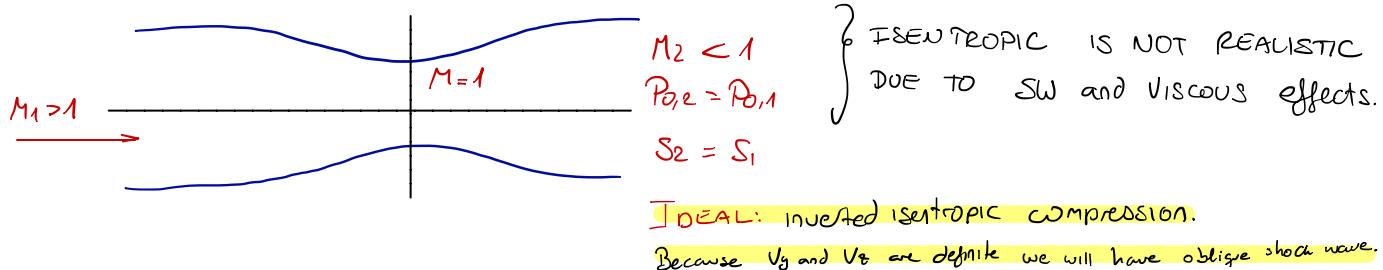


This is caused to accommodate the pressure of the jet to the ambient pressure.

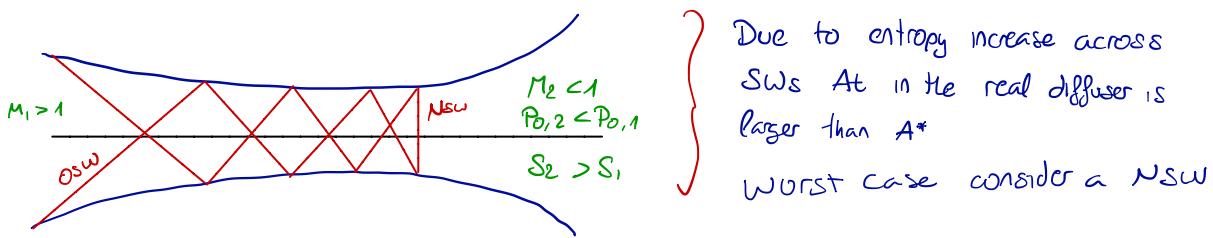


DIFFUSERS

- Any duct designed to slow down the flow to lower velocity is a diffuser.
 - The objective of the application of diffusers is to recover as high as possible total pressure in the stream.
- The ideal diffuser performs an isentropic compression. $A_s = 0 \rightarrow P_{o,2} = P_{o,1}$



ACTUAL SUPERSONIC DIFFUSER



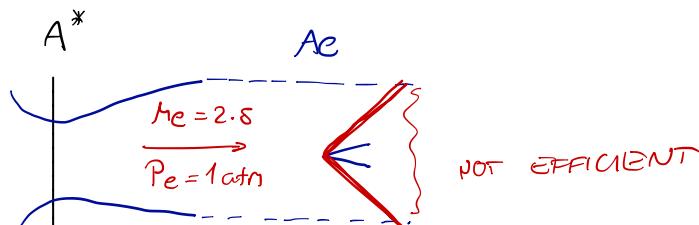
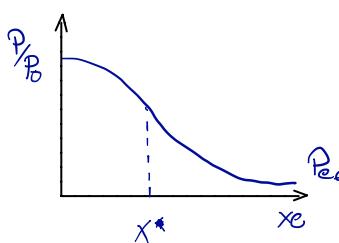
SUPERSONIC WIND TUNNELS

Objective: generate a uniform supersonic stream in a laboratory

E.g. $M = 2.5$

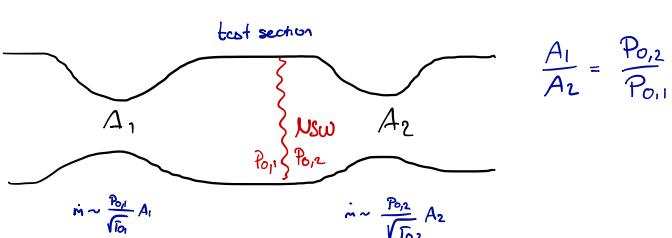
→ 1st choice:

Take a convergent-divergent nozzle with $\frac{A_e}{A^*} = 2.69$. Establish $\frac{P_o}{P_e} = 17.1$ to exit in the ambient at P_e .

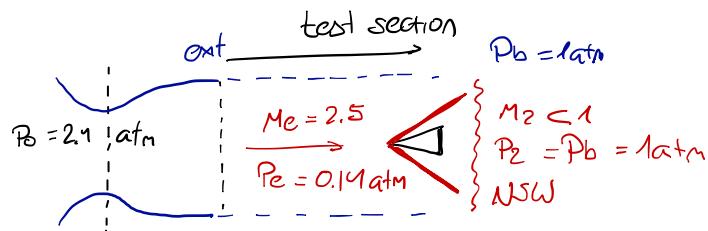


CONSEQUENCES

- need for air storage at $P_o > 17 \text{ atm}$
- large mass flow $\dot{m} = \rho^* u^* A^*$



→ 2nd CHOICE



The nozzle exhaust into a constant area duct.

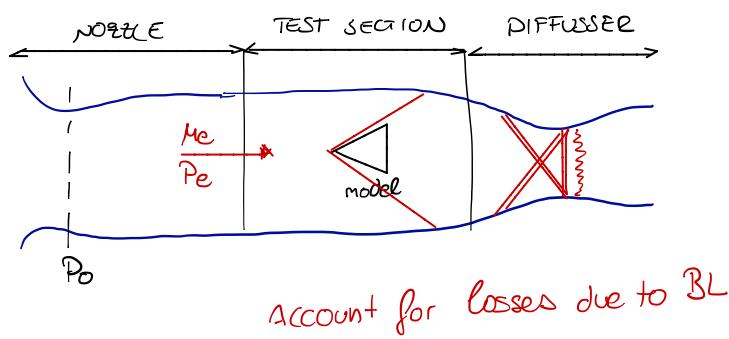
Flow terminates with a NSW

CONSEQUENCES:

- $P_0 = 2.1$ needed reduction in mass flow.

- NSW acts as a diffuser low efficiency & deceleration.

→ 3rd CHOICE: JAVAL NOZZLE + DIFFUSER



CONSEQUENCES:

- Less entropy production decelerating with multiple OSWs

→ P_0 can be further lowered.

- Required pressure ratio P_e/P_0 can be obtained

1.) Pressurized storage vessel ($P_0 > P_{atm}$)

2.) Vacuum at the outlet ($P_0 = P_{atm}$)

DESIGN CRITERIA FOR A SUPERSONIC WIND TUNNEL

1. Operating Mach number M_0 A_e/A^*

Given the size of the test section A_e the first throat A_1^* or A_t_1 is determined

2. Calculation of the section throat A_t_2 (diffuser)

Consider $m = \rho u A = \rho_1^* u_1^* A_1^* = \rho_2^* u_2^* A_2^*$ assuming sonic conditions in both throats

$$\frac{A_{t_2}}{A_{t_1}} = \frac{\rho_1^* u_1^*}{\rho_2^* u_2^*} \stackrel{AF}{=} \frac{\rho_1^*}{\rho_2^*} \quad AF: \text{adiabatic flow}$$

$$\frac{A_{t_2}}{A_{t_1}} = \frac{\rho_1^* R T_2^*}{\rho_2^* R T_1^*} = \frac{\rho_1^*}{\rho_2^*} = \frac{P_{0,1} \left(\frac{2}{\gamma+1}\right)^{\frac{\gamma}{\gamma-1}}}{P_{0,2} \left(\frac{2}{\gamma+1}\right)^{\frac{\gamma}{\gamma-1}}}$$

$$\boxed{\frac{A_{t_2}}{A_{t_1}} = \frac{P_{0,1}}{P_{0,2}}}$$

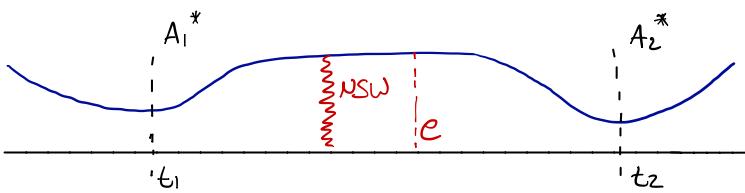
The second throat must always be larger than the first one.

In a preliminary design phase one may assume $\frac{P_{0,2}}{P_{0,1}}$ from a NSW at M_0

$$Iff \quad \frac{A_{t_2}}{A_{t_1}} < \frac{P_{0,1}}{P_{0,2}} \rightarrow \text{tunnel choking.}$$

EXAMPLE determine the SW position for a nozzle operating with P_{e1}, P_e, P_{e2}

Consider that the nozzle exit is followed by another duct with throat A_{t_2} with sonic conditions.



$$\rho_1^* a_1^* A_1^* = \rho_2^* a_2^* A_2^*$$

$$P_0 = P_0 R T_0$$

$$\left(\frac{\rho^*}{\rho_0} P_0 \sqrt{YR} \sqrt{\frac{T^*}{T_0}} \sqrt{A^*} \right)_1 = \left(\frac{\rho^*}{\rho_0} P_0 \sqrt{YR} \sqrt{\frac{T^*}{T_0}} \sqrt{A^*} \right)_2$$

$$\left(\frac{\rho^*}{\rho_0} \right)_1 = \left(\frac{\rho^*}{\rho_0} \right)_2$$

$$\left(\frac{T^*}{T_0} \right)_1 = \left(\frac{T^*}{T_0} \right)_2$$

$$\frac{A_2^*}{A_1^*} = \frac{P_{0,1}}{P_{0,2}} \sqrt{\frac{T_{0,2}}{T_{0,1}}} \xrightarrow{AF} \frac{A_2^*}{A_1^*} = \frac{P_{0,1}}{P_{0,2}}$$

$$M_e^2 \stackrel{AF}{=} \frac{1}{\gamma - 1} \left[\left(1 + 2(\gamma - 1) \left(\frac{2}{\gamma + 1} \right)^{\frac{\gamma+1}{\gamma-1}} \left(\frac{A^*}{A_e} \cdot \frac{P_0}{P_e} \right)^2 \right)^{1/2} - 1 \right]$$

valid for isentropic and adiabatic flow

ADIABATIC NOZZLE FLOW

Even in presence of SWS we can obtain a relation returning the.

- Mach number M_e
- Useful in range $P_{es} < P_e < P_{eg}$

CHAPTER 11 SUBSONIC COMPRESSIBLE FLOW OVER AIRFOILS

VELOCITY POTENTIAL EQUATION

Inviscid, compressible, subsonic flow around an object.

- Irrotational flow
- define a velocity potential ϕ

$$\vec{V} = \vec{\nabla} \phi \quad \text{or} \quad u = \frac{\partial \phi}{\partial x}, \quad v = \frac{\partial \phi}{\partial y}$$

Continuity equation:

$$\frac{\partial}{\partial x} (\rho u) + \frac{\partial}{\partial y} (\rho v) = 0 \quad \rho \left(\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} \right) + \frac{\partial \phi}{\partial x} \frac{\partial \rho}{\partial x} + \frac{\partial \phi}{\partial y} \frac{\partial \rho}{\partial y} = 0$$

Eliminate ρ with momentum equation.

$$d\rho = -\rho V dV \rightarrow d\rho = -\frac{\rho}{2} d(v^2) = -\frac{\rho}{2} d(u^2 + v^2) = -\frac{\rho}{2} d \left[\left(\frac{\partial \phi}{\partial x} \right)^2 + \left(\frac{\partial \phi}{\partial y} \right)^2 \right]$$

$$\left. \frac{\partial p}{\partial p} \right|_s = a^2 \rightarrow dp = a^2 dp$$

$$\frac{\partial p}{\partial x} = -\frac{p}{2a^2} \frac{\partial}{\partial x} []$$

$$dp = -\frac{p}{2a^2} d \left[\left(\frac{\partial \phi}{\partial x} \right)^2 + \left(\frac{\partial \phi}{\partial y} \right)^2 \right] \rightarrow \frac{\partial p}{\partial y} = -\frac{p}{2a^2} \frac{\partial}{\partial y} []$$

$$\frac{\partial p}{\partial x} = -\frac{p}{a^2} \left(\frac{\partial \phi}{\partial x} \frac{\partial \phi}{\partial x^2} + \frac{\partial \phi}{\partial y} \frac{\partial^2 \phi}{\partial x \partial y} \right)$$

SUBSTITUTING IN PREVIOUS RESULT

$$\left[1 - \frac{1}{a^2} \left(\frac{\partial \phi}{\partial x} \right)^2 \right] \frac{\partial^2 \phi}{\partial x^2} + \left[1 - \frac{1}{a^2} \left(\frac{\partial \phi}{\partial y} \right)^2 \right] \frac{\partial^2 \phi}{\partial y^2} - \frac{2}{a^2} \left(\frac{\partial \phi}{\partial x} \right) \left(\frac{\partial \phi}{\partial y} \right) \frac{\partial^2 \phi}{\partial x \partial y} = 0$$

USING the energy equation we can eliminate the speed of sound.

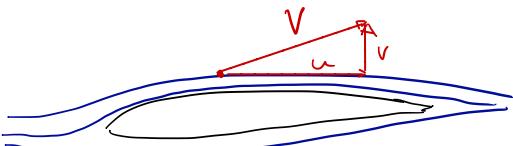
$$a^2 = a_0^2 - \frac{\gamma-1}{2} V^2 = a_0^2 - \frac{\gamma-1}{2} (u^2 + v^2) = a_0^2 - \frac{\gamma-1}{2} \left[\left(\frac{\partial \phi}{\partial x} \right)^2 + \left(\frac{\partial \phi}{\partial y} \right)^2 \right]$$

REMARKS

- Final result: a single PDE in terms of the unknown ϕ
- It can be solved for 2D shapes once given the B.C. at body surface and a
- Once ϕ is known \rightarrow obtain u, v derivatives
 calculate $a = a_0 g(\phi)$
 calculate $M = V/a$
- Mostly solved numerically.
- Valid for any Mach Number.

LINEARIZED VELOCITY POTENTIAL

Consider a 2D body in uniform flow.



$$\left. \begin{array}{l} u = V_\infty + \hat{u} \\ v = \hat{v} \end{array} \right\} \quad \phi = V_\infty x + \phi \quad \begin{array}{l} \frac{\partial \phi}{\partial x} = \hat{u} \\ \frac{\partial \phi}{\partial y} = \hat{v} \end{array}$$

SUBS ON V.P. EQUATION

Therefore

$$\frac{\partial \phi}{\partial x} = V_\infty + \frac{\partial \phi}{\partial x} \quad \frac{\partial \phi}{\partial y} = \frac{\partial \hat{\phi}}{\partial y} \quad \left\{ \left[a^2 - \left(V_\infty + \frac{\partial \phi}{\partial x} \right)^2 \right] \frac{\partial^2 \phi}{\partial x^2} + \left[a^2 - \left(\frac{\partial \phi}{\partial y} \right)^2 \right] \frac{\partial^2 \phi}{\partial y^2} - 2 \left(V_\infty + \frac{\partial \phi}{\partial x} \right) \left(\frac{\partial \phi}{\partial y} \right) \frac{\partial^2 \phi}{\partial x \partial y} = 0 \right.$$

PERTURBATION VELOCITY POTENTIAL EQUATION

$$\left[\alpha^2 - (V_\infty + \hat{u})^2 \right] \frac{\partial \hat{u}}{\partial x} + \left[\alpha^2 - (\hat{v})^2 \right] \frac{\partial \hat{v}}{\partial y} - 2(V_\infty + \hat{u})(\hat{v}) \frac{\partial \hat{u}}{\partial y} = 0$$

$$\frac{\alpha^2}{\gamma-1} + \frac{V_\infty^2}{2} = \frac{\alpha^2}{\gamma-1} + \frac{(V_\infty + \hat{u})^2 + \hat{v}^2}{2}$$

ENERGY EQUATION

$$(1 - M_\infty^2) \frac{\partial \hat{u}}{\partial x} + \frac{\partial \hat{v}}{\partial y} = M_\infty^2 \left[(\gamma+1) \frac{\hat{u}}{V_\infty} + \frac{\gamma+1}{2} \cdot \frac{\hat{u}^2}{V_\infty^2} + \frac{\gamma-1}{2} \cdot \frac{\hat{v}^2}{V_\infty^2} \right] \frac{\partial \hat{u}}{\partial x} +$$

$$+ M_\infty^2 \left[(\gamma+1) \frac{\hat{u}}{V_\infty} + \frac{\gamma+1}{2} \cdot \frac{\hat{v}^2}{V_\infty^2} + \frac{\gamma-1}{2} \cdot \frac{\hat{u}^2}{V_\infty^2} \right] \frac{\partial \hat{v}}{\partial x} + M_\infty^2 \left[\frac{\hat{v}}{V_\infty} \left(1 + \frac{\hat{u}}{V_\infty} \right) \left(\frac{\partial \hat{u}}{\partial x} + \frac{\partial \hat{v}}{\partial y} \right) \right]$$

SIMPLIFYING ASSUMPTIONS

Slender body, t and camber small

Small angle of attack

CONSEQUENCES

$$\left. \begin{array}{l} \frac{\hat{u}}{V_\infty} \ll 1 ; \frac{\hat{v}}{V_\infty} \ll 1 \\ \frac{\hat{u}^2}{V_\infty^2} \ll \frac{\hat{u}}{V_\infty} \end{array} \right\}$$

COMPARING FOR DIFFERENT TERMS

a) For $0 \leq M_\infty < 0.8$ and $M_\infty \geq 1.2$

$$M_\infty^2 \left[(\gamma+1) \frac{\hat{u}}{V_\infty} + \dots \right] \frac{\partial \hat{u}}{\partial x} \ll (1 - M_\infty^2) \frac{\partial \hat{u}}{\partial x}$$

b) For $M_\infty < 5$

$$M_\infty^2 \left[(\gamma-1) \frac{\hat{u}}{V_\infty} + \dots \right] \frac{\partial \hat{v}}{\partial y} \ll \frac{\partial \hat{v}}{\partial y} \quad \text{and also}$$

$$M_\infty^2 \left[\frac{\hat{v}}{V_\infty} \left(1 + \frac{\hat{u}}{V_\infty} \left(\frac{\partial \hat{u}}{\partial x} + \frac{\partial \hat{v}}{\partial y} \right) \right) \right] \text{ is negligible.}$$

VELOCITY PERTURBATION EQUATION

$$(1 - M_\infty^2) \frac{\partial \hat{u}}{\partial x} + \frac{\partial \hat{v}}{\partial y} = 0$$

LINEARIZED EXPRESSION FOR PRESSURE COEFFICIENT

$$C_p = - \frac{2 \hat{u}}{V}$$

VELOCITY POTENTIAL

$$(1 - M_\infty^2) \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = 0$$

The boundary conditions on the body surface and at infinity:

$\phi = \text{constant}$ at infinity because $\hat{u} = \hat{v} = 0$

On the body the flow is tangent to the wall with slope Θ

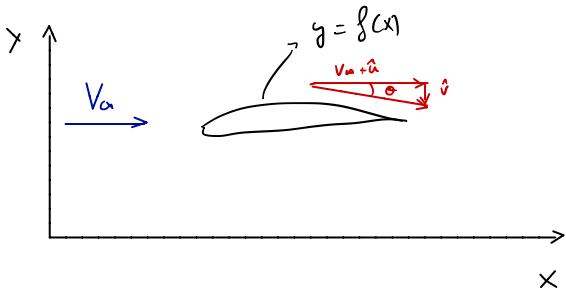
$$\tan \Theta = \frac{v}{u} = \frac{\hat{v}}{\hat{u}} \approx \frac{\hat{v}}{V_\infty} = \frac{1}{V_\infty} \frac{\partial \hat{\phi}}{\partial y}$$

$$\boxed{\frac{\partial \hat{\phi}}{\partial y} = V_\infty \tan \Theta}$$

PRANDTL - GLAUERT COMPRESSIBILITY CORRECTION

Limited to thin airfoils at low α

Purely subsonic $M \leq 0.7$



Flow approximated by

$$(1 - M_\infty^2) \frac{\partial^2 \hat{\phi}}{\partial x^2} + \frac{\partial^2 \hat{\phi}}{\partial y^2} = 0$$

$$\text{Define } \beta = \sqrt{1 - M_\infty^2} \rightarrow \beta^2 \frac{\partial^2 \hat{\phi}}{\partial x^2} + \frac{\partial^2 \hat{\phi}}{\partial y^2} = 0$$

Apply coordinate transform:

$$\left. \begin{array}{l} \xi = x \\ \eta = \beta y \end{array} \right\} \bar{\phi}(\xi, \eta) = \beta \hat{\phi}(x, y)$$

$$\frac{\partial \hat{\phi}}{\partial x} = \frac{\partial \hat{\phi}}{\partial \xi} \frac{\partial \xi}{\partial x} + \frac{\partial \hat{\phi}}{\partial \eta} \frac{\partial \eta}{\partial x} = \frac{\partial \hat{\phi}}{\partial \xi}$$

$$\frac{\partial \hat{\phi}}{\partial y} = \frac{\partial \hat{\phi}}{\partial \xi} \frac{\partial \xi}{\partial y} + \frac{\partial \hat{\phi}}{\partial \eta} \frac{\partial \eta}{\partial y} = \frac{\partial \hat{\phi}}{\partial \eta}$$

Recall that $\bar{\phi} = \beta \hat{\phi}$

$$\frac{\partial \hat{\phi}}{\partial x} = \frac{1}{\beta} \frac{\partial \bar{\phi}}{\partial \xi} \rightarrow \frac{\partial^2 \bar{\phi}}{\partial x^2} = \frac{1}{\beta} \frac{\partial^2 \bar{\phi}}{\partial \xi^2}$$

$$\frac{\partial \hat{\phi}}{\partial y} = \frac{\partial \bar{\phi}}{\partial \eta} \rightarrow \frac{\partial^2 \bar{\phi}}{\partial y^2} = \beta \frac{\partial^2 \bar{\phi}}{\partial \eta^2}$$

SUBSTITUTING IN STARTING EQUATION

$$\beta^2 \frac{1}{\beta} \frac{\partial^2 \bar{\phi}}{\partial \xi^2} + \beta \frac{\partial^2 \bar{\phi}}{\partial \eta^2} = 0$$

$$\boxed{\frac{\partial^2 \bar{\phi}}{\partial \xi^2} + \frac{\partial^2 \bar{\phi}}{\partial \eta^2} = 0}$$

DARLACE EQUATION

CONSEQUENCE:

We can obtain a linearized C_p from subsonic flow theory

$$C_p = -\frac{2 \hat{u}}{V_\infty} = -\frac{2}{V_\infty} \frac{\partial \hat{\phi}}{\partial x} = -\frac{2}{V_\infty} \cdot \frac{1}{\beta} \cdot \frac{\partial \bar{\phi}}{\partial x} = -\frac{2}{V_\infty} \cdot \frac{1}{\beta} \cdot \frac{\partial \bar{\phi}}{\partial \xi}$$

$$\text{INTRODUCED } \bar{u} = \frac{\partial \bar{\phi}}{\partial \xi}$$

$$C_p = \frac{1}{\beta} \left(-\frac{2\bar{u}}{V_\infty} \right) \quad C_{p,0} = -\frac{2\bar{u}}{V_\infty} \quad C_p = \frac{C_{p,0}}{\beta}$$

$$C_p = \frac{C_{p,0}}{\sqrt{1 - M_\infty^2}}$$

Prandtl-Glauert rule

Same works for C_l, C_m, C_d

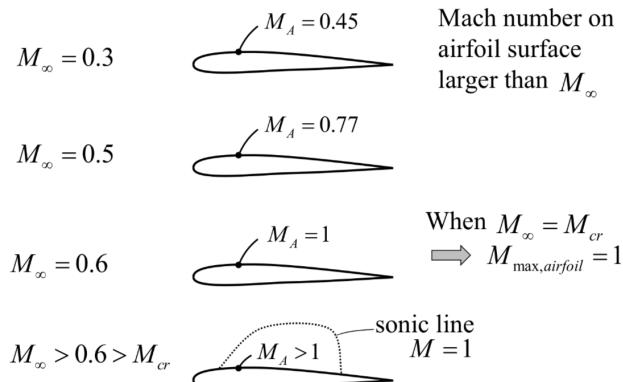
PROBLEM: If M_∞ is high enough ($M_\infty > M_{cr}$) local supersonic flow introduces wave drag and D'Alembert paradox will not be valid.

$$C_p = \frac{C_{p,0}}{\sqrt{1 - M_\infty^2} + \left[n_\infty^2 / \left(1 + \sqrt{1 - M_\infty^2} \right) \right] C_{p,0}/2}$$

CRITICAL MACH NUMBER

If $(M_\infty^2 - 1) \ll 1$ linearized theory does not apply.

If $M_\infty > M_{cr}$ local supersonic flow large increase in drag coefficient.



If $M_\infty = M_{cr} \rightarrow M_A = 1$

$C_{p,cr}$ attained at minimum pressure

$$C_{p,4} = \frac{2}{\gamma M_{cr}^2} \left\{ \left[\frac{1 + \frac{\gamma-1}{2} M_{cr}^2}{\frac{\gamma+1}{2}} \right]^{-1} \right\}^{\frac{\gamma}{\gamma-1}}$$

DETERMINATION OF CRITICAL PRESSURE COEFFICIENT.

Isentropic flow → minimum value static pressure on airfoil.

$$\frac{P_A}{P_\infty} = \frac{P_A}{P_\infty} \cdot \frac{P_0}{P_\infty} = \left[\frac{1 + \frac{\gamma-1}{2} M_\infty^2}{1 + \frac{\gamma-1}{2} M_A^2} \right]^{\frac{\gamma}{\gamma-1}}$$

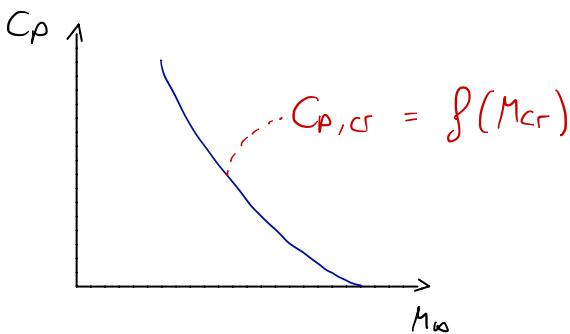
free stream static pressure

$$C_{p,A} = \frac{2}{\gamma M_\infty^2} \left(\frac{P_A}{P_\infty} - 1 \right) = \frac{2}{\gamma M_\infty^2} \left\{ \left[\frac{1 + \frac{\gamma-1}{2} M_\infty^2}{1 + \frac{\gamma-1}{2} M_A^2} \right]^{-1} \right\}^{\frac{\gamma}{\gamma-1}}$$

$$M_A = 1$$

$$C_{p,A} = \frac{2}{\gamma M_\infty^2} \left(\frac{P_A}{P_\infty} - 1 \right) = \frac{2}{\gamma M_\infty^2} \left\{ \left[\frac{1 + \frac{\gamma-1}{2} M_\infty^2}{\frac{\gamma+1}{2}} \right]^{-1} \right\}^{\frac{\gamma}{\gamma-1}}$$

$C_{p,cr}$ and M_{cr} are related graphically like

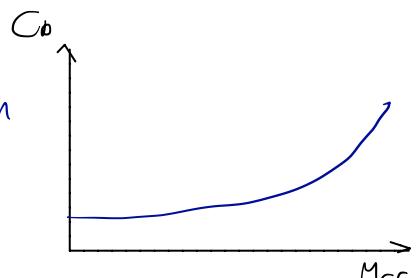


This result with the compressibility correction allows to estimate M_{cr} for a given airfoil.

PROCEDURE

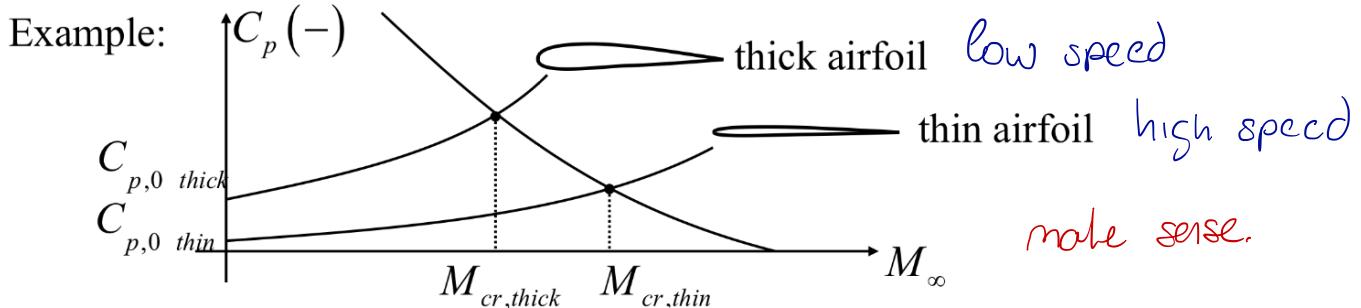
1.) By experiment or theory obtain the value of minimum in the incompressible regime.

2.) Using a compressibility correction plot the function



3.) Determine intersection point where sonic conditions are achieved.

The result depends on the chosen airfoil



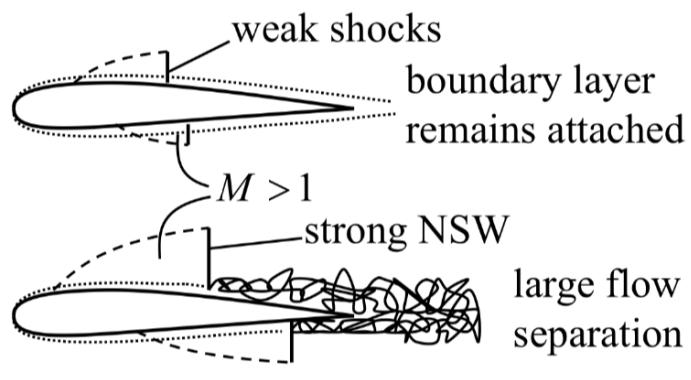
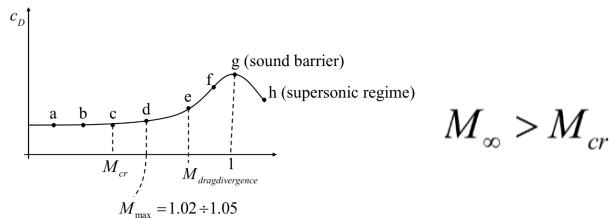
DRAE DIVERGENCE BARRIER

At $M_\infty \geq M_{cr}$ supersonic flow is terminated by shock waves.

- separation
- drag.

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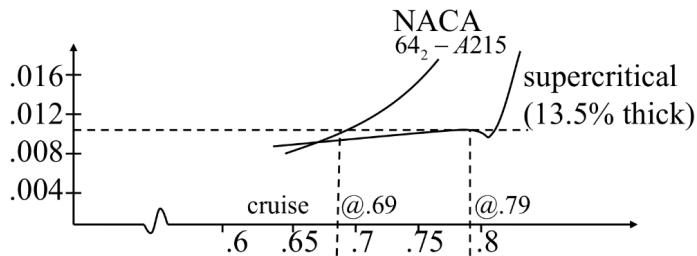
$M_\infty ; M_{cr}$



SUPERCRITICAL AIRFOIL

Designed to obtain low drag increase in proximity of drag divergence.

- Higher cruise Mach number with moderate increase in fuel consumption



Achieved by a flat top.



CHAPTER 12 LINEARIZED SUPERSONIC FLOW

Starting from the linearized perturbation velocity potential.

$$(1 - M_\infty^2) \frac{\partial^2 \hat{\phi}}{\partial x^2} + \frac{\partial^2 \hat{\phi}}{\partial y^2} = 0$$

Which holds for both subsonic and supersonic flow regimes.

• Supersonic $1 - M_\infty^2 < 0$ hyperbolic PDE

• Subsonic $1 - M_\infty^2 > 0$ elliptic PDE

For $M_\infty > 1$ → define $\lambda = \sqrt{M_\infty^2 - 1}$

Solution to this equation given by

$$\hat{\phi} = f(x - \lambda y)$$

Substitution:

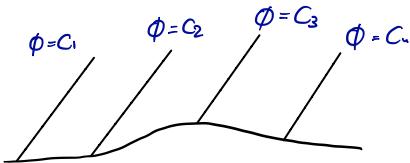
$$\frac{\partial \hat{\phi}}{\partial x} = f'(x - \lambda y) \frac{\partial}{\partial x}(x - \lambda y) = f' \rightarrow \frac{\partial^2 \hat{\phi}}{\partial x^2} = f'' \quad \text{Similarly: } \frac{\partial^2 \hat{\phi}}{\partial y^2} = \lambda^2 f''$$

$$\lambda^2 \frac{\partial^2 \hat{\phi}}{\partial x^2} - \frac{\partial^2 \hat{\phi}}{\partial y^2} = 0 \rightarrow \lambda^2 f'' - \lambda^2 f'' = 0 \quad \text{Not specific:}$$

The identity tells us that if $x - \lambda y = \text{constant}$

- $\hat{\phi}$ is also constant
- slope is $\frac{\partial y}{\partial x} = \frac{1}{\lambda} = \frac{1}{\sqrt{M_\infty^2 - 1}} = \tan \mu$

Flow properties are constant along lines locally inclined of μ . $\hat{\phi}$ is constant along Mach lines.



Waves of finite strength are not accounted for in linearized theory.

LINARIZED C_p IN SUPERSONIC REGIME:

$$\begin{aligned}\hat{u} &= \frac{\partial \hat{\phi}}{\partial x} = f' \\ \hat{v} - \frac{\partial \hat{\phi}}{\partial y} &= -\lambda f'\end{aligned}\left\{ \begin{aligned}\hat{u} &= -\frac{\hat{v}}{\lambda} \\ \hat{v} &= \frac{\lambda \hat{u}}{1 + \lambda^2}\end{aligned}\right.$$

linearized boundary conditions

$$\hat{v} = V_\infty \tan \theta \approx V_\infty \cdot \theta$$

Small perturbations hypothesis

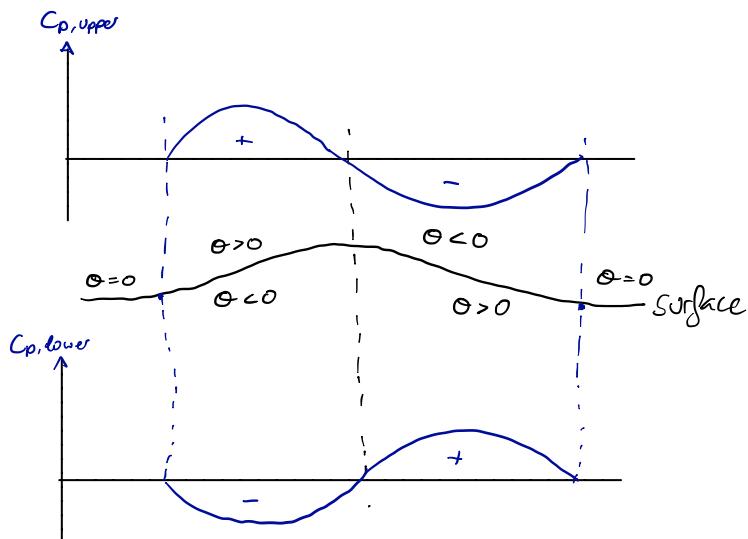
$$\hat{u} = -\frac{V_\infty \theta}{\lambda}$$

C_p is linearly proportional to local surface inclination.

$$C_p = -\frac{2\hat{u}}{V_\infty} = -\frac{2}{V_\infty} \left(-\frac{V_\infty \theta}{\lambda} \right)$$

$$C_p = \frac{2\theta}{\sqrt{M_\infty^2 - 1}}$$

Notice that in the C_p , $\theta > 0$ when measure above the horizontal.



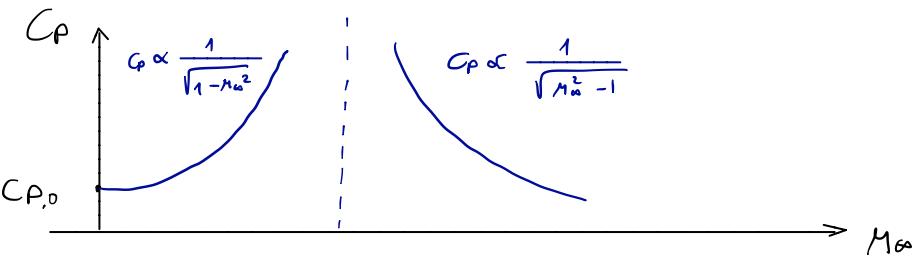
Pressure is higher on the top-front and bottom-rear segments.

- A net force will act on the profile.
- Wave drag characteristic of supersonic flows.
- Even without the presence of shocks, linearized theory predicts wave drag.

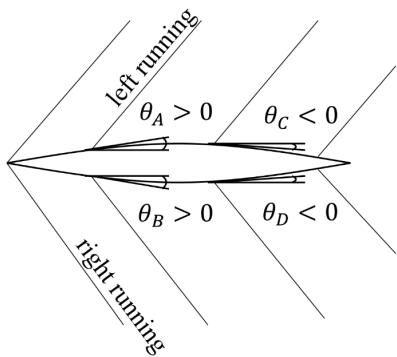
Supersonic Airfoils

Examining $C_p = \frac{2\alpha}{M_\infty^2 - 1}$ C_p decreases if M_∞ increases.

Combining this observation with subsonic compressible part:



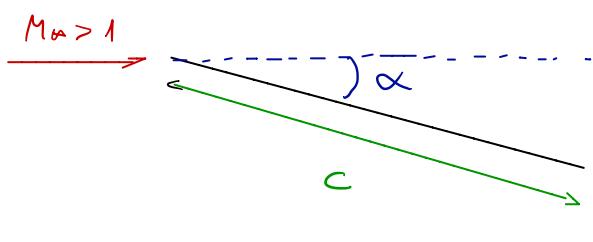
Sign convention for θ is different for left running and right running waves.



$$C_{p,A} = \frac{2\theta_A}{M_\infty^2 - 1} \quad C_{p,C} = \frac{2\theta_C}{M_\infty^2 - 1}$$

$$C_{p,B} = \frac{2\theta_B}{M_\infty^2 - 1} \quad C_{p,D} = \frac{2\theta_D}{M_\infty^2 - 1}$$

FLAT PLATE AT INCIDENCE



$$C_{p,lower} = \frac{2\alpha}{M_\infty^2 - 1}$$

$$C_{p,upper} = \frac{-2\alpha}{M_\infty^2 - 1}$$

$$C_n = \frac{1}{C} \int_0^C (C_{pl} - C_{pu}) dx = \frac{4\alpha}{\sqrt{M_\infty^2 - 1}} \cdot \frac{1}{C} \int_0^C dx = \frac{4\alpha}{\sqrt{M_\infty^2 - 1}}$$

$$C_a = \frac{1}{C} \int_{y=0}^{TE} (C_{pu} - C_{pl}) dy$$

Since the flat plate has zero thickness and camber

- δ_y is identically zero.
 - $C_a = 0$ (pressure only normal to the axis)
- $$Cl = C_n \cos \alpha - C_a \sin \alpha; \quad C_n = C_a \alpha$$
- $$Cd = C_n \sin \alpha - C_a \cos \alpha; \quad C_n \propto -C_a$$

For the flat plate case:

$Cl = C_n$ $Cd = C_n \alpha$		<div style="display: flex; justify-content: space-between;"> <div style="width: 45%;"> <p>Lift coefficient</p> <p>Wave drag coefficient</p> </div> <div style="width: 45%;"> $Cl = \frac{4\alpha}{\sqrt{M_\infty^2 - 1}}$ $Cd = \frac{4\alpha^2}{\sqrt{M_\infty^2 - 1}}$ </div> </div>
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For a thin airfoil of arbitrary shape:

$$Cl = \frac{4\alpha}{\sqrt{M_\infty^2 - 1}} \quad \text{still holds}$$

$$Cd = \frac{4}{\sqrt{M_\infty^2 - 1}} \cdot (\alpha^2 + g_c^2 + g_t^2)$$

g_c is the function of the camber line

g_t is the function of the thickness